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Platforms of Palaeolithic knappers reveal complex linguistic abilities

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ABSTRACT

Recent studies in cognitive neurosciences have postulated a possible link between manual praxis such as tool-making and human languages. If confirmed, such a link opens significant avenues towards the study of the evolution of natural languages. Yet, archaeologists would need the development of a rigorous methodology to formalize language appearance. We propose a 'formal grammar of action' to help formalizing some early aspects of lithic chaînes opératoires, and simultaneously question the link with human cognitive abilities. The approach, based on the foundations of Chomsky's minimalist program and the grammar of action theory, focuses on the development of components and syntax suggested by some aspects of knapping during early phases and simple (Oldowan and early Acheulean) technologies. In this theoretical study, we rigorously analyse terminals and non-terminals (vocabulary), production rules and syntax (grammar) of idealized stone technologies and then provide possible productions (tools and handaxes). More specifically, issues related to platform preparation and cognitive strategies required during knapping are discussed. Formal grammars proposed here for interpreting knapping contribute to a greater systematization in classifying chaînes opératoires and in exploring complexity in lithic reduction sequences. As a central result, these grammars are theoretically able to rigorously demonstrate syntax presence and central recursion, thus helping us to study early linguistic abilities.

Keywords: Oldowan, Stone Technologies, natural language, formal grammar, cognitive ability.



more complex procedures with a focus on shaping large flakes or other blanks into a range of artefacts. Such later artefacts highlight increasingly symmetrical, predominantly bifacial flaked tools such as handaxes and cleavers (Beyene et al. 2013; Goren-Inbar 2011; Gowlett et al. 2014; Moore 2010; Pappu et al. 2011; Pelegrin 1990; Sharon and Goren Inbar 1999; Texier 1996). This progression of abilities strongly suggests that formalizing the sequence of actions in knapping, to produce flakes or shape bifaces, would greatly help in understanding structural and temporal (i.e. sequential and syntactical) aspects of how primitive (i.e. atomic or unitarian) motor actions combine to produce complex tool types.

Only a few models have been developed for this purpose. Among them, grammars of actions have been proposed in the past, from abstract 'design space' (Greenfield 1991; Moore 2010; Muller et al. 2017), to more formal grammars inspired from linguistics (Chomsky 1995; Mahaney 2014; Pastra and Aloimonos 2012). The 'Minimalist Grammar of Action (MGA) possibly provides the most powerful formalization framework for goal-directed actions. Such formal systems belong to the large body of discrete-event models (Gaucherel et al. 2012; Gaucherel and Pommereau 2019), models handling discrete components and events that seem better adapted than continuous equation-based models for such human activities. Such a formalism inheriting from the Chomskyan minimalist program, not confined to the idiosyncrasies of human language, would thus benefit from long experience and an expanded toolbox. The closest study to the present paper (Mahaney 2014) differs in three main aspects: first, it builds on an earlier Chomskyan program (Chomsky 1956); secondly, it focuses mainly on a highly complex (Acheulean) lithic technology on the basis of observed assemblages; thirdly and above all, it sets out to demonstrate the homology between the knapping process and natural language (on the basis of an informational Shannon measure), which this study does not.

Here, we draw on the theoretical foundations of the MGA following Pastra and Aloimonos (2012) to define a rigorous grammar of action dedicated to understanding strategies of flaking patterns noted in the Lower Palaeolithic technologies. In a more conservative way, we use this grammar to identify the cognitive strategies responsible for the knapping actions. We intend to address two interlinked questions: i) examining actions and action ordering required for knapping flakes; and ii) exploring cognitive strategies in these tool reduction sequences. The central hypothesis is that high-order syntax and cognitive abilities possibly exist as early on as the Oldowan epoch (Harmand et al. 2015). Although reasonable, it seems that this hypothesis has never been "demonstrated", i.e. tested with a formal model. Finally, we will discuss the heuristic abilities of such formalization of Palaeolithic reduction sequences in terms of semantic (and evolutionary) perspectives.

2. Materials - Lithic Reduction Sequences

Numerous studies testify to the relationship between knapping methods and tool form, in the sense that certain strategies, such as shaping bifaces, require a complex sequence of actions (Belfer-Cohen and Goren-Inbar 1994; Bradley and Sampson 1986; Goren-Inbar et al. 2011; Moore 2010; Newcomer 1971; Roche and Texier 1991; Sharon and Goren Inbar 1999; Texier 1996). The main objective of action grammars should be to help in interpreting this development of knapping complexity in terms of the properties used in grammar. The ultimate issue for the model would be to discriminate between various hierarchical organizations of

a



b



Figure 1. (a) Examples of Oldowan artefacts (courtesy Dr Kathy Kuman), (b) and Acheulean artefacts (courtesy Kumar Akhilesh, inset scale is 10 cm).

Striking a core with a hammerstone not only supposes actions involving direct percussion, but also requires knowledge of the geometry of the core (i.e. for producing a flake or for producing a tool). This includes rotation (around a horizontal axis) of the core, followed by turning (vertical axis) to determine the correct surface to strike, or the 'platform', and lastly by tilting to adjust for the angle at which the platform is to be struck at the point of impact. This action is almost instantaneous (and unconscious) for expert knappers, and the entire process should thus be considered as one complex striking action. Geometrical identification leading to the striking of a flake thus occurs. The specificities of the grammar of action for this sequence are named ST2. At this stage, we should differentiate the debitage, for which the aim is to produce



flakes, to the *façonnage*, producing a tool from the core and for which flakes are waste products only. Hence, these knapping methods show sharp conceptual differences by the aim or the intent of a single strike.

