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Variational Data Assimilation with Turbulence Modelling

Pranav Chandramouli¹, Etienne Memin¹, Dominique Heitz²



Motivation

To assimilate observations and optimise the analysis trajectory for turbulent flows using:

- Turbulence modelling^[1, 2]
- Volumetric observations^[3]
- Accurate background condition^[3]
- Background covariance estimation
- Optimised model coefficient

Mathematical Formulation^[4]

Cost

$$J(\delta x_0, \delta u) = \frac{1}{2} \|\delta x_0\|_{B^{-1}}^2 + \frac{1}{2} \int_{t_0}^{t_f} \|\delta u_t\|_{B_c^{-1}}^2 dt + \frac{1}{2} \int_{t_0}^{t_f} \|\mathbb{H}(x_t) - y(t)\|_{R^{-1}}^2 dt$$

Gradient

$$\frac{\partial J}{\partial(\delta x_0)} = -\lambda(t_0) + B^{-1} \delta x_0 \quad \frac{\partial J}{\partial(\delta u)} = -\lambda(t_0) + B_c^{-1} \delta u + (\partial_u \mathbb{M})^* \lambda$$

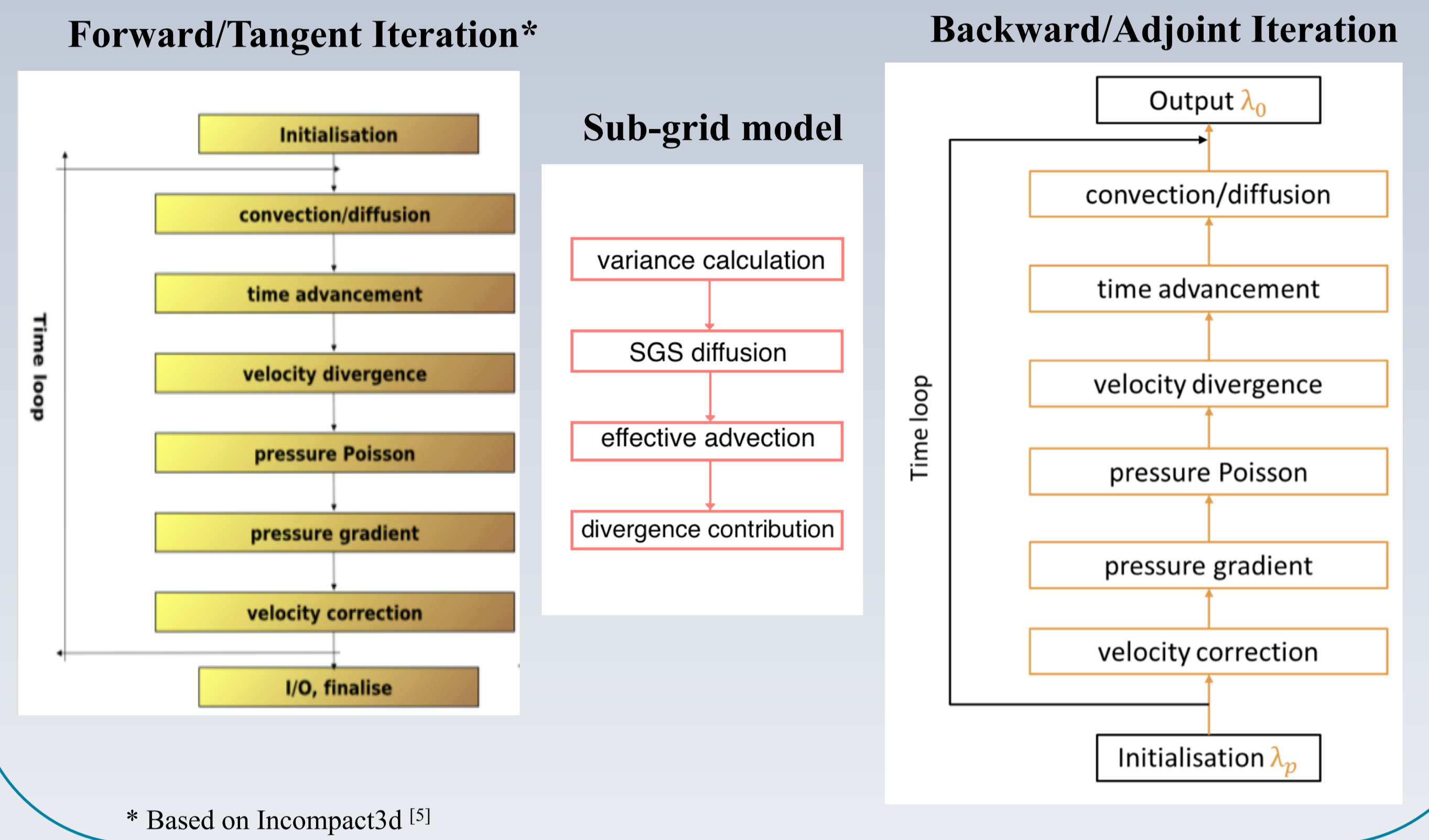
Background Error (under B^{-1}), *Control Error* (under B_c^{-1}), *Observation Error* (under R^{-1})

Glossary:

x_0 – Initial state (x) of the system
 u – Control parameters
 B – background covariance matrix
 R – observation covariance matrix
 λ – adjoint variable

\mathbb{H} – observation operator
 y – set of observations
 \mathbb{M} – dynamical evolution model
 $(\partial_u \mathbb{M})^*$ – adjoint of the control dynamical model

