Time scales in a coagulation-fragmentation model, Nucleation Time in Stochastic Becker-Döring Model

Romain Yvinec

Time scales in a coagulation-fragmentation model
Nucleation Time in Stochastic Becker-Döring Model

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Amyloid diseases and nucleation

Becker-Döring model

Coarse-graining : to include nucleation in continuous model

Stochastic Becker Döring model

Variability in nucleation time
  Re-scaling reaction rates with M
  Re-scaling nucleus size with M
  Back to classical nucleation theory

Outline

Protein accumulation in amyloid by nucleation-dependent polymerization

Misfolding

Prusiner model for prion

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The early aggregation formation requires a series of association steps that are thermodynamically unfavorable (with an dissociation constant $K_d \gg 1$).
These aggregation steps are unfavorable up to a given size (that is not currently known), which is referred to the nucleus size.

Protein accumulation in amyloid by nucleation-dependent polymerization
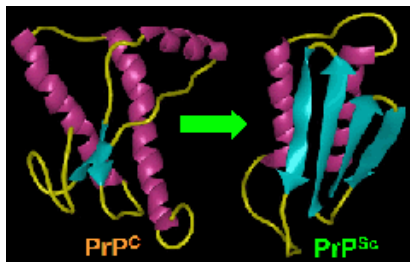
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Prusiner model for prion

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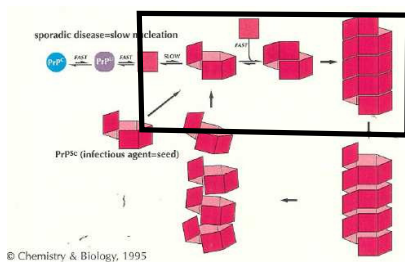
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These aggregation steps are unfavorable up to a given size (that is not currently known), which is referred to the nucleus size.

Key questions

We want to study nucleation mechanism for *in-vitro* spontaneous
polymerization experiments of *rPrP* (kinetics monitored by
fluorescence intensity)

- ▸ How to include nucleation in (macroscopic) model of protein
  polymerization ?
- ▸ How to explain large variability in nucleation lag time, despite
  the large number of proteins ?

Outline

Becker-Döring model

Reversible one-step
coagulation-fragmentation

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}, \quad i = 2,, 3, \cdots$$

- First used in the work *Kinetic treatment of nucleation in supersaturated vapors* by physicists Becker and Döring (1935).
- Traditionally used as an infinite set of Ordinary Differential Equations. More recently used as a finite state-space Markov Chain.

Becker-Döring model

Reversible one-step
coagulation-fragmentation

*Ball, Carr, Penrose, Comm. Math. Phys
104(4), 1986*

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$
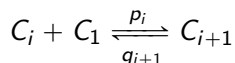
- Purely kinetic model (law of mass-action) : no space, no
  polymer structure (but size-dependent kinetic rates).

Becker-Döring model

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*Ball, Carr, Penrose, Comm. Math. Phys
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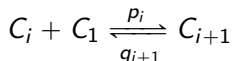
- Purely kinetic model (law of mass-action) : no space, no polymer structure (but size-dependent kinetic rates).
- Indirect interaction between polymer C_i, $i \geqslant 2$ via the available number of monomers C_1.

$$C_1(t) + \sum_{i \geqslant 2} iC_i(t) = \text{constant}$$

Becker-Döring model

Reversible one-step
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Ball, Carr, Penrose, Comm. Math. Phys
104(4), 1986

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$
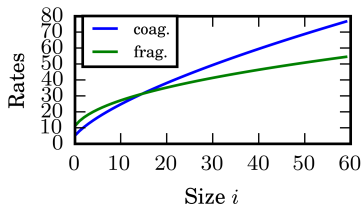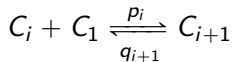
▸ Typical coefficient are derived from physical principles

$$p_i = i^\alpha, \quad q_i = p_i \left(z_s + \frac{q}{i^\gamma} \right).$$

Becker-Döring model

Reversible one-step
coagulation-fragmentation
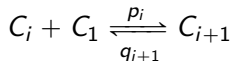
Ball, Carr, Penrose, Comm. Math. Phys 104(4), 1986

Deterministic and Stochastic Becker-Döring equations:
Past and Recent Mathematical Developments

E. Hingant   R. Yvinec

April 24, 2017
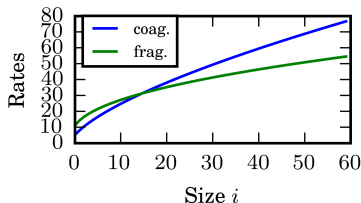
$$C_i + C_1 \xrightleftharpoons[q_{i+1}]{p_i} C_{i+1}$$

- Typical coefficient are derived from physical principles

$$p_i = i^{\alpha}, \quad q_i = p_i \left(z_s + \frac{q}{i^{\gamma}} \right).$$

Becker-Döring model

Reversible one-step coagulation-fragmentation

Set of kinetic reactions :

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}, \quad i \geqslant 1.$$
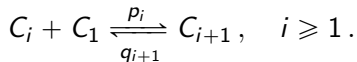
- In spontaneous polymerization experiment,
  - Initial condition given by $c_i(t = 0) = 0 \ \forall i \geqslant 2$.
  - Measured variable : $\sum_{i \geqslant n} iC_i$ (n is an unknown parameter)
- The (observed) nucleation time is given by

$$\inf\{t \geqslant 0 : \sum_{i \geqslant n} iC_i(t) \geqslant \delta m \mid C_i(t = 0) = m\delta_{i=1}\}.$$

Another quantity of interest is the following **First Passage Time**,

$$\inf\{t \geqslant 0 : C_N(t) \geqslant 1 \mid C_i(t = 0) = m\delta_{i=1}\}.$$

Deterministic Becker-Döring model
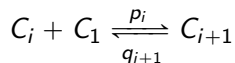
Reversible one-step
coagulation-fragmentation

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$

$$\begin{cases} \dfrac{dc_i}{dt} &= J_{i-1} - J_i \, , \, i \geqslant 2 \, , \\ J_i &= p_i c_1 c_i - q_{i+1} c_{i+1} \, , \, i \geqslant 1 \, , \\ \dfrac{dc_1}{dt} &= -J_1 - \sum_{i=1}^{\infty} J_i \, . \end{cases}$$

▸ Deterministic version : infinite system of ODEs.

Deterministic Becker-Döring model
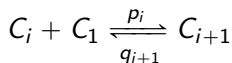
Reversible one-step
coagulation-fragmentation

$$C_i + C_1 \xrightarrow[q_{i+1}]{p_i} C_{i+1}$$

$$\begin{cases} \dfrac{dc_i}{dt} &= J_{i-1} - J_i \,, i \geqslant 2 \,, \\ J_i &= p_i c_1 c_i - q_{i+1} c_{i+1} \,, i \geqslant 1 \,, \\ \dfrac{dc_1}{dt} &= -J_1 - \sum_{i=1}^{\infty} J_i \,. \end{cases}$$

- Deterministic version : infinite system of ODEs.
- Well-posedness theory for sublinear coefficients in

$$\mathcal{X} = \left\{ (c_i)_{i \geqslant 1} \in \mathbb{R}_+^{\mathbb{N}} \, : \, \sum_{i \geqslant 1} i c_i < \infty \right\}$$

Deterministic Becker-Döring model

Reversible one-step
coagulation-fragmentation

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$

$$\begin{cases} \dfrac{dc_i}{dt} = J_{i-1} - J_i \,, i \geqslant 2 \,, \\ \quad J_i = p_i c_1 c_i - q_{i+1} c_{i+1} \,, i \geqslant 1 \,, \\ \dfrac{dc_1}{dt} = -J_1 - \sum_{i=1}^{\infty} J_i \,. \end{cases}$$

