



Latest developments of the airGR rainfall-runoff modelling R package: new calibration procedures and other features

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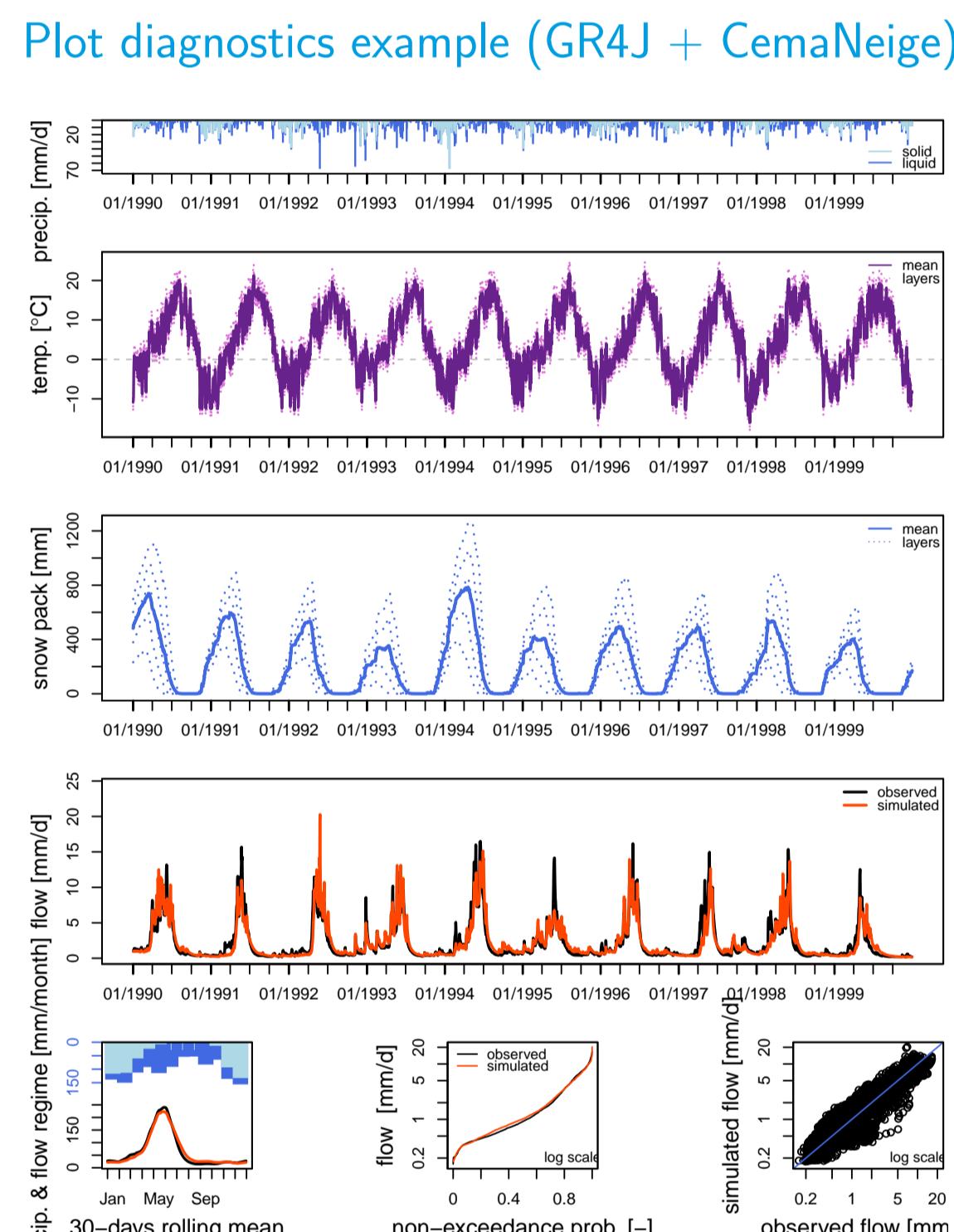
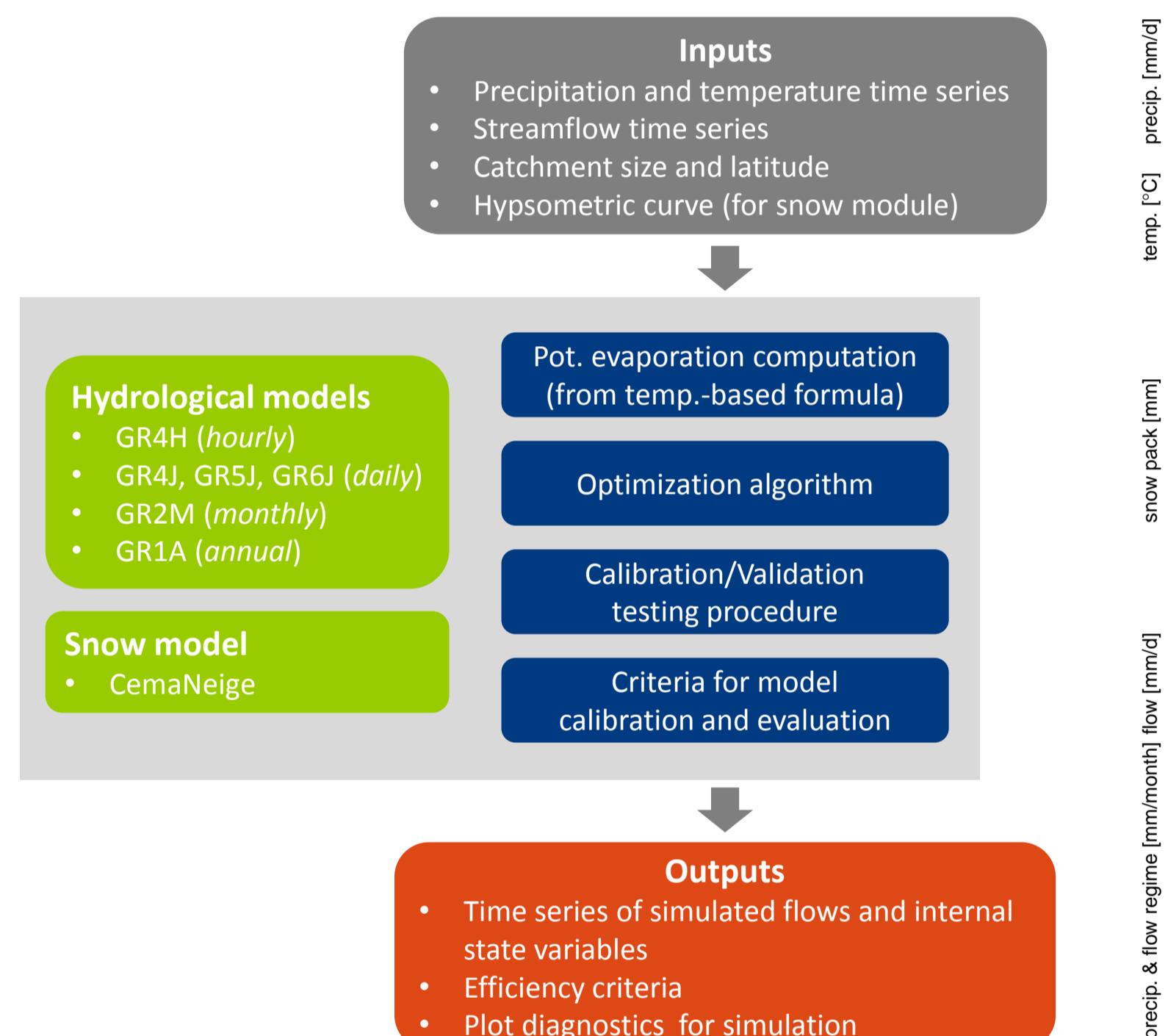
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GR is a family of lumped hydrological models designed for flow simulation at various time steps. The models are freely available in an R package called airGR (Coron et al., 2017a, 2017b). The models can easily be implemented on a set of catchments with limited data requirements.

