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COMPLEXITY OF SURFACE TEMPERATURE IN THE URBAN ENVIRONMENT

Directional anisotropy and emissivity

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Introduction : TIR directional anisotropy and emissivity in urban context



Coupling of energy and radiative transfer processes

TIR directional anisotropy (both daytime and nighttime)





Variety of artificial materials + vegetation

Variability of emissivity crucial for urban ST (compositing, directionality, temperature emissivity separation)

Experimental characterization of TIR directional anisotropy



Data acquisition

- Airborne TIR camera with wide-angle lenses inclined backward
- Flight pattern : 4 axis flown in oposite directions crossing at the center of the studied area
- allows a spatio-temporal integration of LST to be performed





Data processing

- Camera : calibration, distortion, etc...
- Atmospheric correction (MODTRAN)
- Assumption $\varepsilon = 1 \rightarrow$ retrieval of **brightness LST** from Brightness Temperature at sensor level

TIR directional anisotropy defined as the difference between oblique and nadir brightness LST :

DBTA = Tb(θ_v , ϕ_v) – Tb_{nadir} zenith viewing angle θ_v : 0 $\rightarrow \sim 60^\circ$ azimuth viewing angle ϕ_v : 0 $\rightarrow 360^\circ$

Examples of anisotropy over Marseille (ESCOMPTE experiment, 2001 :

- the hot spot position follows the Sun displacement
- maximum anisotropy variation with θ_{v} in the principal solar plane
- attention to be paid to possible 'smoothing effect' due to aircraft movements (attitude)







Individual houses with gardens Saint Barnabé district

Less impact in perpendicular plane
 4th EarthTemp Network meeting, 8-10 June 2015, Reading

Lagouarde et al. (2004). Remote Sens. Environ. 93, 443-462

Impact of TIR directional anisotropy on satellite temporal series data (ESCOMPTE/Marseille)



Based on the use of SOLENE (collab. with IRSTV, Nantes)

SOLENE : Software for simulating of sunshine, lighting and thermal radiation

CRENAU (Nantes) http://cerma.archi.fr/









Toulouse / CAPITOUL project

Possible direct approach to simulate directional LST using SOLENE simulations in [0 50°] and [1 360°] zenital θ_v and azimuthal ϕ_v angles too time and computer ressources consuming,

Development of a simplified methodology proposed

Hénon et al., (2012). Part 1: *Theor. Appl. Climatol.*, DOI 10.1007/s00704-012-0615-0. Hénon et al. (2012). Part 2: *Theor. Appl. Climatol.*, DOI 10.1007/s00704-012-0616-z. Modelling daytime directional anisotropy over the city center of Toulouse : methodology



Simplified approach:

based on the aggregation in any viewing direction of 6 directional temperatures only (sunlit/shaded walls/streets/roofs) weighted by their corresponding surface ratios within the scene viewed.

The city is described by 18 canyon streets oriented in all directions

 $T_{b}(\theta_{V},\varphi_{V}) = \left[\sum_{i,j} A_{ij}(\theta_{V},\varphi_{V}) \left[T_{b\,ij}(\theta_{V},\varphi_{V})\right]^{4}\right]^{1/4}$

Actual surface ratios of each class computed from images generated with the POV-Ray software (<u>http://www.povray.org/</u>) and 3D model

Temperatures are determined by integrating SOLENE simulations SOLENE repeated for the 18 canyon streets



Example of temperature and ratio for 2 classes



Directional brightness temperatures (in °C) computed for sunlit walls (a) and sunlit roofs (b) with the 18 canyon street model. July 15th, 11:35 UT



 A_{ij} fractions (in percent) for sunlit walls (c) and sunlit roofs (d) The direction opposite to Sun (ϕ_{vSUN} = 334.1, θ_{vSUN} = 23.9) is referred to by a black cross

Modelling daytime directional anisotropy over Toulouse city center of Toulouse

SUNLIT STREET DIRECTIONAL RATIO

Validation of the 18 canyon street approach against the actual 3D model of Toulouse



SUNLIT WALLS DIRECTIONAL RATIO

Modelling daytime directional anisotropy over Toulouse city center of Toulouse : results



Lagouarde et al. (2010). Remote Sens. Environ. 114, 87-105



- Similar airborne protocol measurements as for daytime
- Similar results obtained on 3 autumn and winter nights
- Anisotropy remains small within the 0 50° range investigated with the M740 camera equipped with wide angle lenses)
- No effect of azimutal viewing direction



- Same methodology as for daytime modeling, but with 3 classes walls/roofs/street only
- 2 models used for computing facet surface temperatures :

SOLENE (with 2 geometries) TEB (Meteo France)