Contrary to flakes, handaxes are shaped by successive flake detachments (Bradley and Sampson 1986; Kumar and Pappu 2015) primarily designed to create a suitable working edge (Fig. 1b). Platform is a general term, sometimes termed *beveling*, which indicates the presence on a blank of a surface that was intentionally struck for knapping activities, be it prepared or not; therefore, if a “stone” is identified as a core, it should have at least one striking platform. Although platforms on cores are noted even at Oldowan sites (de la Torre 2011; Hovers 2012; Toth 1985), early Acheulean assemblages do not always display evidence of the presence of faceting (Kumar and Pappu 2015). Here, we will focus on *chaînes opératoires* of handaxes shaping only, involving the intentional preparation of a striking platform through faceting, not to be confused with multifaceted butts in other knapping methods (de la Torre 2011). Detachment of these ‘anticipatory flakes’ on the faceted platform (Moore 2010), a priori requires the same set of actions as in the case of flake detachment strategies, possibly with a preliminary assessment of the geometry of the blank/handaxe preform and its positioning prior to flaking. The blank/preform may be flipped between platform preparations and removing the objective flake, which is included hereafter in the ‘move core’ action (Fig. 1b). This preform is already correctly positioned in most instances, prior to application of a combined action set to tilt and strike at finer scales in order to facet the platform. This sequence is formalized as ST3.

In addition to faceting a platform, the knapper may repeatedly abrade (i.e. grind) the surface to create a suitable platform; this sequence of actions differs from that involved in faceting (Stout et al. 2014). This step concerns artefacts from late Acheulean and possibly earlier. This sequence requires estimating platform angularity, a kind of platform strength proxy, instead of estimating the high-mass distribution of the core (Young and Bonnichsen 1984). In addition, platform abrasion involves rubbing and shearing the core, instead of striking it, although similar geometry identification also takes place in this process. Moore used the term, ‘elaborated flake unit’, to define the combination of platform abrasion and detachment of the ‘objective flake’ terminating the process (Moore 2010; Young and Bonnichsen 1984). This fourth stone technology requiring a platform of another kind (any action different to that of faceting, such as abrasion with hard or organic soft hammers) is named ST3’.

Other elaborated flake units occur in modern human assemblages from the Late Pleistocene onwards. However, with the four above-mentioned technological strategies, we already have sufficient action diversity to explore grammatical syntax of knapping, if any. In order to shape a complete handaxe, sequences ST2 to ST3 and ST3’, should then be combined in specific ways. As regards handaxes, ways in which flake units are combined into assemblies and higher-order units appear even more complicated (Mahaney 2014; Muller et al. 2017), and will not be analysed in this study.



3. Methods - Grammars of action

Here, we draw on the 'Minimalist Grammar of Action' (MGA) (Pastra and Aloimonos 2012) inspired by the latest formulation of the Chomskyan tradition of generative grammar (Chomsky 1995), and apply it to the study of lithic technological strategies. Generative grammars initially developed to analyse natural (human) languages, and are composed of a set of elements and a set of production (or rewriting) rules that predict acceptable combinations of elements (i.e. phrases). The latest version of generative grammars provides a mathematical framework that concentrates a grammar into a powerful computational mechanism imbued with the principle of economy/minimalism in both the production of phrases (derivation) and representation of syntactic structures (Chomsky 1995). Hence, we will use concepts of Recursion, Merge and Move of this grammar (Pastra and Aloimonos 2012), to build a dedicated grammar of action. These three operations are central and allow reiterating into, combining with and shifting some structures into others, respectively.

Pastra and Aloimonos (2012) observe that the generative grammar of such a language is a set of sentences made up of words and of intermediate structures. Hence, it requires: i) a set of terminals (T) consisting in lexical units (tip or primitive elements) in a parse tree combining them and representing the analysed structure; and ii) a finite set of non-terminals (NT) or phrase types combining the terminals and non-terminals. As such, NTs are syntactic categories recursively producing an infinite number of grammatical structures. This recursion is a central principle for repeating a process, i.e. a rule rewrites as a previous rule or as itself (Pastra and Aloimonos 2012), examples are given in the following section. A recursion may be terminal if made at the end of a sequence (a phrase), or central if it temporarily interrupts a sequence. The derivation of a syntactic structure, i.e. a phrase construction, starts as a bottom-up approach. A 'Merge' function checks the features of a terminal 'T' and for those features with un-attributed values (i.e. variables), it initiates a 'Search' for another unit whose feature-values can be unified with the variables (Chomsky 1995; Lasnik 2002). This merging is applied recursively until all features are 'interpreted' (have a value). The additional 'Move' operator is the merging of a syntactic element with itself, and is frequently used (Pastra and Aloimonos 2012). Additional details may be found the previously cited papers as well as in the figure captions.

In this context, the sensorimotor domain is associated with a set of terminals (action primitives, i.e. which may not be decomposed), non-terminals ('phrases' of actions, combining the previous ones) and production rules (merging) for its generative grammar. The MGA proposes a human action to be defined as: 'a serial or parallel conjunction of perceptible movements carried out by one or more actors with a certain goal' (Pastra and Aloimonos 2012). These authors show that simpler models, such as finite automata, would not be appropriate to formalize such complex actions. This leads to three specific rules dedicated to actions and later applied to knapping: the 'tool complement' of an action, the 'affected-object' complement, and the 'goal' of the whole action structure (Pastra and Aloimonos 2012). These syntactic features go beyond (mostly quantitative) movement execution features such as direction, velocity, etc. in that they distinguish one action type from another (see Pastra and Aloimonos 2012: 106, for more details). The tool complement (tc) is the effector of a movement, such as a body part, a combination of body parts or the extension of a body part with a graspable object used as a tool. The object complement (Oc) is any object affected by a tool use



action. The goal (g) is the final purpose of an action sequence of any length or complexity (Fogassi et al. 2005), yet predicted from the very first action primitives of the sequence. Here, note that the present model differs from Mahaney's model in that it assumes that the knapper has a goal, irrespective the stone technology, an assumption incompatible with Mahaney's blind Markov model (Mahaney 2014). A goal might be conscious or unconscious, as to shape a tool or to simply produce a flake, respectively. Finally, a modifier (m) may be added to this list to denote the location/scene an action takes place at.

