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A framework for detecting stage-discharge hysteresis due to flow unsteadiness : application to France's national hydrometry network

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Abstract

1

A generic framework is proposed to evaluate the relative discharge error 2 made when ignoring stage-discharge hysteresis due to transient flow over large 3 gauging station networks. The diagnosis is conducted using the Jones equation, based on a simple hydraulic concept relating discharge to stage and its 5 time-gradient. The main input data used for the method are the flow re-6 sistance coefficients, the temporal stage gradients, and the bed slopes. The hysteresis effect is quantified for each gauging station and mapped using the 8 relative discharge error. The method was applied to 2618 gauging stations 9 of France's national hydrometry network using observational data extracted 10 from the national hydrological archive and from Digital Terrain Models. The 11 diagnostic results highly depend on slope estimates used as inputs. Substan-12 tial hysteresis effects were found at stations with low bed slope combined with 13 a fast flood regime. The France application shows the difficulty to provide a 14 firm conclusion about stations prone to hysteresis due to the slope data uncer-15 tainty. This issue is not specific to France; slope estimates at a country-level 16 is difficult to obtain in many countries. The use of local bed slope estimates 17 is recommended to approach the slopes of the reaches controlling the station 18 flow dynamics. 19

21 1 Introduction

Hysteresis in the stage-discharge relations (i.e. rating curves) of gauging stations 22 can be observed during flood events (Rantz, 1982; Muste et al., 2020). Figure 1 23 is an illustration of the effect of unsteady flows on different flow variables in time 24 and on the stage-discharge relationship compared to the case of uniform steady 25 flows. During the propagation of transient flows, the celerity of the pressure wave 26 (stage) is smaller than the celerity of the velocity wave, hence smaller than the 27 celerity of the discharge wave (Graf and Qu, 2004). In such case, for the same given 28 stage, the discharge during the rising limb is higher than during the falling limb 29 of the event, leading to a non-unique stage-discharge relation. Hysteresis creates a 30 loop in the rating curve, which is more or less wide depending on the geometrical 31 characteristics of the channel and on the type (intensity, gradient) of floods (Lee, 32 2013). Other phenomena can create looped rating curves, such as variable backwater 33 (i.e. changes in the downstream conditions), or variable roughness (Boyer, 1964; 34 Fenton and Keller, 2001; Mansanarez, 2016). In this study, the focus is on hysteresis 35 induced by unsteady flow only. 36

In practice, this hysteresis effect is often neglected, partly because it is not cap-37 tured by the occasional measurements of discharge and stage (a.k.a. gaugings). 38 Indeed, during flood events, gaugings are generally made after the flood peaks, for 39 practical and safety reasons. Thus, the loop induced by the hysteresis phenomenon 40 in the rating curve is often not observed. The evolution of the gauging techniques 41 toward non-intrusive and less dangerous methods, e.g. radar (Welber et al., 2016) 42 and image velocimetry (Dramais et al., 2011), will certainly help to overcome this 43 lack of information in the coming years. Substantial biases in flood prediction can 44 arise if hysteresis is ignored, such as underestimation of discharge during the ris-45 ing limb of the flood, including the peak discharge, time lag in the overall flood 46 hydrograph and larger uncertainty of the discharge estimations due to the scatter 47

of gauging data around the rating curve (Holmes, 2016; Mansanarez, 2016; Muste
et al., 2020).

Numerous methods exist to adjust the rating curves when unsteadiness is signifi-50 cant (cf. Lee, 2013; Dottori et al., 2009, for method reviews). They are usually based 51 on a correction of the standard discharge, estimated with a unique rating curve valid 52 for steady flow conditions, to account for hysteresis and compute the real discharge. 53 Jones (1915) method is the most used by the hydrometric community. It assumes 54 that the flood wave propagates without any attenuation. Based on this kinetic wave 55 approximation, the discharge in unsteady flows can be deduced from the stage and 56 its time-gradient. More general expressions accounting for inertial forces have been 57 proposed and used by Fread (1975); Fenton and Keller (2001); Perumal et al. (2004); 58 Petersen-Overleir (2006); Wolfs and Willems (2014); Mansanarez (2016); Lee and 59 Muste (2017); Muste et al. (2020) for example. 60

It is important to know where and when hysteresis can occur and how large it is to 61 better evaluate the flood hazard (Lee, 2013; Muste et al., 2020). The main objective 62 of this paper is to propose a diagnostic approach to quantify the risk of hysteresis 63 over a large set of hydrometric stations, typically over an entire national network. 64 The gauging stations prone to hysteresis are identified from the relative discharge 65 error ϵ potentially made when ignoring the hysteresis effect. The parameter ϵ is 66 defined as the relative bias between discharge estimates accounting (Q) or not (Q_0) 67 for flow unsteadiness (Figure 1). It informs about the exposure of gauging stations 68 to hysteresis effect during specific events. The parameter ϵ is similar to the PDIFF 69 parameter introduced by Holmes (2016), which refers to the percent difference of the 70 measured discharge from the discharge estimated using the unique standard rating 71 curve. However, ϵ seems more suitable for massive diagnosis since it is based solely 72 on discharge models and does not depend on available discharge measurements. 73 The diagnosis is intended to massive and large-scale deployment and to overview 74 the areas influenced by hysteresis, before proceeding to a more accurate station-by-75 station analysis using available gaugings. 76



Figure 1: Discharge error due to flow unsteadiness hysteresis: temporal time series (U : average velocity, Q : discharge, h : stage), rating curves (dashed line for steady uniform flow regime and solid line for unsteady flow regime) and the relative discharge error ϵ comparing the two discharges of the two different regimes (Q: unsteady discharge, Q_0 : steady discharge).