Numerical Formulation

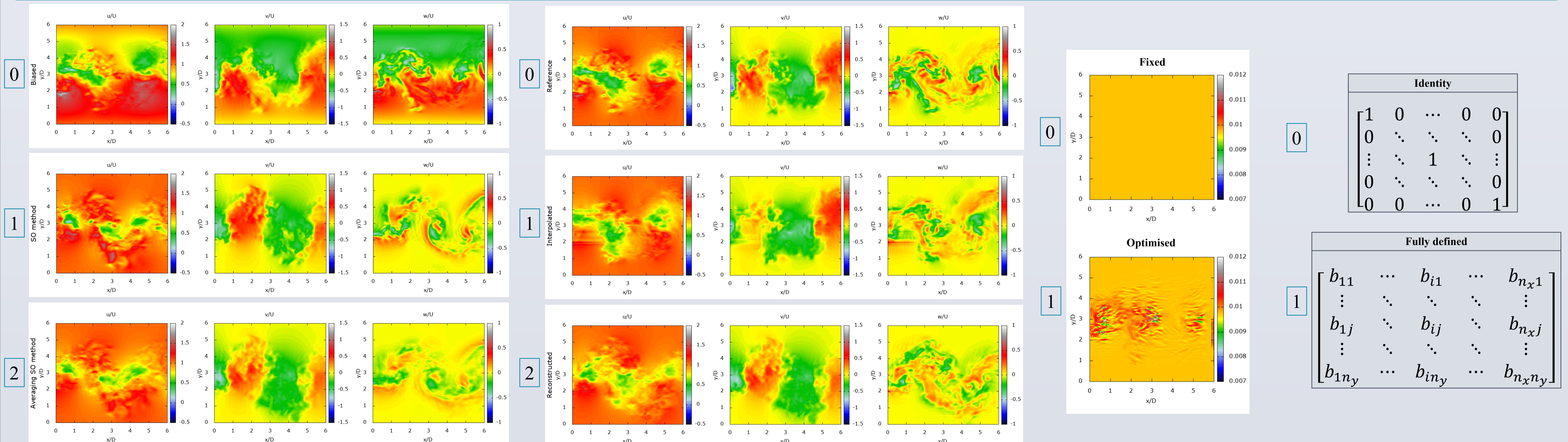


Background @ t_0 - (1)234

Observations @ t_0 - 1(2)34

Coefficient - 12(3)4

Background Covariance - 123(4)



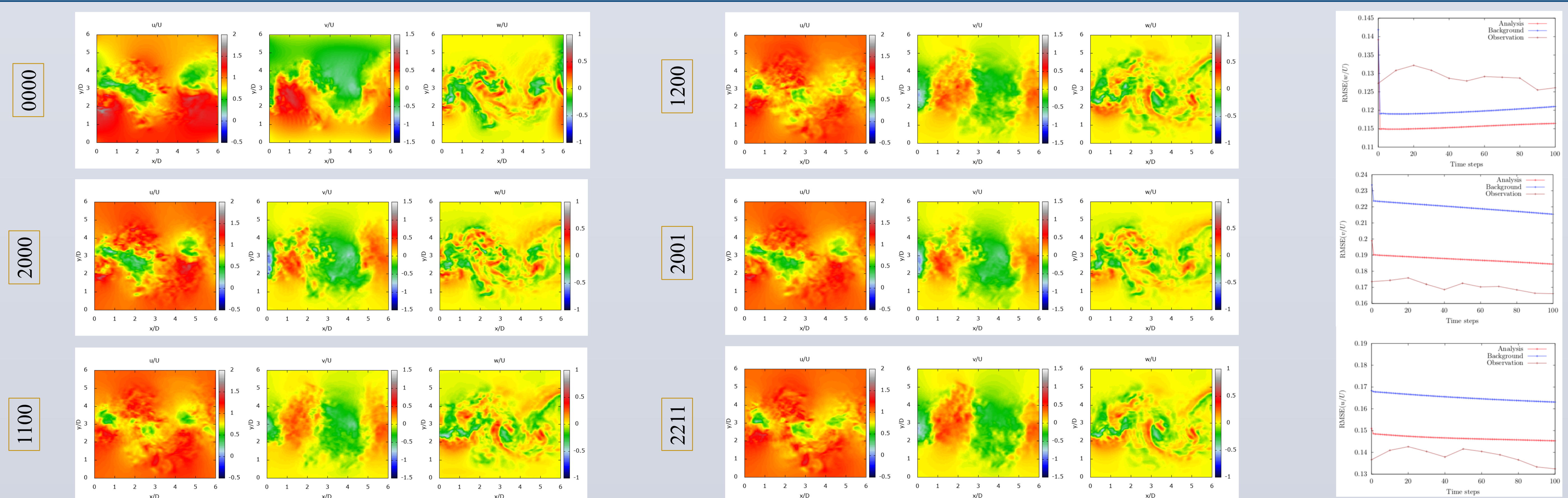
Case

Analysis @ t_0

Case

Analysis @ t_0

RMSE - 2211



Conclusion

- ✓ Turbulence modelling facilitates assimilation of turbulent flows
- ✓ Well-estimated background significantly improves analysis
- ✓ Physically relevant coefficient estimation is feasible via data assimilation
- ✓ Fully-defined background covariance matrix reduces computational time significantly at minor loss of accuracy
- ✓ Reconstructed volumetric observations are sufficient to perform assimilation and achieve meaningful results

Reference

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