The vocabulary of MGA is composed of action terminals (A), action non-terminals (A') and action grammar rules based on entities (i.e. perceptible objects participating in any motor program) and on the three main previous syntactic features (see Pastra and Aloimonos 2012: 108, figure 1). The former defines primitive and combined actions (in a certain temporal sequence) that are perceptible movements carried out by an agent to achieve a goal, which have one or more body part tool-complements and no object complements. The latter define the action grammar production rules (Pastra and Aloimonos 2012): [4] $A \rightarrow g, A; 3) A \rightarrow (m), A; 2) A \rightarrow A, Oc; 1) A \rightarrow A, tc]$, with the plus notations and where A'' is the maximal (last) action structure. These rules state that any set of actions has a compulsory goal specifier and a compulsory tool complement, whereas modifier and object complement are optional only (in parentheses). Concerning the motor program mentioned, the ongoing debated about the exact definition an action is out of the scope of this work (e.g. Biryukova and Brill 2008). Hereafter, we will thus assume for the sake of simplicity that any action is associated to a specific movement (i.e. into a bijective relationship).

So, any action tree, such as those shown in the following section, can now be rigorously derived bottom-up through recursive application of the grammar rules, from 1 (A) to 4 (A'') (Pastra and Aloimonos 2012). E'' is the maximal projection of an entity structure. Triangles in the tree denote that the corresponding part of the tree is not fully analysed for keeping the figure simple. Parentheses present the morphological features of the corresponding tree nodes, in an 'attribute:value' format; the plus sign denotes the presence of such features, while a minus denotes the absence of a feature. The exact type of relation between branches of the tree is clearly denoted for clarification purposes; 'action-tool' and 'action-object' are complements of an action and as such they are inherently related to the corresponding action structure. Sub-actions of a complex action are sequential or parallel in time, i.e. they are related through the corresponding 'temporal conjunction' type (tempConj:sequ, or tempConj:par). All other features are specific to each action tree (see fig. captions). The proposed grammar of knapping has been built manually, but Pastra and Aloimonos (2012) have developed a parser that could theoretically allow the automatic application of MGA to stone technologies.

4. Results - A grammar of knapping

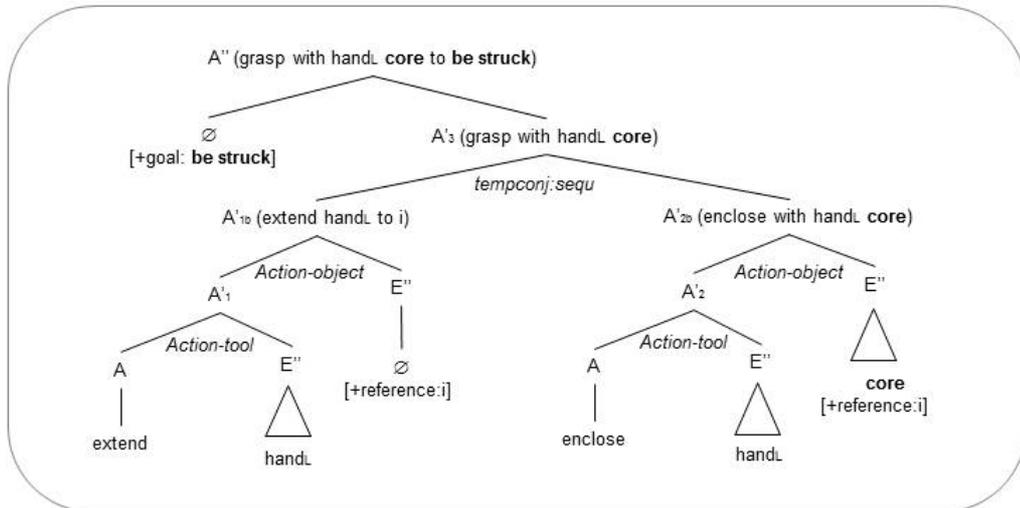
Here, we present and explain the successive action trees and production rules corresponding to Lower Palaeolithic sequences (ST1 to ST3'). The sequences used in this theoretical work have been idealized on the basis of (my) knapping experience, and do not correspond to any specific artefact.



4.1 First Stone Technology. ST1

The action parse tree related to the first stone technology (ST1) shows action-tool binary branches (Fig. 2a). This part of an action tree for 'grasp with handL core to be struck' is produced bottom-up by successive merging and checking, in a very similar way to the first example 'grasp [apple] with hand knife to slice' of MGA (Pastra and Aloimonos 2012). The action sequentially develops rightward, meaning that actions come successively (not to be confused to the action geometry). A similar action tree for 'grasping the hammerstone with handR to strike' can be drawn (not shown). Then, a maximum action tree can be built for 'striking a core with hammerstone' by sequentially combining the two previous trees (i.e. to grasp core and to grasp hammerstone) and checking their compatibility (Fig. 2b). Action A'3a shares the same tool complement with A'1a (handR) and its object complement (hammerstone) is referred to as A'1a. Therefore, its expected position is semantically exactly after A'1a in position A'1b. However, owing to the disruption by other actions (with handL), this position is empty; the action is in position A'3a. Thus, a 'trace' of the action is left in position A'1b, which is linked with the action in position A'3a. The two structures A'1 and A'3 are not temporally combined, they are discontinuous; the actions A'2 that intervene here are part of the same action structure (Pastra and Aloimonos 2012). After linking the discontinuous sub-action constituents, structure A'2 is found to share an object complement with constituents of the action structure A'3 (i.e. the core). Importantly, we slightly modified the MGA pattern to handle fine scale binary branches only, except in implicit terminal actions (Fig. 2b).