- Deterministic version : infinite system of ODEs.
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$$\mathcal{X} = \left\{ (c_i)_{i \geqslant 1} \in \mathbb{R}_+^{\mathbb{N}} : \sum_{i \geqslant 1} i c_i < \infty \right\}$$

- Preserves mass for all times

$$\sum_{i=1}^{\infty} i c_i(t) = \sum_{i=1}^{\infty} i c_i(0) =: m \,.$$

Equilibrium of the BD model

Ball, Carr, Penrose, Comm. Math. Phys 104(4), 1986

$$\begin{cases} \dfrac{dc_i}{dt} &= J_{i-1} - J_i\,, i \geqslant 2\,, \\ J_i &= p_i c_1 c_i - q_{i+1} c_{i+1}\,, i \geqslant 1\,, \\ \dfrac{dc_1}{dt} &= -J_1 - \sum_{i=1}^{\infty} J_i\,. \end{cases}$$

Equilibrium is given by $J_i \equiv J = 0$, which implies

$$c_i = Q_i z^i\,, \quad Q_i = \frac{p_1 p_2 \cdots p_{i-1}}{q_2 q_3 \cdots q_i}$$

z is given by the mass at equilibrium,

$$m(z) := \sum_{i \geqslant 1} i Q_i z^i$$

Is there a solution of

$$m(z) =^? m(= \sum_{i \geqslant 1} i c_i(t))$$

Equilibrium of the BD model

Ball, Carr, Penrose, Comm.
Math. Phys 104(4), 1986

$$\begin{cases} \dfrac{dc_i}{dt} &= J_{i-1} - J_i \,, i \geqslant 2 \,, \\ J_i &= p_i c_1 c_i - q_{i+1} c_{i+1} \,, i \geqslant 1 \,, \\ \dfrac{dc_1}{dt} &= -J_1 - \sum_{i=1}^{\infty} J_i \,. \end{cases}$$

If the serie $m(z) = \sum_{i \geqslant 1} iQ_i z^i$ has a finite radius of convergence z_s and if

$$\sup\{m(z) \,, z < z_s\} =: m_s < \infty \,,$$

then there is a critical mass such that there is **no equilibrium** with mass $m > m_s$.

Deterministic BD model and Classical Nucleation Theory

$$
\begin{cases}
\dfrac{dc_i}{dt} = J_{i-1} - J_i \,, \, i \geqslant 2 \,, \\
\quad J_i = p_i c_1 c_i - q_{i+1} c_{i+1} \,, \, i \geqslant 1 \,, \\
\dfrac{dc_1}{dt} = -J_1 - \sum_{i=1}^{\infty} J_i \,.
\end{cases}
$$

Ball, Carr, Penrose, Comm. Math. Phys 104(4), 1986
Slemrod, Nonlinearity 2(3), 1989
Cañizo, Lods, J. Diff. Eqs. 255(5), 2013

If $m \leqslant m_s$, then (with strong convergence)

$$
\lim_{t \to \infty} c_i(t) = Q_i z^i \,, \quad m(z) = m
$$

If $m > m_s$, then (with weak convergence)

$$
\lim_{t \to \infty} c_i(t) = Q_i z_s^i \,, \quad m - m_s = \text{"loss of mass to } \infty\text{"}
$$

Remark

There is a Lyapounov function, given by

$$
H(c) = \sum_{i \geqslant 1} c_i \left(\ln \left(\frac{c_i}{Q_i} \right) - 1 \right) \,.
$$

Deterministic BD model and Classical Nucleation Theory

Penrose, Comm. Math. Phys
124, 1989

$$\begin{cases} \dfrac{dc_i}{dt} &= J_{i-1} - J_i \,, i \geqslant 2 \,, \\ J_i &= p_i c_1 c_i - q_{i+1} c_{i+1} \,, i \geqslant 1 \,, \\ \dfrac{dc_1}{dt} &= -J_1 - \sum_{i=1}^{\infty} J_i \,. \end{cases}$$

There exist "almost steady-states", for which $J_i \equiv J^*(m) \neq 0$. As $m \searrow m_s$, if such steady-states are used as initial condition, then the solution

- (for finite t) $c_i(t) - c_i(0)$ is exponentially small
- $\lim_{t \to \infty} c_i(t) - c_i(0)$ is not exponentially small

Moreover $J^*(m)$ is exponentially small

- **The new phase is being formed extremely slowly, after a long metastable period**.

Deterministic BD model – Some remarks

▸ For constant or linear kinetic rates p_i, q_i, one can reduce the system to 1 or 2 ODEs on

$$c_1, \quad \sum_{i \geqslant 2} c_i, \quad \sum_{i \geqslant 2} i c_i .$$

Deterministic BD model – Some remarks

- For constant or linear kinetic rates p_i, q_i, one can reduce the system to 1 or 2 ODEs on

$$c_1, \quad \sum_{i \geqslant 2} c_i, \quad \sum_{i \geqslant 2} i c_i.$$

- Based on scaling arguments, one can show that for $q_i = 0$ (irreversible nucleation),

$$\inf\{t \geqslant 0 : c_n(t) \geqslant \delta m \mid c_i(t = 0) = m\delta_{i=1}\} \simeq \frac{1}{m}.$$

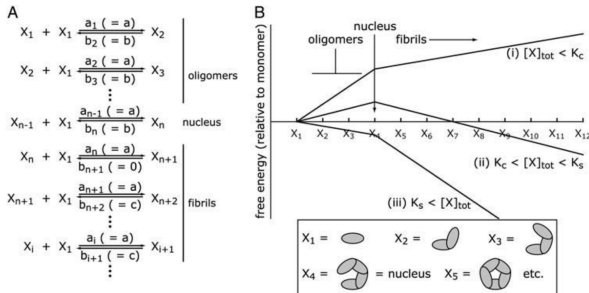while for "$q_i \to \infty$" (pre-equilibrium nucleation),

$$\inf\{t \geqslant 0 : c_n(t) \geqslant \delta m \mid c_i(t = 0) = m\delta_{i=1}\} \simeq \frac{1}{m^n}.$$

Use of BD-like model in protein polymerization models

Irreversible nucleation step, "Heaviside" rates

Powers & Powers, Biophys. J. 91, 2006

For $b \gg c$: pre-equilibrium hypothesis.

Use of BD-like model in protein polymerization models

pre-equilibrium nucleation step, constant rates

$$\left\{ \begin{array}{rcl} \dfrac{dc_1}{dt} & = & -(pc_1 - q)y, . \\ \dfrac{dy}{dt} & = & Kc_1^n(+Q(m - c_1(t))) , \\ \dfrac{dz}{dt} & = & (pc_1 - q)y, . \end{array} \right.$$

Ferrone et al., Bophys. J. 32, 1980

$y = \sum_{i \geqslant n} c_i$
$z = \sum_{i \geqslant n} i c_i$
$p(i) = p$, $q(i) = q$
$Q =$ secondary nucleation mechanism (fragmentation, heterogeneous nucleation...)