Good agreement model/measurements

• According to sensitivity tests to canopy geometry (not presented here), anisotropy remains lower than 1.5°C up to 60° zenih viewing angles

Lagouarde et al. (2011). Rem. Sens. Environ., 117, 19-33

Modelling nighttime directional anisotropy : simulation/effect of thermal inertia

No more thermal inertia effect remaining about 4 hours after sunset

Modelling nighttime directional anisotropy : simulation/evolution throughout night

Objectives:

- Emissivity facilities and examples in urban area
- Emissivity estimation from aircraft
- Error budget to retrieve emissivity and temperature
- Unmixing in the LWIR

In-lab and ou-door facilities to measure the spectral emissivity

Quasi simultaneous measures on solar spectral reflectance and spectral emissivity

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that party and the set of the

... Stored in ONERA MEMOIRES data base

0.5

Several types of brick, tile, asphalt (road, pavement), paint, rendered facade, marble, ... in terms of color, use, age

brique saumon

Emissivity/temperature retrieval in urban area: methodology (Valence university, J. Sobrino, R. Oltra-Carrio)

$$L_i(T_i) = L_{g,i}\tau_i + L_i^{\uparrow}$$
+ MODTRAN $L_{g,i} = \varepsilon_i B_i(T_s) + (1 - \varepsilon_i) L_i^{\downarrow}$

$$L_{g,i} = \frac{L_i(T_i) - L_i^{\uparrow}}{\tau_i}$$

LSE retrieval

<u>NDVI™</u>*

Input: ρ_{red} ; ρ_{NIR}

* Sobrino, J. A., et al. 2008. IEEE TGRS, 46.

<u>TES</u>**

Input: L_{g,TIR} AHS TIR channels: 72, 73, 75, 76, 77, 78, 79 Gillespie, A. et al. 1998. IEEE TGRS, 36(4)

TISI^{***} Input: $L_{g,MWIR}$; $L_{g,TIR}$ night and day Becker, F. Li, Z.-L., 1990. RSE, 32.

LST retrieval

Split Window

Input: w, LSE, T_{sensor}

i=AHS band 75, j=AHS band 79

Emissivity/temperature retrieval in urban area: DESIREX experiment (Valence university, J. Sobrino, R. Oltra-Carrio)

DESIREX 2008 field campaign:

- Founded by the ESA
- Coordinated by the Global Change Unit (GCU) from the University of Valencia (UVEG)
- Data acquisition in collaboration with different European teams

Data acquired:

•Airborne data with the AHS sensor covering two different patterns

•Spaceborne images: ASTER/TERRA, MODIS/TERRA.

•Atmospheric and ground parameters: air temperature, surface temperature, wind speed and direction, emissivity and reflectivity of urban and rural surfaces, radiation balance. (In situ measurements, fixed masts and car transects)

J.A. Sobrino, R. Oltra-Carrio, J.C. Jimenez-Mu~noz, Y. Julien, G. Soria, B. Franch, and C. Mattar. Emissivity mapping over urban areas using a classication-based approach: Application to the Dual-use European Security IR Experiment (DESIREX). International Journal of Applied Earth Observation and Geoinformation, 18:141{147, 2012.

Emissivity/temperature retrieval in urban area: Results (Valence university, J. Sobrino, R. Oltra-Carrio)

Results from AHS with ASTER configuration bands

Good performance for λ> 10 µm Better performance of algorithms TES and TISI

Error budget: methodology (ONERA, Valence univ.)

•TITAN 3D RT (Modtr analysis 3 Error sources:

- •TES algorithm
- Atmospheric correction
- •3D structure of the city

"TITAN : an Infrared Radiative Transfer Model for Heterogeneous 3-D Surface - Application over Urban Areas", <u>G.</u> Fontanilles, <u>X. Briottet</u>, T. Tremas, Applied Optics, Vol. 47, Issue 31, pp. 5799-5810

Error budget: TES algorithm (Gillespie, 1998)

ε_{min} and MMD relationship

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Error budget: TES algorithm (Gillespie, 1998)

Scene definition

- LST: 295 K, 300 K, 305 K, 310 K
- 36 targets (9 materials at four LST)
- Atmospheric conditions: DESIREX atmospheric profile (w= 1.59 g/cm²)
- illumination conditions: same as in DESIREX (θ_s =20.11°, φ_s =144.5°)
- Observation conditions: sensor altitude = 1866m; nadir viewing

Error budget: TES algorithm (Gillespie, 1998)