a



ST1

b

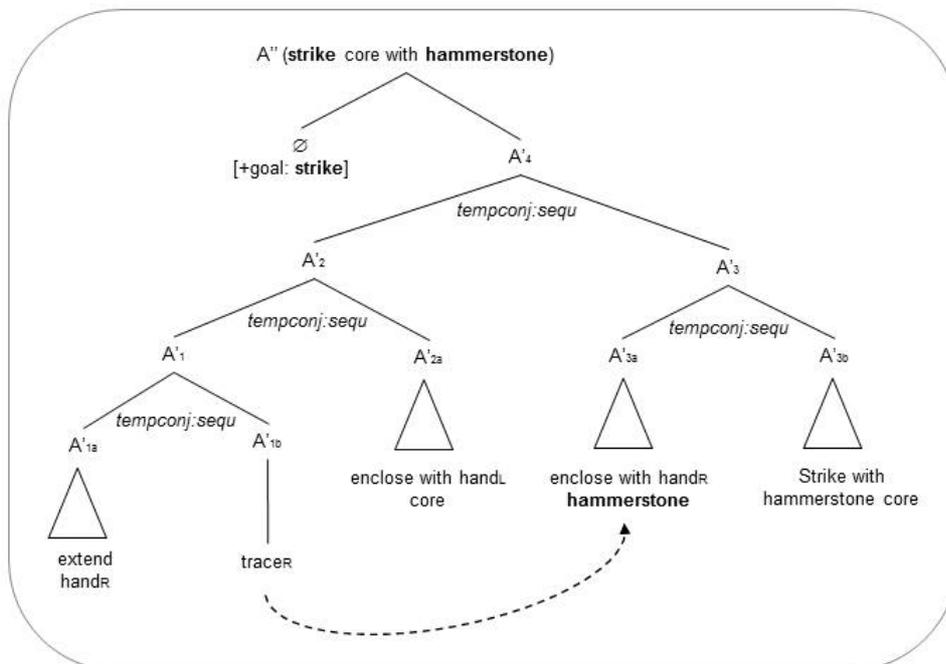


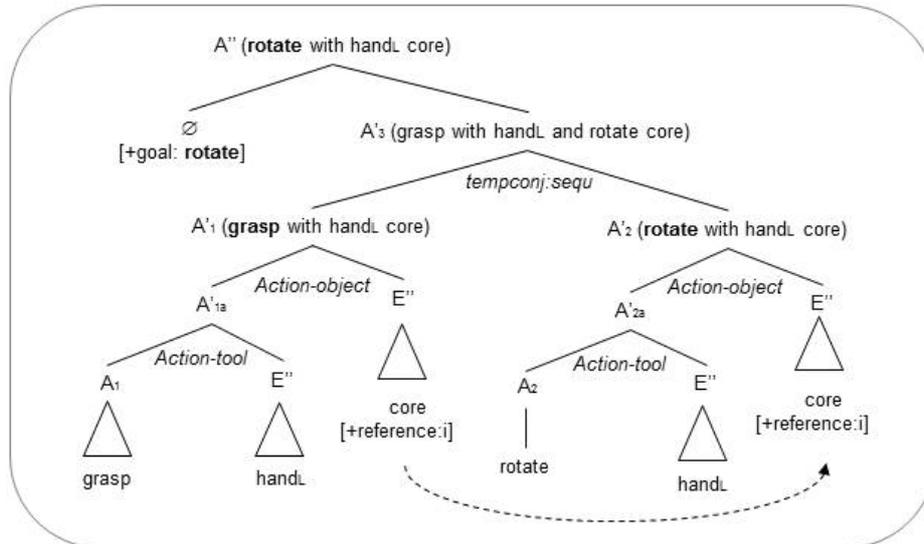
Figure 2. Action trees related to ST1 stone technology. Part of an action tree for ‘grasping with handL core to be struck’ (a), maximum action tree for ‘strike core (handR) with hammerstone (handL)’ (b), and display of the corresponding struck core (insert). The second action tree (b) duplicates the first one (a), as to strike first supposes to grasp core and to grasp hammer. In (a), we assume that: i) the core is fixed to examine it, ii) the hammer may be chosen earlier but used sequentially later, and iii) the core size is small enough so that it is held in the hand. In (b), the trace (linguistic terminology of Chomsky) states that the object to be held in the left hand is the same as that the one to be struck by the right hand.

Thus, based on Figures 2a and 2b, the three independent action structures identified are combined into a common structure with a common final goal. At this stage, it is possible to list terminal and non-terminal actions as well as the production rules concerned by ST1. Starting from terminal entities such as left/right hand, core, hammerstone, action terminals, non-terminals, and maximal action structure can be listed alongside the corresponding production rules (Table 1). Rule number one uses a tool complement (to grasp tools), rule two an (affected) object complement (struck core), and rule three a goal (to strike a tool with the other one). Interestingly, there is no need here for any rule with a modifier, as the movement of the core (e.g. turning, tilting, etc.) is a property of the object itself and thus no other movement need be considered here. This final action tree corresponds to the simplest possible striking action between two objects grasped in two hands (ST1). It does not necessarily presuppose any complex knowledge of the geometry of the core to adjust for the correct angle of striking the same and therefore does not usually produce any real flakes. ST1 involves the same gestures as nut cracking but applied to stone; it is not a knapping strategy in that it does not yet presuppose intentional core reduction.