Use of BD-like model in protein polymerization models

pre-equilibrium nucleation,
polymerization-fragmentation, "oligomers at 0"

Knowles et al., Science 326, 2009

Approximate analytical solution.

$$\begin{cases} \dfrac{dc_1}{dt} &= -pc_1 \sum_{i \geqslant n} c_i + 2q \sum_{i=1}^{n-1} \sum_{j \geqslant i+1} ic_j - nKc_1^n \,. \\[2ex] \dfrac{dc_i}{dt} &= pc_1(c_{i-1} - c_i) - q(i-1)c_i + 2q \sum_{j \geqslant i+1} c_j + Kc_1^n \delta_{i,n} \,, i \geqslant n \,, \end{cases}$$

$$\begin{cases} \dfrac{dc_1}{dt} &= -pc_1 y + n(n-1)qy - nKc_1^n \,. \\[2ex] \dfrac{dy}{dt} &= qz - (2n-1)qy + Kc_1^n \,, \quad y = \sum_{i \geqslant n} c_i \,, \\[2ex] \dfrac{dz}{dt} &= pc_1 y - n(n-1)qy + nKc_1^n \,, \quad z = \sum_{i \geqslant n} ic_i \,. \end{cases}$$

Use of BD-like model in protein polymerization models

Continuous approximation, nucleation as a boundary condition

Helal et al., J. Math. Biol., 2013

$f(t, x)$=number of polymer size x

$N(c_1) = \alpha c_1^n$

$$\begin{cases} \dfrac{\partial f(x, t)}{\partial t} + c_1(t) \dfrac{\partial p(x) f(x, t)}{\partial x} &= [\cdots] . \\ c_1(t) p(x_0) f(x_0, t) &= N(c_1(t)), \\ \dfrac{dc_1}{dt} &= \lambda - \gamma c_1 - nN(c_1) - c_1 \int_{x_0}^{\infty} p(x) f(x, t) \, d \end{cases}$$

Use of BD-like model in protein polymerization models

Continuous approximation, nucleation as a boundary condition

Prigent et al., Plos One, 7, 2012
Banks et al., J. Math. Biol., 74, 2017

$$
\begin{cases}
\dfrac{\partial f(x,t)}{\partial t} + \dfrac{\partial (p(x)c_1(t) - q(x))f(x,t)}{\partial x} &= \left[\cdots \right]. \\
p(x_0)f(x_0,t) &= p(x_0)\dfrac{p_N c_1(t)^n}{q_N + p(x_0)c_1(t)},
\end{cases}
$$

Outline

Large Size, Excess of monomer

We start from a rescaled model ($\varepsilon = 1/n$, $\varepsilon^2 = 1/m$)

$$
\begin{cases}
\dfrac{dc_i^\varepsilon}{dt} &= \dfrac{1}{\varepsilon}\left[J_{i-1}^\varepsilon - J_i^\varepsilon \right], \quad i \geqslant 2, \\
m^\varepsilon &= c_1^\varepsilon(t) + \varepsilon^2 \displaystyle\sum_{i \geqslant 2} i c_i^\varepsilon(t).
\end{cases}
$$

Scaling idea : **excess of monomer**, time scale $= 1/\varepsilon$

$$
c_1^\varepsilon(t) := \varepsilon^2 c_1(t/\varepsilon), \quad c_i^\varepsilon(t) := c_i(t/\varepsilon)
$$

Compensated aggregation / fragmentation

$$
p_i^\varepsilon := \frac{p_i}{\varepsilon^2}, \quad q_i^\varepsilon := q_i, \quad J_i^\varepsilon = p_i^\varepsilon c_1^\varepsilon c_i^\varepsilon - q_{i+1}^\varepsilon c_{i+1}^\varepsilon
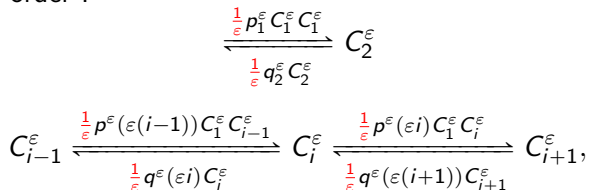$$

and **slow first step** :

$$
p_1^\varepsilon := \frac{p_1}{\varepsilon^4},
$$

Large Size, Excess of monomer

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$$
\begin{cases}
\dfrac{dc_i^\varepsilon}{dt} &= \dfrac{1}{\varepsilon}\left[J_{i-1}^\varepsilon - J_i^\varepsilon\right], \quad i \geqslant 2, \\
m^\varepsilon &= c_1^\varepsilon(t) + \varepsilon^2 \displaystyle\sum_{i \geqslant 2} i c_i^\varepsilon(t).
\end{cases}
$$

From the polymer point of view, we have accelerated fluxes, all of the same order :

$$
\xrightleftharpoons[\frac{1}{\varepsilon} q_2^\varepsilon C_2^\varepsilon]{\frac{1}{\varepsilon} p_1^\varepsilon C_1^\varepsilon C_1^\varepsilon} C_2^\varepsilon
$$

$$
C_{i-1}^\varepsilon \xrightleftharpoons[\frac{1}{\varepsilon} q^\varepsilon(\varepsilon i) C_i^\varepsilon]{\frac{1}{\varepsilon} p^\varepsilon(\varepsilon(i-1)) C_1^\varepsilon C_{i-1}^\varepsilon} C_i^\varepsilon \xrightleftharpoons[\frac{1}{\varepsilon} q^\varepsilon(\varepsilon(i+1)) C_{i+1}^\varepsilon]{\frac{1}{\varepsilon} p^\varepsilon(\varepsilon i) C_1^\varepsilon C_i^\varepsilon} C_{i+1}^\varepsilon,
$$

Large Size, Excess of monomer

We start from a rescaled model ($\varepsilon = 1/n$, $\varepsilon^2 = 1/m$)

$$
\left\{
\begin{array}{rcl}
\dfrac{dc_i^\varepsilon}{dt} & = & \dfrac{1}{\varepsilon}\left[J_{i-1}^\varepsilon - J_i^\varepsilon\right], \quad i \geqslant 2, \\[2mm]
m^\varepsilon & = & c_1^\varepsilon(t) + \varepsilon^2 \displaystyle\sum_{i \geqslant 2} i c_i^\varepsilon(t).
\end{array}
\right.
$$

Weak form : for any test function (φ_i),

$$
\frac{d}{dt} \sum_{i \geqslant 2} c_i^\varepsilon \varphi_i = \frac{1}{\varepsilon} J_2^\varepsilon \varphi_2 + \sum_{i \geqslant 3} J_i^\varepsilon \left[\frac{\varphi_{i+1} - \varphi_i}{\varepsilon} \right].
$$

Large Size, Excess of monomer

We start from a rescaled model ($\varepsilon = 1/n$, $\varepsilon^2 = 1/m$)

$$
\begin{cases}
\dfrac{dc_i^\varepsilon}{dt} &= \dfrac{1}{\varepsilon} \left[J_{i-1}^\varepsilon - J_i^\varepsilon \right], \quad i \geqslant 2, \\
m^\varepsilon &= c_1^\varepsilon(t) + \varepsilon^2 \sum_{i \geqslant 2} i c_i^\varepsilon(t).
\end{cases}
$$