GR hydrological models

- ▶ Designed with the objective to be as efficient as possible for flow simulation at various time steps (from hourly to interannual)
- ▶ Warranted complexity structures and limited data requirements
- ▶ Can be applied on a wide range of conditions, including snowy catchments (CemaNeige snow routine included)

Main components of the airGR package



News since EGU 2017 – airGR 1.0.9.64 vs airGR 1.0.5.12

- ▶ The Param Sets GR4J dataset was added. It contains generalist parameter sets for the GR4J model
- ▶ If the calibration period is too short (< 6 months) and by consequence non representative of the catchment behaviour, a local calibration algorithm can give poor results and we recommend to use the generalist parameter sets instead
- ▶ Vignettes were added. They explain how to perform parameters estimation with:
 - ▶ Differential Evolution calibration algorithm
 - ▶ Particle Swarm calibration algorithm
 - ▶ MA-LS-Chains calibration algorithm
 - ▶ Bayesian MCMC framework
- ▶ A new airGRteaching package (Delaigue et al., 2018) provides tools to simplify the use of the airGR hydrological package for education, including a 'Shiny' interface

Future developments

- ▶ New version of CemaNeige that allows to use satellite snow cover area for calibration (Riboust et al., accepted)
- ▶ Parameters maps on France for GR4J, GR5J & GR6J models for ungauged basins (Poncelet et al., submitted)

How to use other R packages to perform parameters estimation

- ▶ Definition of the necessary function:
 - ▶ transformation of parameters to real space (available in airGR)
 - ▶ computation of the value of the performance criterion (e.g. RMSE)
- ```

OptimGR4J <- function(Param_Optim) {
 Param_Optim_Vre <- airGR:::TransfoParam_GR4J(ParamIn = Param_Optim,
 Direction = "TR")
 OutputsModel <- airGR:::RunModel_GR4J(InputsModel = InputsModel,
 RunOptions = RunOptions,
 Param = Param_Optim_Vre)
 OutputsCrit <- airGR:::ErrorCrit_RMSE(InputsCrit = InputsCrit,
 OutputsModel = OutputsModel)
 return(OutputsCrit$CritValue)
}

```
- ▶ Definition of the lower and upper bounds of the four GR4J parameters in the transformed parameter space
- ```

lowerGR4J <- rep(-9.99, times = 4)
upperGR4J <- rep(+9.99, times = 4)

```
- ▶ Local optimisation
 - ▶ Single-start (here) or multi-start approach to test the consistency of the local optimisation
- ```

startGR4J <- c(4.1, 3.9, -0.9, -8.7)
optPORT <- stats::nlminb(start = startGR4J, objective = OptimGR4J,
 lower = lowerGR4J, upper = upperGR4J,
 control = list(trace = 1))

```
- ▶ Global optimisation
    - ▶ Most often used when facing a complex response surface, with multiple local minima
    - ▶ Differential Evolution
- ```

optDE <- DEoptim::DEoptim(fn = OptimGR4J,
                           lower = lowerGR4J, upper = upperGR4J,
                           control = DEoptim::DEoptim.control(NP = 40, trace = 10))

```
- ▶ Particle Swarm
- ```

optPSO <- hydroPSO::hydroPSO(fn = OptimGR4J,
 lower = lowerGR4J, upper = upperGR4J,
 control = hydroPSO::hydroPSO.control(maxEval = 2000))

```
- ▶ MA-LS-Chains
- ```

optMAL <- Rmalschains::malschains(fn = OptimGR4J, maxEvals = 2000,
                                    lower = lowerGR4J, upper = upperGR4J)