Stone Technology	Main characteristic	Associated vocabulary (T or primitive, NT or intermediate, MA or latest ones)	Grammatical rules	Associated cognitive strategy
ST1	Simple strike (Fig. 2)	T = {extend, enclose, reach, strike}, NT = {extend hand, enclose with hand, grasp with hand, strike with tool}, MA = {strike core with hammerstone}	3) A'' → striking, A' 2) A' → A', (core) 1) A' → A, hammerstone	Pairing (Fig. 6a)
ST2	With geometrical identification (Fig. 3)	T = {grasp with hand, rotate, turn, tilt, strike}, NT = {move, position, correctly strike}, MA = {flake}	3) A'' → flake, A' 2) A' → A', (positioned core) 1) A' → A, hammerstone	Pot (Fig. 6b)
ST3	Platform facet (Fig. 4)	Same as ST2 + NT = {platform facet}, MA = {elaborated flake}	3) A'' → flake, A' 2) A' → A', (platform facet) 1) A' → A, hammerstone	Subassembly (Fig. 6c)
ST3'	Platform abrasion (Fig. 5)	Same as ST3 + T = {rub, shear}, NT = {platform abrasion}, MA = {objective flake, elaborated flake}	4) A'' → elaborated flake, A' 3) A' → (platform abrasion), A' 2) A' → A', (platform facet) 1) A' → A, hammerstone.	Interrupted (Fig. 6d)

Table 1. List of the main properties of the four stone technologies (STs) studied (first column). Their main knapping characteristic (2), grammar entities such as action terminals T, non-terminals NT and maximal action MA (3), grammatical rules with A, action terminal; A', intermediate action structure; A'', maximal action structure (4), and associated cognitive strategy (last column) are listed.

a



ST2

b

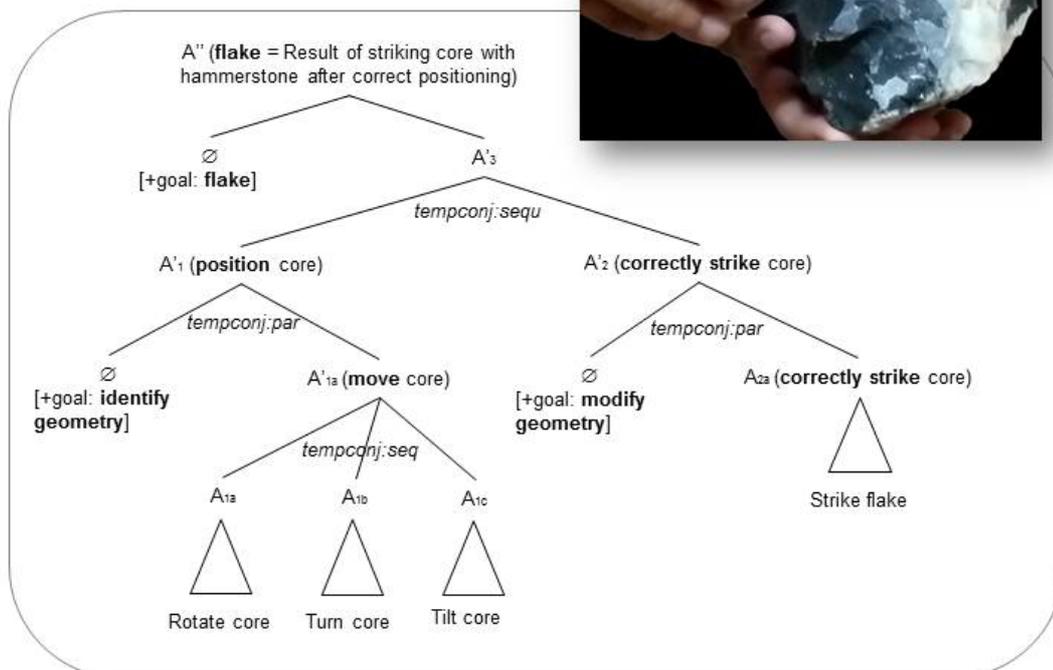


Figure 3. Action trees related to ST2 stone technology. Part of an action tree for 'rotate with handL core' (a), maximum action tree for a flake, i.e. 'strike core with hammerstone after correct positioning' (b), and illustration of the corresponding struck core (insert, the left hand handles the core while the right hand strikes it with a hammerstone pebble, photo: K. Akhilesh).



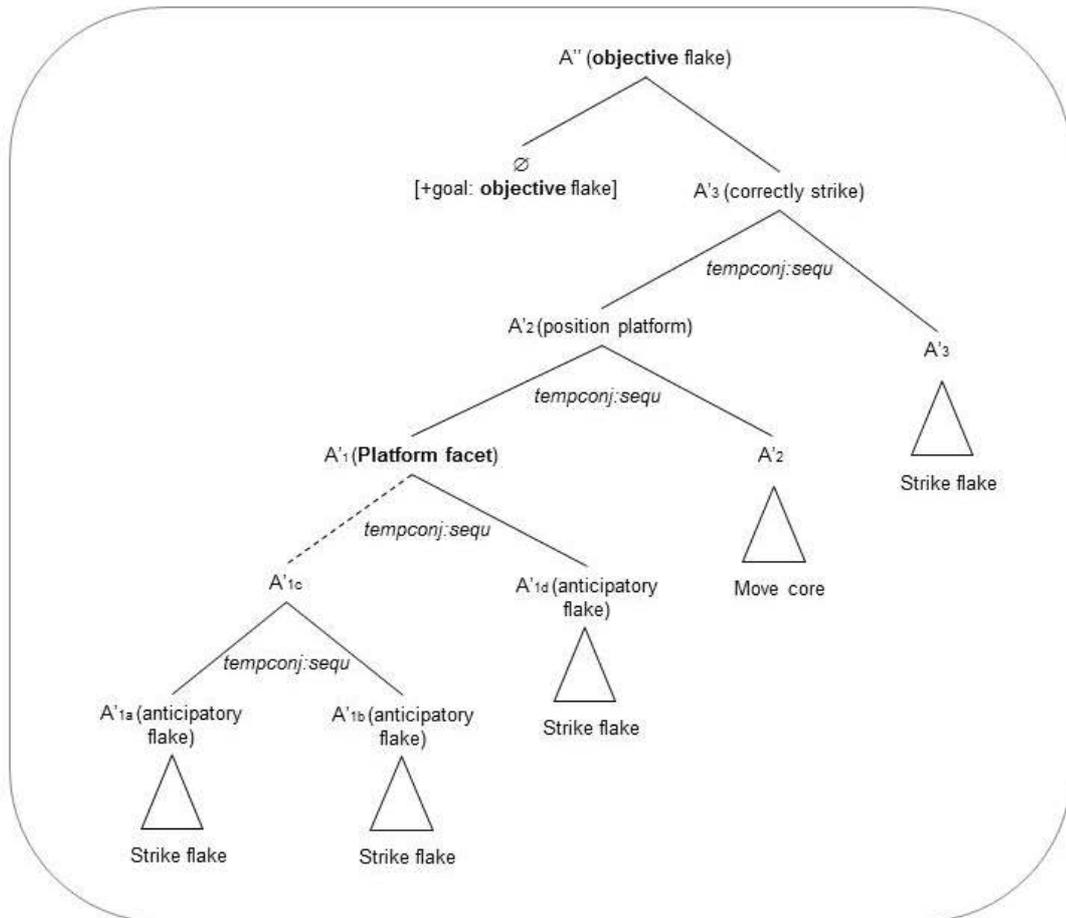
These actions can now be combined into a higher level action intending to ‘strike core with hammerstone after correct positioning’ (Fig. 3b). Our maximal action tree revisits the ‘basic flake unit’ described in detail by Moore, yet with slight changes in the process (Moore 2010). From our personal lithic knapping experience and additional discussions (J. Pelegrin, K. Akhilesh and M. Moore, pers. comm.), the identification of core geometry continues simultaneously with changing orientations. This leads to intermediate (not maximal) goals in the tree action, possibly with parallel temporal conjunctions (to be discussed). We also admit here that most modern knappers adjust core angles prior to striking the platform, not at the same time as the strike is delivered. This observation suggests considering the tilt action as a separate gesture in the sequential positioning of the core. The same logic and notation lead to the maximal tree action of a basic flake unit (Fig. 3b), and to the corresponding grammar vocabulary and production rules (Table 1). Here again, the three ST1 rules used do not need any modifier. This final action tree corresponds to an already complex flake including the concepts of geometrical identification and modifications (ST2). As noted above, the knapping strategies considered here have an angle of flaking lower than 90°.