$f^\varepsilon(t,x) = \sum_{i \geqslant 2} c_i^\varepsilon(t) \mathbf{1}_{[(i-1/2)\varepsilon,(i+1/2)\varepsilon)}(x)$, $\varphi_i = \int_{(i-1/2)\varepsilon}^{(i+1/2)\varepsilon} \varphi(x)dx$,

$$
\begin{cases}
\dfrac{d}{dt} \displaystyle\int_0^{+\infty} f^\varepsilon(t,x)\varphi(x)\,dx &= \left[p_1^\varepsilon c_1^\varepsilon(t)^2 - q_2^\varepsilon c_2^\varepsilon(t) \right] \left(\dfrac{1}{\varepsilon} \displaystyle\int_{3/2\varepsilon}^{5/2\varepsilon} \varphi(x)\,dx \right) \\
&\qquad + \displaystyle\int_0^{+\infty} J^\varepsilon(t,x)\Delta_\varepsilon \varphi(x)\,dx, \\
m^\varepsilon &= c_1^\varepsilon(t) + \displaystyle\int_0^{+\infty} x f^\varepsilon(t,x)\,dx.
\end{cases}
$$

where $\Delta_\varepsilon \varphi(x) = \dfrac{\varphi(x+\varepsilon)-\varphi(x)}{\varepsilon}$ and $J^\varepsilon(t,x) = .p^\varepsilon(x)c_1^\varepsilon(t)f^\varepsilon(t,x) - q^\varepsilon(x+\varepsilon)f^\varepsilon(t,x+\varepsilon)$

$$\frac{d}{dt} \int_0^{+\infty} f^\varepsilon(t, x)\varphi(x)\, dx = \left[p_1^\varepsilon c_1^\varepsilon(t)^2 - q_2^\varepsilon c_2^\varepsilon(t) \right] \left(\frac{1}{\varepsilon} \int_{3/2\varepsilon}^{5/2\varepsilon} \varphi(x)\, dx \right)$$

$$+ \int_0^{+\infty} \left[p^\varepsilon(x) c_1^\varepsilon(t) f^\varepsilon(t, x)\Delta_\varepsilon \varphi(x) - q^\varepsilon(x) f^\varepsilon(t, x)\Delta_{-\varepsilon}\varphi(x) \right]\, dx \,,$$

Theorem (Deschamps, Hingant, Y. (2016))

We suppose :

- ▸ *Control and convergence of rate functions*
- ▸ *Control and convergence of initial condition*
- ▸ $p(x) \sim \overline{p}x^{r_p}$, $q(x) \sim \overline{q}x^{r_q}$ *near* $x = 0$*, and* $r_q \geqslant r_p$*.*
- ▸ $c_1(0) > \rho := \lim_{x \to 0} q(x)/p(x)$

$$\frac{d}{dt} \int_0^{+\infty} f^\varepsilon(t, x) \varphi(x) \, dx = \left[p_1^\varepsilon c_1^\varepsilon(t)^2 - q_2^\varepsilon c_2^\varepsilon(t) \right] \left(\frac{1}{\varepsilon} \int_{3/2\varepsilon}^{5/2\varepsilon} \varphi(x) \, dx \right)$$

$$+ \int_0^{+\infty} \left[p^\varepsilon(x) c_1^\varepsilon(t) f^\varepsilon(t, x) \Delta_\varepsilon \varphi(x) - q^\varepsilon(x) f^\varepsilon(t, x) \Delta_{-\varepsilon} \varphi(x) \right] \, dx \,,$$

Theorem (Deschamps, Hingant, Y. (2016))
we have $f^\varepsilon \to f$ (in $\mathcal{C}\left([0, T]; w - * - \mathcal{M}([0, \infty))\right)$) solution of

$$\frac{d}{dt} \int_0^{+\infty} f(t, x) \varphi(x) \, dx = N(t) \varphi(0)$$

$$+ \int_0^{+\infty} \left[p(x) c_1(t) - q(x) \right] \varphi'(x) f(t, x) \, dx \,,$$

for all $\varphi \in C_0[0, \infty)$, which is the weak form of

$$\frac{\partial f}{\partial t} + \frac{\partial (J(x, t) f(t, x))}{\partial x} = 0 \,, \quad \lim_{x \to 0} J(x, t) f(t, x) = N(t) \,.$$

$$\frac{d}{dt} \int_0^{+\infty} f^\varepsilon(t,x)\varphi(x)\,dx = \left[p_1^\varepsilon c_1^\varepsilon(t)^2 - q_2^\varepsilon c_2^\varepsilon(t)\right] \left(\frac{1}{\varepsilon} \int_{3/2\varepsilon}^{5/2\varepsilon} \varphi(x)\,dx\right)$$

$$+ \int_0^{+\infty} \left[p^\varepsilon(x)c_1^\varepsilon(t)f^\varepsilon(t,x)\Delta_\varepsilon\varphi(x) - q^\varepsilon(x)f^\varepsilon(t,x)\Delta_{-\varepsilon}\varphi(x)\right]\,dx\,,$$

Theorem (Deschamps, Hingant, Y. (2016))

$N(t)$ is an explicit function of $c_1(t)$, and is given by a quasi steady-state approximation of $c_2^\varepsilon = f^\varepsilon(t,2\varepsilon)$, given by the solution of

$$\left\{ \begin{array}{rcl} 0 & = & \left[J_{i-1}(c_1) - J_i(c_1)\right]\,, \quad i \geqslant 2\,, \\ c_1(t) & = & c_1\,. \\ J_i(c_1) & = & \overline{p}i^{r_p}c_1 - \overline{q}(i+1)^{r_q}\mathbf{1}_{r_p=r_q}\,. \end{array} \right.$$

When $c_1 > \lim_{x\to 0} \frac{q(x)}{p(x)}$, the solution of $J_i \equiv J \neq 0$ is linked to the loss of mass in the classical BD theory.

Exemples

- For $r_p < r_q$, we get $N(c_1) = \alpha c_1^2$, and

$$\lim_{x \to 0^+} x^{r_p} f(t, x) = \frac{\alpha}{\bar{p}} c_1(t) \,.$$

Exemples

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$$\lim_{x \to 0^+} x^{r_p} f(t, x) = \frac{\alpha}{\overline{p}} c_1(t)\,.$$

- For $r_p = r_q$, we get $N(c_1) = \frac{\alpha}{\overline{p}} c_1(\overline{p} c_1 - \overline{q})$, and

$$\lim_{x \to 0^+} x^{r_p} f(t, x) = \frac{\alpha}{\overline{p}} c_1(t)\,.$$

Exemples

- For $r_p < r_q$, we get $N(c_1) = \alpha c_1^2$, and

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- For $r_p = r_q$, we get $N(c_1) = \frac{\alpha}{\overline{p}} c_1(\overline{p} c_1 - \overline{q})$, and

$$\lim_{x \to 0^+} x^{r_p} f(t, x) = \frac{\alpha}{\overline{p}} c_1(t) \,.$$

- For faster fragmentation rate q_2^ε, we may get $N(c_1) = \alpha c_1^2 \frac{\overline{p} c_1}{\overline{p} c_1 + q_2}$ and

$$\lim_{x \to 0^+} x^{r_p} f(t, x) = \alpha c_1(t) \frac{c_1(t)}{\overline{p} c_1(t) + q_2} \,,$$

or $N(c_1) = 0$, and

$$\lim_{x \to 0^+} x^{r_p} f(t, x) = 0 \,.$$

Outline

Stochastic Becker Döring model

Reversible one-step
coag.-frag.

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$

$$
\begin{cases}
C_i(t) &= C_i^{\mathrm{in}} + J_{i-1}(t) - J_i(t), \quad i \geqslant 2 \\
J_i(t) &= Y_i^+ \Big(\int_0^t p_i C_1(s) C_i(s) ds \Big) \\
&\quad - Y_{i+1}^- \Big(\int_0^t q_{i+1} C_{i+1}(s) ds \Big) \\
C_1(t) &= C_1^{\mathrm{in}} - 2J_1(t) - \sum_{i \geqslant 2} J_i(t),
\end{cases}
$$

▸ Stochastic version : Finite-state space Markov Chain, in

$$X_M := \left\{ C = (C_i)_{i \geqslant 1} \in \mathbb{N}^{\mathbb{N}} : \sum_{i=1}^{\infty} i C_i = M \right\}.$$

Stochastic Becker Döring model

Reversible one-step
coag.-frag.

$$\begin{cases} C_i(t) &= C_i^{\text{in}} + J_{i-1}(t) - J_i(t), \quad i \geqslant 2 \\ J_i(t) &= Y_i^+\left(\int_0^t p_i C_1(s) C_i(s) ds\right) \\ & \quad -Y_{i+1}^-\left(\int_0^t q_{i+1} C_{i+1}(s) ds\right) \\ C_1(t) &= C_1^{\text{in}} - 2J_1(t) - \sum_{i \geqslant 2} J_i(t), \end{cases}$$

$$C_i + C_1 \xrightleftharpoons[q_{i+1}]{p_i} C_{i+1}$$

▸ Stochastic version : Finite-state space Markov Chain, in

$$X_M := \left\{ C = (C_i)_{i \geqslant 1} \in \mathbb{N}^{\mathbb{N}} \, : \, \sum_{i=1}^{\infty} i C_i = M \right\}.$$

▸ Preserves mass for all times

$$\sum_{i=1}^{\infty} i C_i(t) = \sum_{i=1}^{\infty} i C_i(0) =: M.$$

Stochastic Becker-Döring model

Reversible one-step
coag.-frag.