```

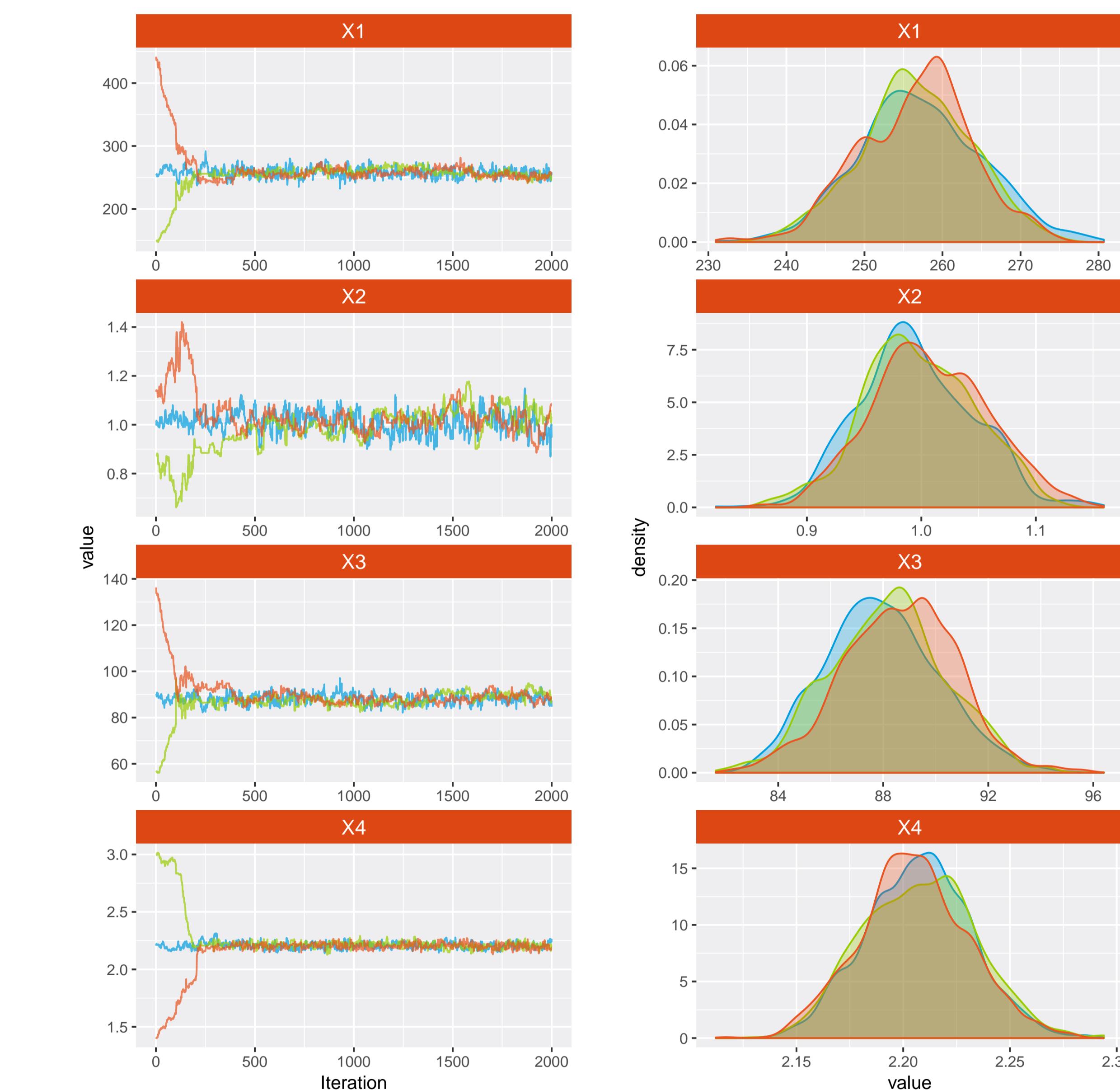
Results

Algo	X1	X2	X3	X4	RMSE	CPU
airGR	257.238	1.012	88.235	2.208	0.7852	00.53 s
PORT	256.808	1.004	88.167	2.205	0.7852	01.79 s
DE	256.808	1.004	88.167	2.205	0.7852	75.10 s
PSO	256.836	1.006	88.207	2.204	0.7852	29.55 s
MA-LS	256.808	1.004	88.167	2.205	0.7852	18.42 s

Download the airGR package

The airGR package is available on the Comprehensive Archive Network:
<https://CRAN.R-project.org/package=airGR/>

Evolution of 3 Markov chains & posterior density for each parameter



References

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