Error budget: Atmospheric correction

- LST: 295 K, 300 K, 305 K, 310 K
- 36 targets (9 materials at four LST)
- Atmospheric conditions: DESIREX atmospheric profile (w= 1.59 g/cm²)
- illumination conditions: same as in DESIREX (θ_s =20.11°, φ_s =144.5°)
- Observation conditions: sensor altitude = 1866m; nadir viewing
- Inversion procedure: new values of water vapour content;
- w' = ± 20%w (w'= 1.27 g/cm²; 1.91 g/cm²)

Error budget: Atmospheric correction

Error budget: 3D shape

Scene definition

• Building height : 15 m

	Canyon A	Canyon B	Canyon C	Canyon D
Street width (m)	10	10	10	10
Buildings width (m)	15	15	15	15
Left building height (m)	15	22	30	50
Right building height (m)	12	16	24	44

									. `
		Test 1	Test 2	Test 3	Test 4	Test 5	Test 6	Test 7	
Wall (Brick)	Sunlit LST (K)	296	301	306	311	316	321	326	Ι
	Shaded LST (K)	286	291	296	301	306	311	316	
Ω_{t}	Sunlit LST (K)	316						Ī	
Street (Asphait)	Shaded LST (K)	301							
Roof (Tile)	Sunlit LST (K)	311			•				
AT (K)		300.8							

- Atmospheric conditions: DESIREX atmospheric profile (w= 1.59 g/cm²)
- Illumination conditions: same as in DESIREX (θ_s =20.11°, φ_s =144.5°)
- Observation conditions: sensor altitude = 1866m; nadir viewing

Error budget: 3D shape

• RMSE increases when the wall LST does. Except for the points closest to the shaded wall.

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- When going from the sunlit to the shaded facets, the RMSE decreases.
- At the center of the canyon the RMSE increases with the canyons height.
- The bias decreases next to both walls.

Man-made materials (Flat assumption)

Error source	LSE RMSE	LST RMSE (K)		
TES algorithm	0.017	0.9		
Atmospheric correction	0.005	0.4		
Root Sum Square	0.018	1		

Asphalt (with 3D)

Error source	LSE RMSE	LST RMSE (K)
TES algorithm	0.001	0.1
Atmospheric correction	0.005	0.4
3D structure (Test 4)	0.005	0.2
Root Sum Square	0.007	0.5

R. Oltra-Carri'o, M. Cubero-Castan, X. Briottet & J. Sobrino, "Analysis of the performance of the TES algorithm over urban areas", IEEE Transactions on Geoscience and Remote Sensing, vol.52, no.11, pp.6989-6998, Nov. 2014.

Unmixing: context

Pure pixel

atmosphere

Required steps:

- Atmospheric Compensation
- TES

Mixed pixel

Three steps to retrieve:

- The number of endmembers,
- The endmembers: Ti, εi
- Their abundances.

"Aggregation process of optical properties and temperature over heterogeneous surfaces in the infrared domain", G. Fontanilles, X. Briottet, S. Fabre, S. Lefebvre and P.-F. Vandenhaute, Applied Optics, 20 Août 2010, Vol 49 N° 26, pp 4655-4669

Unmixing: TRUST methodology (ONERA, GIPSA-Lab)

A two-steps process:

- Estimation of the **mean temperature** and the **emissivity** on pure pixels, with a supervised or unsupervised localization.
- Estimation of the subpixel temperature and the abundances with TRUST method

Constraint: take into account the intraclass spatial variability of the temperature

Manuel Cubero-Castan, Jocelyn Chanussot, Véronique Achard, Xavier Briottet, Michal Shimoni. "A physics-based unmixing method to estimate subpixel temperatures on mixed pixels", Geoscience and Remote Sensing, IEEE Transactions on. Vol. 53, N. 4, 03/2015.

Image: TASI sensor (32 bands, 8-12 μ m) with 1m GSD. DUCAS Experiment (EDA) at Zeebruges, Belgium (2011).

Image Pan - CANON/FOI - EDA DUCAS Pure and mixed pixels location - Image EAGLE/Fraunhofer IOSB - EDA DUCAS

Unmixing: results

Abundance map

Sub pixel temperature

- Abundance: TRUST method favors the sparsity
- **Coherent** estimation of subpixel temperatures when 2 endmembers
- Errors: mis-estimation of the abundance, 3 endmembers mixed pixel

General conclusion

 Experimental methodology for characterizing brightness temperature directional anisotropy efficient, but can be improved (a little)

- Simplified simulation methodology combining a transfer model and 3D information allows to simulate directional anisotropy.
- Impact of small scale heterogeinities on daytime anisotropy to be evaluated
- Nighttime anisotropy < 2K</p>
- ◆ Documentation of spectral emissivity → MEMOIRES database
- Availability of a complete simulator LES, LST surface ↔ sensor (radiative transfer withTITAN + atmosphere + instrument)
- Adaptation of TES to urban surfaces

PART 2 emissivity