Graph (M=5) at iter. 0

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$
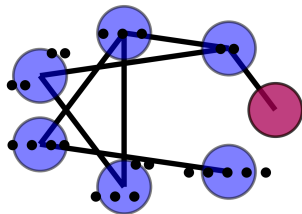
Transitions are given by

$$\mathcal{P} \left\{ \begin{array}{l} C_1(t+dt) = C_1(t) - 2 \\ C_2(t+dt) = C_2(t) + 1 \end{array} \right\} = p_1 C_1(t)(C_1(t) - 1)dt + o(dt)$$

Stochastic Becker-Döring model

Reversible one-step coag.-frag.

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$
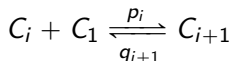
Graph (M=5) at iter. 0

Transitions are given by

$$\mathcal{P} \left\{ \begin{array}{c} C_1(t+dt) = C_1(t) - 1 \\ C_i(t+dt) = C_i(t) - 1 \\ C_{i+1}(t+dt) = C_{i+1}(t) + 1 \end{array} \right\} = p_i C_1(t) C_i(t) dt + o(dt)$$

Stochastic Becker-Döring model

Reversible one-step
coag.-frag.

Graph (M=5) at iter. 0

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$

Transitions are given by

$$\mathcal{P}\left\{ \begin{array}{c} C_1(t+dt) = C_1(t)+1 \\ C_i(t+dt) = C_i(t)+1 \\ C_{i+1}(t+dt) = C_{i+1}(t)-1 \end{array} \right\} = q_{i+1}C_{i+1}(t)dt + o(dt)$$

Stochastic Becker-Döring model

Reversible one-step coag.-frag.

Graph (M=5) at iter. 1

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$
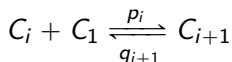

Time interval between transition

$$T_{i+1} - T_i \sim \mathcal{E}\left(p_1 C_1(C_1 - 1) + \sum_{i \geqslant 2} p_i C_1 C_i + q_i C_i\right)$$

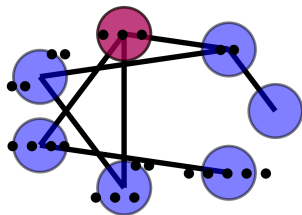A given transition is selected at random according to its weight.

Stochastic Becker-Döring model

Reversible one-step
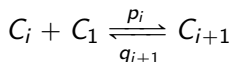coag.-frag.

Graph (M=5) at iter. 2

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftarrows}} C_{i+1}$$

Time interval between transition

$$T_{i+1} - T_i \sim \mathcal{E}\left(p_1 C_1(C_1 - 1) + \sum_{i \geqslant 2} p_i C_1 C_i + q_i C_i\right)$$
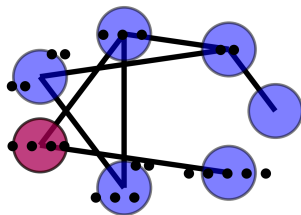
A given transition is selected at random according to its weight.

Stochastic Becker-Döring model
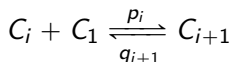
Reversible one-step coag.-frag.

Graph (M=5) at iter. 3

$$C_i + C_1 \xrightleftharpoons[q_{i+1}]{p_i} C_{i+1}$$

Time interval between transition

$$T_{i+1} - T_i \sim \mathcal{E}\left(p_1 C_1 (C_1 - 1) + \sum_{i \geqslant 2} p_i C_1 C_i + q_i C_i \right)$$
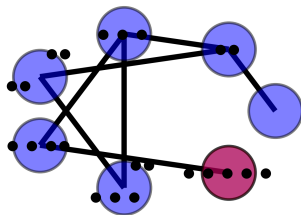
A given transition is selected at random according to its weight.

Stochastic Becker-Döring model

Reversible one-step
coag.-frag.

Graph (M=5) at iter. 4

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$

Time interval between transition

$$T_{i+1} - T_i \sim \mathcal{E}\left(p_1 C_1(C_1 - 1) + \sum_{i \geqslant 2} p_i C_1 C_i + q_i C_i\right)$$

A given transition is selected at random according to its weight.

Stochastic Becker-Döring model

Reversible one-step
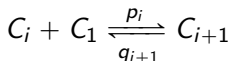coag.-frag.

Graph (M=5) at iter. 5

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$

Time interval between transition

$$T_{i+1} - T_i \sim \mathcal{E}\left(p_1 C_1(C_1 - 1) + \sum_{i \geqslant 2} p_i C_1 C_i + q_i C_i \right)$$

A given transition is selected at random according to its weight.

Stochastic Becker-Döring model
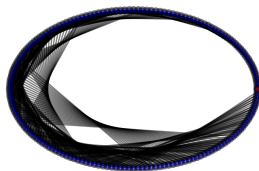
Reversible one-step coag.-frag.

Graph (M=5) at iter. 6

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$

Time interval between transition

$$T_{i+1} - T_i \sim \mathcal{E}\left(p_1 C_1(C_1 - 1) + \sum_{i \geqslant 2} p_i C_1 C_i + q_i C_i\right)$$

A given transition is selected at random according to its weight.

Stochastic Becker-Döring model

Reversible one-step
coag.-frag.

Graph (M=15) at iter. 0

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$

$$X_M := \left\{ C \in \mathbb{N}^{\mathbb{N}} : \sum_{i=1}^{\infty} iC_i = M \right\}$$

Drawback : exponential increase of the size of the state-space !

$$M \mid X_M \mid = \sum_{i=1}^{M} \sigma(i) \mid X_{M-i} \mid, \quad \mid X_M \mid \propto \frac{1}{4M\sqrt{3}} \exp\left(\pi \sqrt{\frac{2M}{3}} \right) ,$$

where $\sigma(i)$ is the sum of the divisors of i

Stochastic Becker-Döring model

Reversible one-step coag.-frag.