4.3 ST3

The same tree action is used to describe the anticipatory flakes concerned in the faceting of the striking platform (Fig. 3b). A stage ST2, the final ST3 tree action is not yet available, as it requires combining the faceted platform, moving the core and finally striking the desired or objective flake (Moore 2010; Stout et al. 2014). These three successive sub-actions build the maximal tree for the objective flake (Fig. 4). The action terminals, action non-terminals and production rules of ST3 are the same as those of ST2, in addition to the platform facet related elements (Table 1). It is possible – and indeed this often occurs – to use some of the previous sub-actions separately, as well as to repeat this complex action several times with the same tool to shape the object (Moore 2010). Here probably comes the transition between making flakes (as in Oldowan technologies) and shaping a handaxe (as in Late Acheulean technologies). Yet, it is not necessary to accurately date this technology for providing a relevant faceting grammar. The action order and the exact action sequence has been shown as critical in longer and higher-order actions such as handaxe knapping (Mahaney 2014; Muller et al. 2017).

ST3

a



b



c



Figure 4. Maximum action trees related to ST3 stone technology (a) and its display (b, c). Maximum action tree for an 'objective flake' involving a platform facet (i.e. the action tree grows rightwards, a). The dashed connector highlights the fact that several other strikes may combine to create a faceted platform). Illustration of the corresponding platform preparation (b, the left hand handles the experimental core while the right hand strikes it with a hammerstone pebble,