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$
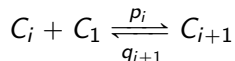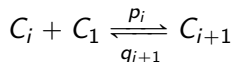
Due to detailed-balance, the asymptotic prob. distribution is

$$\Pi(C) = B_M \prod_{i=1}^{M} \frac{(Q_i)^{C_i}}{C_i!}, \quad Q_i = \frac{p_1 p_2 \cdots p_{i-1}}{q_2 q_3 \cdots q_i}.$$

Stochastic Becker-Döring model
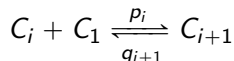
Reversible one-step coag.-frag.

$$C_i + C_1 \xrightleftharpoons[q_{i+1}]{p_i} C_{i+1}$$

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The expected number of clusters of size i is

$$\mathbf{E}_\Pi C_i = Q_i B_M / B_{M-i}, \quad \text{and} \quad M B_M^{-1} = \sum_{i=1}^{M} i Q_i B_{M-i}^{-1}.$$

Stochastic Becker-Döring model

<p style="text-align:center">Reversible one-step coag.-frag.</p>

$$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$

Due to detailed-balance, the asymptotic prob. distribution is

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$$\mathbf{E}_\Pi C_i = Q_i B_M / B_{M-i}, \quad \text{and} \quad M B_M^{-1} = \sum_{i=1}^{M} i Q_i B_{M-i}^{-1}.$$

Moreover, analogy with supercritical case in BD holds :

$$\left(\lim_{i \to \infty} \frac{p_i}{q_{i+1}} = z_s > 0 \right) \Rightarrow \left(\lim_{M \to \infty} \mathbf{E}_\Pi C_i = Q_i z_s^i \right)$$

- With the large volume scaling :
  $c_i^\varepsilon = \varepsilon C_i$, and $p_i = \varepsilon \overline{p}_i$,
  $q_i = \overline{q}_i$: Law of large numbers
  as $M \to \infty$ [Jeon, CMP (1998)]

- Any macroscopic quantity like
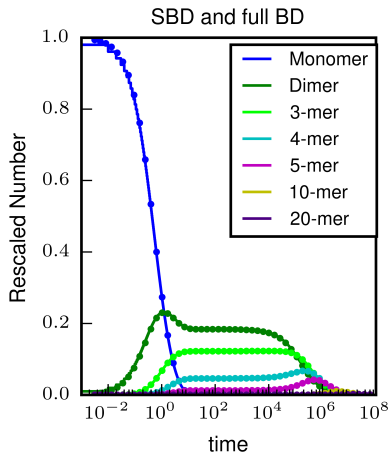
$$\inf\{t \geqslant 0 : \sum_{i \geqslant N} iC_i(t) \geqslant \rho M$$
$$\mid C_i(t = 0) = M\delta_{i=1}\}.$$

  converges *(in standard scaling)*
  to a finite deterministic value as
  $M \to \infty$.

SBD and full BD

Legend: Monomer, Dimer, 3-mer, 4-mer, 5-mer, 10-mer, 20-mer

Rescaled Number vs time
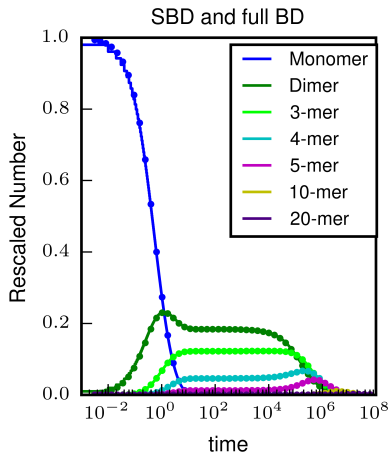
- With the large volume scaling :
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- Any macroscopic quantity like

$$\inf\{t \geqslant 0 : \sum_{i \geqslant N} iC_i(t) \geqslant \rho M$$
$$\mid C_i(t = 0) = M\delta_{i=1}\} .$$

  converges *(in standard scaling)*
  to a finite deterministic value as
  $M \to \infty$.

- This may not be true for
  microscopic quantity, for instance.

$$\inf\{t \geqslant 0 : C_N(t) \geqslant 1$$
$$\mid C_i(t = 0) = M\delta_{i=1}\} .$$

SBD and full BD

[Y., D'Orsogna, Chou JCP (2012)]
[Y., Bernard, Hingant, Pujo-Menjouet JCP (2016)]

Outline

How to explain large variability in $M \to \infty$?

Roughly speaking, due to the law of large number (+CLT), in order to obtain a positive variance in a continuous settings, one needs to avoid that the nucleation occurs in finite time in the limit $M \to \infty$.

- ‣ We seek situations (model, scaling) where the nucleation is a *rare event*, that do not occurs in the deterministic limit $M \to \infty$.

Coarse-Grained model

$$C_1, Y, Z \mapsto \begin{cases} C_1 - n, Y + 1, Z + n & \text{at rate} \quad \alpha(C_1), \\ C_1 - 1, Y, Z + 1 & \text{at rate} \quad pC_1Y, \\ C_1, Y + 1, Z & \text{at rate} \quad qZ. \end{cases}$$

Then, for "small α", and large volume, the lag time is composed of the convolution of an Exponential variable of rate α and a deterministic time given by the ODE

Szavits-Nossan et al., PRL 113, 2014
$Y = \sum_{i \geqslant 2} C_i$, $Z = \sum_{i \geqslant 2} iC_i$

$$\begin{cases} \dfrac{dc_1}{dt} & = & -pc_1y \; (-n\alpha(c_1)). \\ \dfrac{dy}{dt} & = & qz \; (+\alpha(c_1)), \quad y = \sum_{i \geqslant n} c_i, \\ \dfrac{dz}{dt} & = & pc_1y + (n\alpha(c_1)), \quad z = \sum_{i \geqslant n} ic_i. \end{cases}$$

Coarse-Grained model

$$C_1, Z \mapsto \left\{ \begin{array}{lll} C_1 - 2, Z + 2 & \text{at rate} & \varepsilon^\nu \alpha (\varepsilon C_1)^2 \,, \\ C_1 - 1, Z + 1 & \text{at rate} & p(C_1 \varepsilon)(Z \varepsilon) \,. \end{array} \right.$$

Then, for $\nu > 1$, and $\varepsilon \to 0$, the lag time converges "essentially" to an exponential distribution (in the time scale $\varepsilon^\nu t$)
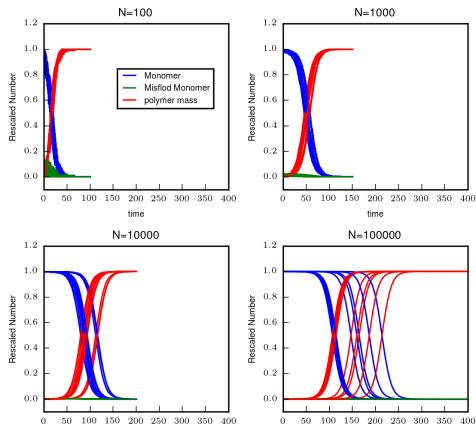
Doumic et al., SIAM J. App. Math., 76(6) (2016)
$Z = \sum_{i \geqslant 2} i C_i$

$$\left\{ \begin{array}{lll} \dfrac{dc_1}{dt} & = & -pc_1 z \ (-2\alpha c_1^2) \,. \\ \dfrac{dz}{dt} & = & pc_1 z \ (+2\alpha c_1^2) \,, \quad z = \sum_{i \geqslant n} i c_i \,. \end{array} \right.$$

Coarse-Grained model

$$\begin{cases} C_1 & \xrightarrow[\gamma_*/\varepsilon^\nu]{\gamma} & C_1^* , \\ C_1^* + C_1^* & \xrightarrow{\varepsilon\alpha} & 2Z , \\ C_1 + Z & \xrightarrow{\varepsilon p} & 2Z . \end{cases}$$
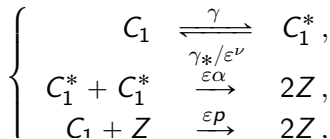
Adapted from *Eugène et al.,JCP, 144(17), 2016* and Doumic et al., SIAM J. App. Math., 76(6) 2016

Then, for the rescaled process $\varepsilon(C_1(t), C_1^*(t), Z(t))$ we observ "translated trajectory" as $\varepsilon \to 0$

Unfavorable aggregation in SBD

Reversible one-step coag.-frag.   *Y. et al., JCP, 144, 2016*

$$C_i + C_1 \underset{q_{i+1}/\varepsilon}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$
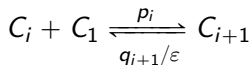
Using pre-equilibrium hypothesis, in the unfavorable aggregation limit, the leading order of the first assembly time of a cluster of size N is

$$< T > \approx_{\varepsilon \to 0} \frac{1}{\varepsilon^{N-2}} \frac{\prod_{k=2}^{N-1} q_k}{\prod_{k=1}^{N-1} p_k \prod_{k=0}^{N-1} (M-k)} \,.$$

Also, in the asymptotic $\varepsilon \to 0$ the first assembly time T is an exponential distribution.

▸ This behavior can be used to couple a first part, very unfavorable, to a second part, favorable or irreversible

Unfavorable aggregation in SBD
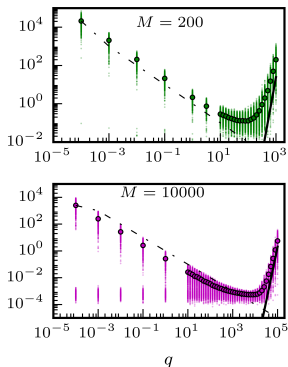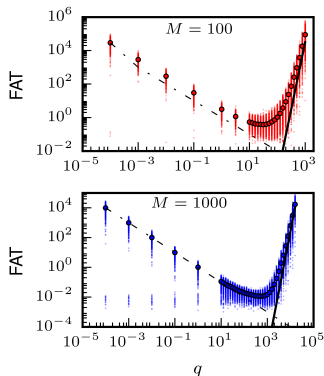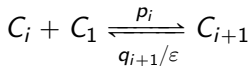
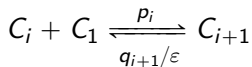Reversible one-step coag.-frag.

Y. et al., JCP, 144, 2016

$$C_i + C_1 \xrightleftharpoons[q_{i+1}/\varepsilon]{p_i} C_{i+1}$$

Unfavorable aggregation in SBD

Reversible one-step coag.-frag.

Y. et al., JCP, 144, 2016
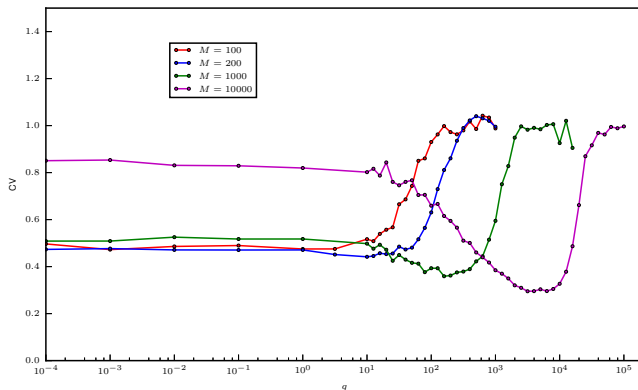
$$C_i + C_1 \underset{q_{i+1}/\varepsilon}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$$

Large nucleus scaling

Reversible
one-step
coag.-frag.

$f^\varepsilon(t, x) = \sum_{i \geqslant 2} C_i^\varepsilon(t) \mathbf{1}_{[(i-1/2)\varepsilon, (i+1/2)\varepsilon)}(x)$
converges towards solution of

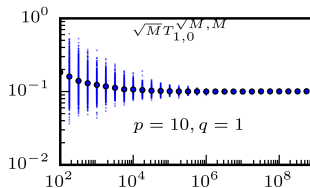$$\frac{\partial f}{\partial t} + \frac{\partial (J(x,t)f(t,x))}{\partial x} = 0,$$

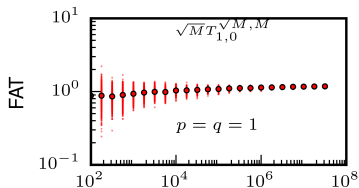$C_i + C_1 \underset{q_{i+1}}{\overset{p_i}{\rightleftharpoons}} C_{i+1}$

(+boundary condition, if needed) and

$$J(x,t) = p(x)c_1(t) - q(x).$$

- How can we obtain large assembly time in this scaling?

Large nucleus scaling

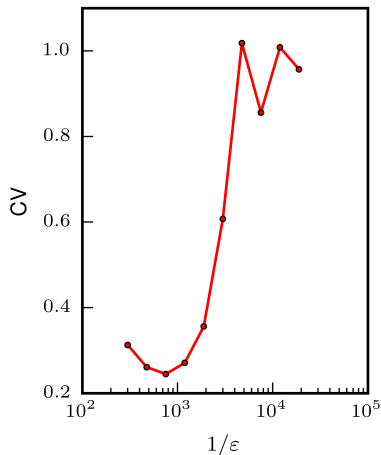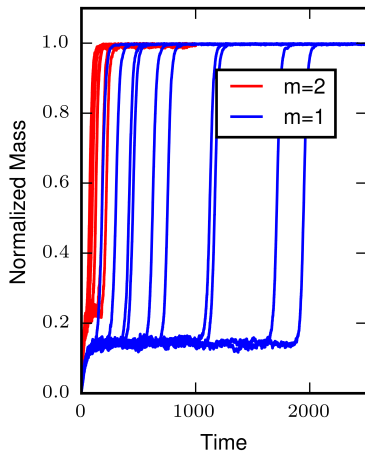- First case $(p(0)m > q(0))$: Convergence towards a deterministic value.
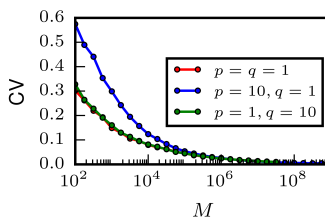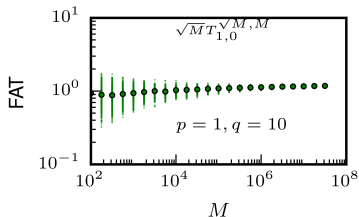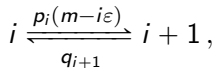

- case A

- case B

Large nucleus $N \sim \sqrt{M}$

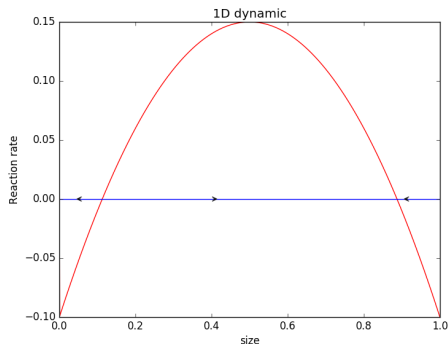- ▸ Second case ($p(0)M < q(0)$) : Exponentially large time and 'translated' trajectory. ($p(x) = x$, $q(x) = 0.1$.)