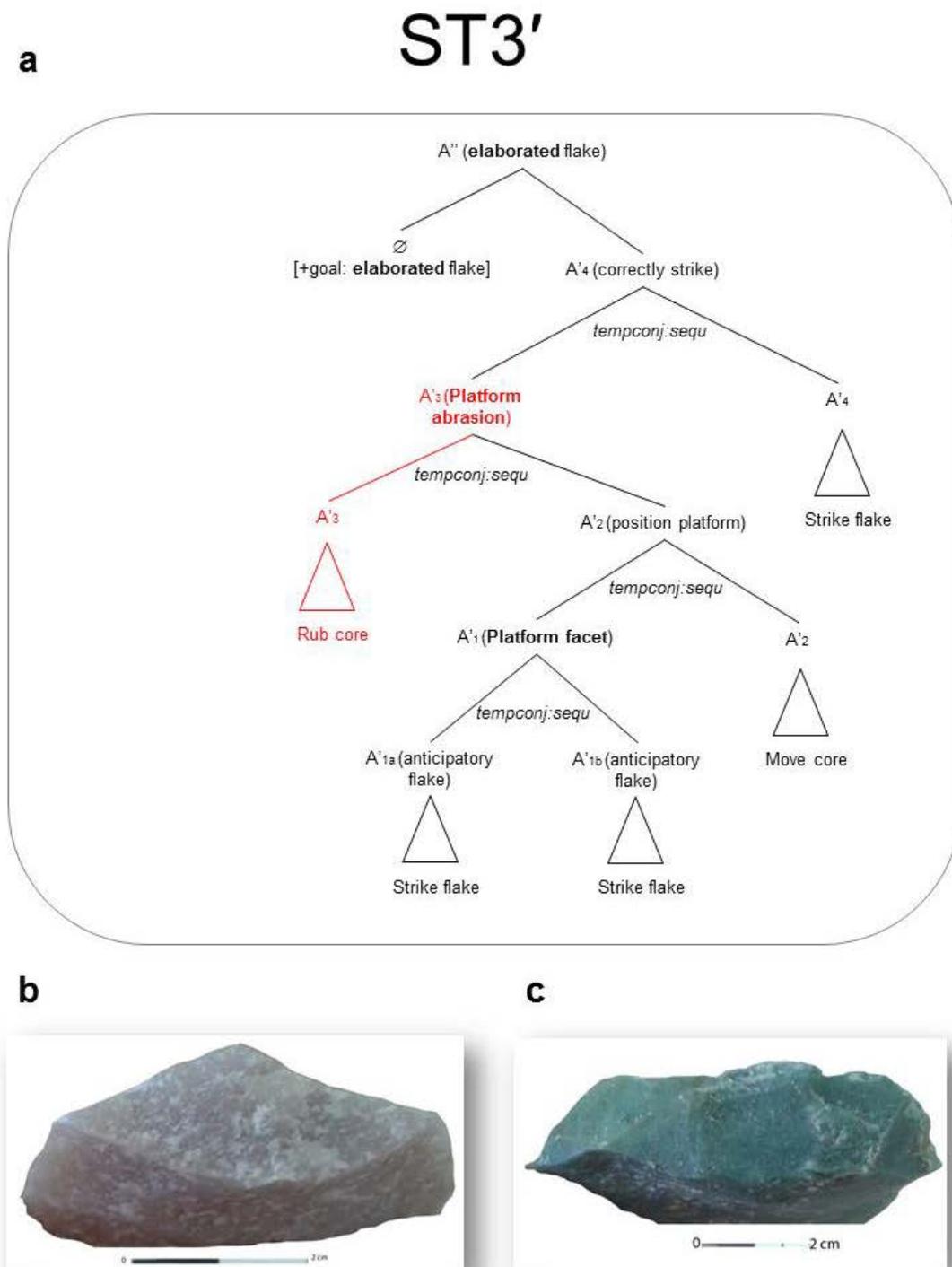


Figure 5. Maximum action trees related to ST3' stone technology (a) and displays (b, c). Maximum action tree for an 'elaborated flake' involving a platform abrasion (here a, the action tree may grow leftwards, in red). Illustrations of the corresponding platform preparations: images of a platform generated by abrasion (b) and, as a comparison, by faceting (c) using a hard stone hammer on an experimentally knapped quartzite flake. (Note that micro-abrasions may not be always visible at this magnification.)



With this ST1-ST3' grammar, it becomes easy to describe an observed or collected knapping sequence, as well as to produce a virtually new one as in Upper Palaeolithic and late Acheulean (Mahaney 2014; Stout et al. 2014). Again, it was not our intention here to accurately date ST3' technology, although it may be questioned how early it is. Indeed, it is not necessary to shape a whole handaxe to use the ST3' technology, as intermediate actions for making simpler product such as a single edge. This explains why we should postpone this schedule to a later date. For example, a possible sequence of MGA actions using the complex ST3' realization may be written as (to be read retrograde): [ST2b, flake → ST2b, flake → ST2a, tilt → ST3', abrade platform → ST2b, flake → ST3, strike platform → ST2b, flake → ST2a, tilt → ST2a, turn → ST2b, flake → ST1b, strike → ST2a, tilt → ST2a, turn → ST2a, rotate → ST1a, hammerstone → ST1a, core].

5. Discussion

5.1 A rigorous grammar for knapping actions

Here, we propose several Grammars of Action for describing and formalizing stone technologies (STs) observed during the Lower Palaeolithic. This work is based on recent results derived from deconstructing knapping sequences (Faisal et al. 2010; Greenfield 1991; Moore 2010; Pelegrin 1990), from our own experience of knappers, and from Grammars of Actions recently developed (Chomsky 1995; Juhola 1995; Pastra and Aloimonos 2012). The lithic technologies analysed here, be they for debitage and subsequently for façonnage, exhibit dominant characteristics: ST1—striking of a core with a hammerstone; ST2 – detaching the basic unit comprising the intended flake; ST3 – faceting of the platform in order to shape a tool; and ST3' – detachment of the flake following abrasion of the platform. These formalizations merely constitute a bare outline for one proposed Grammar of Action, keeping in mind the variability arising from raw materials, knapping skills and blank types selected. This study is in no way claiming to have developed the grammar of Lower Palaeolithic knapping. As a perspective, careful calibration and validation stages should be performed from empirical knapping and observed assemblages (Moore and Perston 2016; Tennie et al. 2017). However, the approach and these schemes can easily be modified depending on the assemblage being studied and the conceptual action hierarchy assumed (Mahaney 2014; Muller et al. 2017).

In terms of action terminals and non-terminals, i.e. primitive and intermediate actions respectively, the proposed grammars clearly demonstrate an increasing complexity. The transition between ST1 and ST2 was characterized by a change in sub-action types, although roughly with the same number of actions. Indeed, ST2 terminals were clearly based on ST1 non terminals: ST2 terminals were no more using concrete entities (hands, hammerstone), rather than primitive actions earlier formalized (grasp, enclose) in ST1. Further, this replacement of nth ST terminals by (n-1)th ST non terminals is confirmed. The transition to deliberate tool-making certainly occurs in the transition from ST1 to ST2, while tool-shaping certainly occurs from ST2 to ST3. In terms of production rules, most action grammars need similar rule types, namely tool complement, object complement, and goal oriented rules (STa = ST1 to ST3). The last technology (ST3') shows a profound difference with others, although the only difference relies on an additional rule, for allowing different sub-actions on the tool (ST3' rule n°3, Table 1). This observation has been made possible only due to the fine



analysis of Oldowan stone technologies and their associated primitive actions, a step circumvented by other models found in the literature (Mahaney 2014; Muller et al. 2017). This central observation comes only from the rigorous grammar developed here.

The cognitive strategies related to each stone technology are critical to inferring the cognitive abilities of the hominins who used them. To explain actions of human infants, primates and hominins, it has been proposed several strategies of increasing complexity: pairing (a single active object acts on a single static one to create a final structure), pot (multiple active objects act on a single static one), and subassembly (multiple active objects are combined to form a subassembly, which is in turn combined with a static object) strategies (Conway and Christianson 2001; Greenfield 1998; Moore 2010). In this regard, ST1 is a clear pairing strategy (a strike, Fig. 6a), while ST2 is pot strategy, as successive sub-actions are modifying the static core (e.g. some moves, Fig. 6b). ST3 is a subassembly strategy, as it requires the assemblage of several successive flakes, yet of the same nature than the last 'correctly struck' of the set (Fig. 6c and 5). These examples clearly demonstrate the need for syntax to interpret early knapping (Stout and Chaminade 2012; Stout et al. 2011; Wynn 1991).