Quantifying the rare event in a toy model

A much simpler version of this model consider that a **single** aggregate may be formed at a time :

$$i \xrightarrow[q_{i+1}]{p_i(m-i\varepsilon)} i + 1 \,,$$

which converges (with time rescaling) to

$$\frac{dx}{dt} = p(x)(m - x) - q(x)$$

$(m = 1,\ p(x) = x,\ q(x) = 0.1)$

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▸ To leading order the stationary prob. density is

$$u^*(x) = C \frac{e^{-\frac{1}{\varepsilon} \int^x \log\left(\frac{q(y)}{p(y)(m-y)}\right) dy}}{\sqrt{p(x)(m-x)q(x)}} \,.$$

▸ MFPT is explicit and is exponentially large in ε

▸ The "rate" is exponentially small
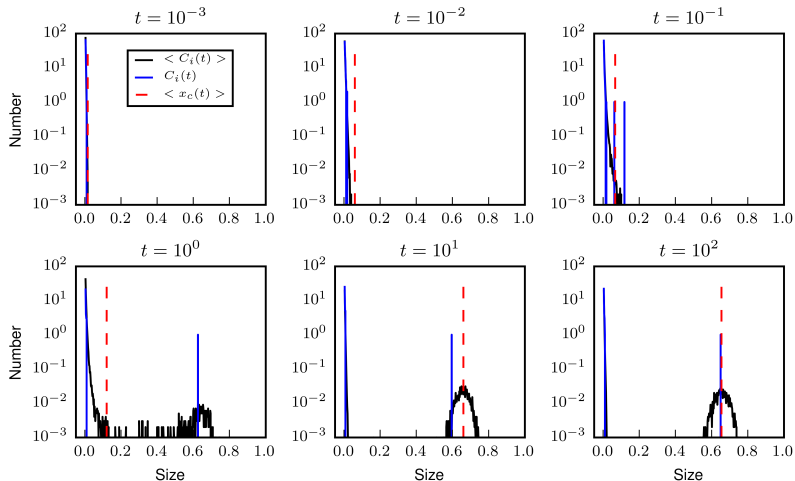
Stochastic view of Classical Nucleation Theory

In the classical scaling from SBD to BD, with gelation coefficients $\left(\sup\left(\sum iQ_i z^i\right) = \rho_s < \infty\right)$, there is a phase transition in **finite random time**
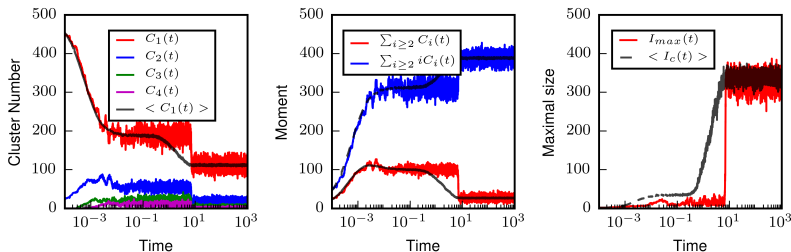
The transition phase is abrupt and corresponds to the rapid formation of a **single** large cluster
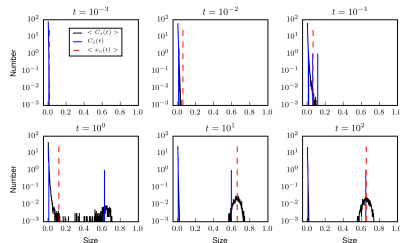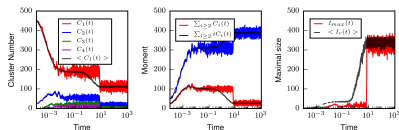
Stochastic view of Classical Nucleation Theory

The transition phase is abrupt, occurs at a **random time** and corresponds to the rapid formation of a **single** large cluster

Open Questions on Metastability in the (S)BD model

Schweitzler et al., Physica A, 150, 1988

- ‣ Which initial conditions go through the metastable state ? *Completely open*
- ‣ How long (and variable) is the metastable period ? *[Partial numerical answers in Y. et al, JCP 137 (2012), Y. et al, JCP 144 (2016)]*
- ‣ How does the largest cluster size I_{max} behave as $M \to \infty$? *[Partial answers in the literature : Niethammer, Penrose, Wattis, etc...*

Summary

- ‣ A framework to include nucleation in continuous-size model
- ‣ A stochastic version of a classical model of nucleation
- ‣ Several scaling possibilities to obtain positive variance in the limit $M \to \infty$.
    - ‣ Rate scaling
    - ‣ Size scaling
    - ‣ Large time behavior (metastability)

Thanks for your attention !
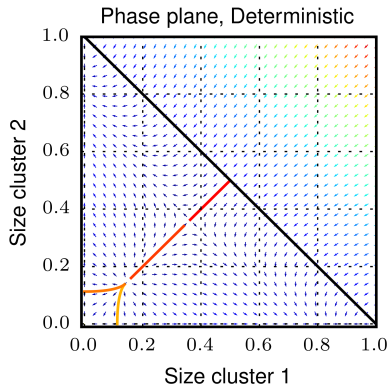
n cluster models

Can we perform LDP calculations with *n* clusters ?

$$(k_0, k_1) \quad \xrightleftharpoons[q_{k_0+1}]{p_{k_0}(m-(k_0+k_1)\varepsilon)} \quad (k_0 + 1, k_1),$$

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which converges (with time rescaling) to

$$\frac{dx}{dt} = p(x)(m - x - y) - q(x)$$
$$\frac{dy}{dt} = p(y)(m - x - y) - q(y)$$

Phase plane, Deterministic

Size cluster 2 (vertical axis, 0.0 to 1.0)
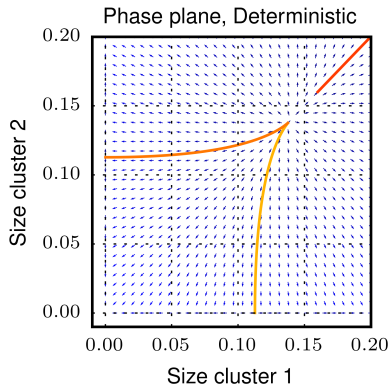
Size cluster 1 (horizontal axis, 0.0 to 1.0)

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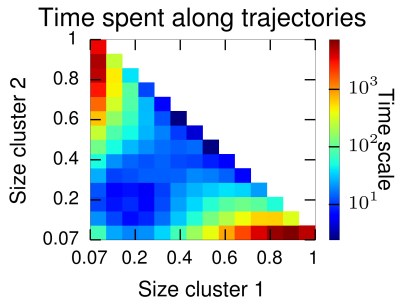

Phase plane, Deterministic

Size cluster 2 / Size cluster 1

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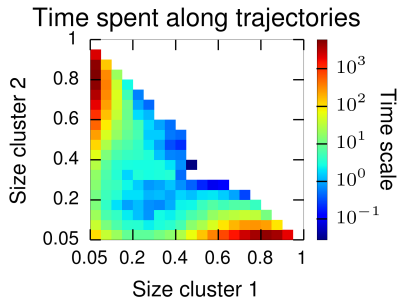$$\frac{dy}{dt} = p(y)(m - x - y) - q(y)$$

Time spent along trajectories

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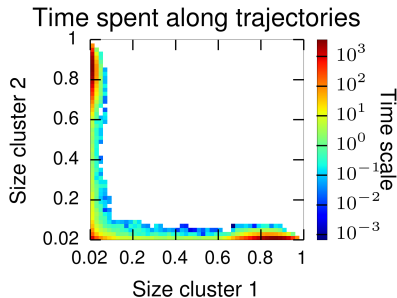$\dfrac{dy}{dt} = p(y)(m - x - y) - q(y)$

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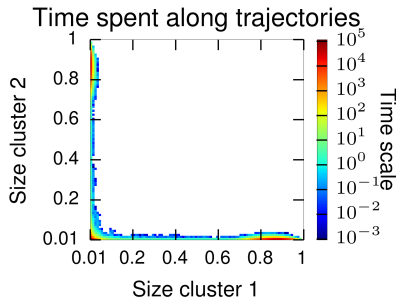$$\frac{dy}{dt} = p(y)(m - x - y) - q(y)$$

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Time spent along trajectories

Size cluster 2 / Size cluster 1 — color scale from 10^{-3} to 10^6 (Time scale)

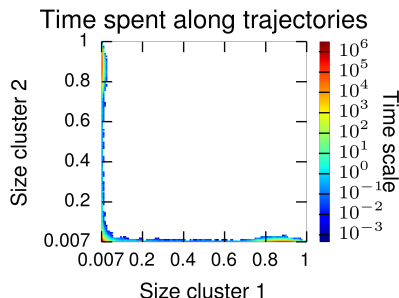## *n* cluster models

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