5.2 Emergence of a more complex cognition

Interestingly, the action grammar proposition suggests that the procedures for platform abrasion do not require the same cognitive abilities as the previous and following (future) sub-actions. Indeed, it suggests an interruption in the procedures for the linear succession of flakes, in order to enable a different action to prepare the platform (Fig. 5, in red) prior to striking the next flake (Moore 2010; Stout et al. 2014). Conversely, platform faceting still requires similar procedures for striking flakes, thus not interrupting the nature of the action sequences. To abrade (grind or rub) a platform is a clear disruption of the edge shaping, sometimes requiring even to change the nature of the hammerstone/abrader being used. This interruption is clearly illustrated by the need of a left-located complement (Table 1, rule n°3, last line) in actions, and a potentially leftward developing action tree (Fig. 5, red action(s), or to be confused with the action geometry). For these serial actions, a specific and new strategy is required (Conway and Christianson 2001; Greenfield 1998), here termed 'interrupted' strategy (Fig. 6d, Table 1, last column). As soon as multiple active objects are combined, it is possible and necessary to differentiate the way they are combined. This interrupted strategy explicitly shows how successive pot or subassembly strategy chain-like of actions (Fig. 6b, c) may be disrupted by a radically new action (Fig. 6d, step 2 in red) to create the final structure. This is clearly what happens in any platform abrasion (Fig. 5, in red), and could never be produced with the previous actions/strategies.

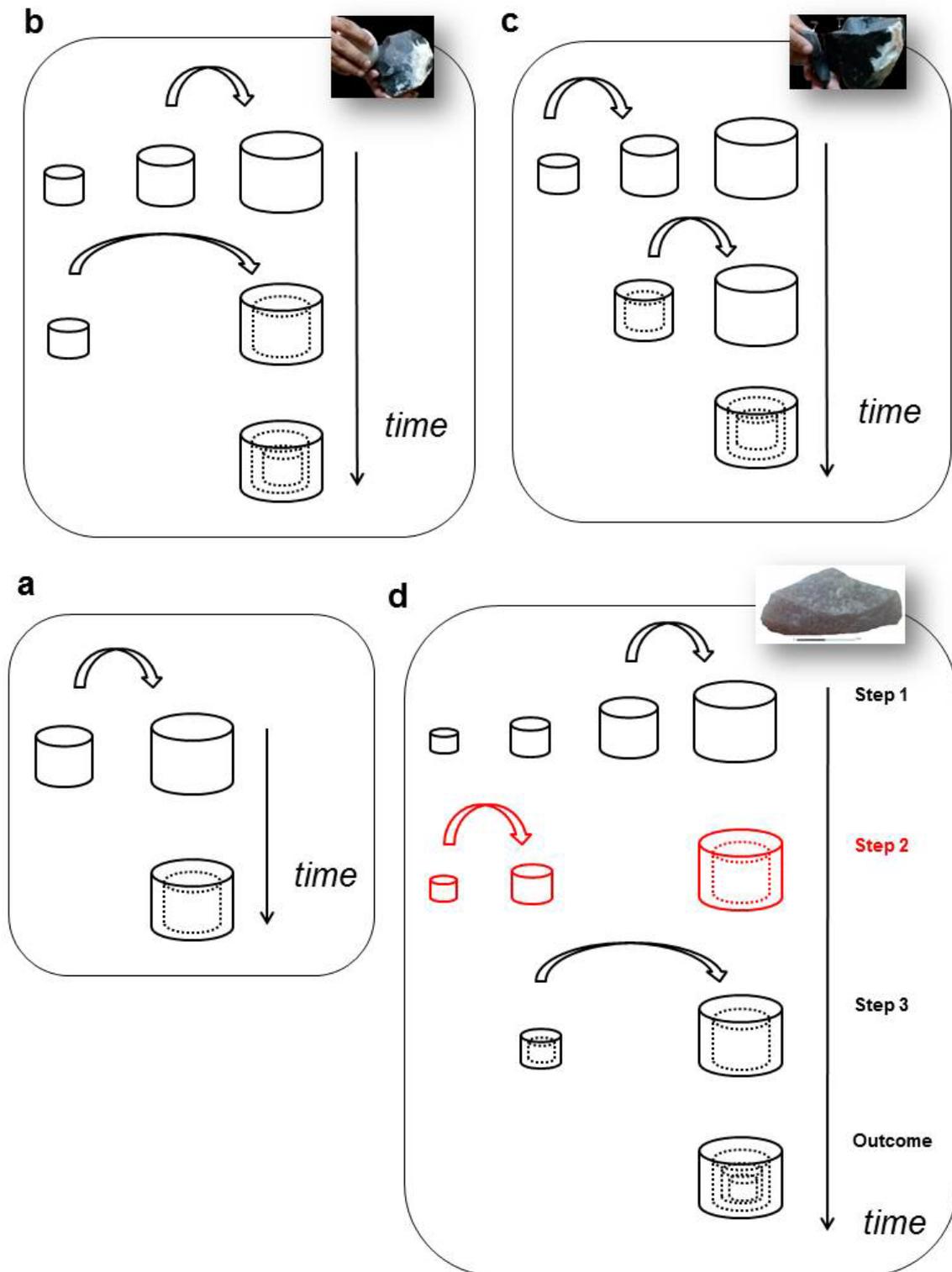


Figure 6. Cognitive strategies associated with a more or less complex set of actions (with their previous illustrations in inserts). The pairing (a), pot (b), subassembly (c) and interrupted (d) strategies are displayed with downward time in two to four steps, while arrows indicate pairwise associations (modified from (Conway and Christianson 2001; Moore 2010)). The second step of the most complex strategy (in red) highlights the specific action of platform abrasion discussed in the main text.



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Conflict of interest disclosure

The authors of this preprint declare that they have no financial conflict of interest with the content of this article.

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