The rest of the paper is organized as follows. First, the rating curve model for 77 unsteady flows used in the diagnosis procedure is detailed in Section 2. Simple rating 78 curve models such as the well-accepted Jones (1915) equation are preferred for the 79 diagnosis because it requires limited information that is available on large datasets 80 and easily measurable on the field. The presented method is intended to be used 81 for hydrometric purposes. Other more complex equations mentioned above require 82 too much additional information and as shown by Mansanarez (2016), they do not 83 significantly improved nor reduced the uncertainty related to the estimation of the 84 discharge during unsteady flows compared to Jones (1915) equation. Then, the 85 generic framework is described in Section 3 along with the required input data and 86 the criteria retained for quantifying the hysteresis effect. The diagnosis is eventually 87 applied to the gauging stations of the French national hydrometry network (Section 88 4). The limit of the method is pointed out using a sensitivity analysis of input data 89 of the hysteresis model. 90

⁹¹ 2 Theory

⁹² 2.1 Rating curve model for steady uniform flow

⁹³ Hysteresis due to transient flows is known to be observed during intense floods.
⁹⁴ In those conditions, it is usually relevant to approximate the hydraulic controls at

gauging stations by a single channel control. The diagnosis is therefore performed
with this assumption.

The Manning-Strickler equation is generally used for stage-discharge models of gauging stations with channel controls, for which the flow is mainly controlled by friction (Rantz, 1982; World Meteorological Organization, 2010; Le Coz et al., 2014) :

$$Q_0 \approx KAR_h^{2/3}\sqrt{S_0} \tag{1}$$

with Q_0 [m³/s] the discharge in uniform steady flow, K [m^{1/3}.s⁻¹] the Strickler flow resistance coefficient, A [m²] the wetted area, R_h [m] the hydraulic radius and S_0 [-] the channel slope. A unique relation between stage and discharge is thus obtained. Equation 1 is valid only for uniform steady flow; although it is often used for nonuniform unsteady flows in the hydraulic community.

¹⁰⁶ 2.2 Rating curve model for unsteady flow - Jones equation

Equation 1 is based on the assumption that the energy slope S_f can be approximated by the channel slope S_0 . It is not applicable in case of unsteady flow. Indeed, the water free-surface varies continuously during the flood wave propagation and the longitudinal water profile is not parallel to the river bed profile. Therefore, a correction of the steady-flow rating curve is required to capture the hysteresis effect. The energy slope S_f can be expressed through the one-dimensional momentum equation of Saint-Venant, which describes the full dynamics of a flood wave propagation :

$$S_f = S_0 - \frac{\partial h}{\partial x} - \frac{1}{g} \left(\frac{\partial U}{\partial t} + U \frac{\partial U}{\partial x} \right)$$
(2)

with $g \text{ [m.s}^{-2]}$ the gravitational acceleration, $U \text{ [m.s}^{-1]}$ the cross-sectional average water velocity, t [s] the time, x [m] the streamwise distance and h [m] the water surface elevation (a.k.a. the stage). The relative importance of the terms detailing the full dynamics of the flood wave propagation (Equation 2) determines the type of wave occurring at specific sites and particular events (Muste et al., 2020). For example, neglecting the inertia terms compared to the pressure term and gravity force leads to the so-called diffusion wave (Equation 3):

$$S_f \approx S_0 - \frac{\partial h}{\partial x}$$
 (diffusion wave assumption) (3)

¹²¹ The diffusion wave assumption is generally accepted for low-gradient channels.

¹²² Combining Equation 1 and Equation 3, the stage-discharge model for unsteady ¹²³ flow becomes:

$$Q = Q_0 \sqrt{1 - \frac{1}{S_0} \frac{\partial h}{\partial x}} \tag{4}$$

The discharge is therefore expressed as a steady-flow reference discharge Q_0 multiplied by a corrective term accounting for flow unsteadiness.

The Jones (1915) approximation avoids estimating the longitudinal gradient term $\partial h/\partial x$, which is rarely measured at gauging stations, except in the case of twin gauge stations (Petersen-Øverleir and Reitan, 2009; Mansanarez, 2016). As a substitute, the temporal variation of stage $\partial h/\partial t$ is used, which is always available from stage records. The Jones approximation is based on the kinematic wave assumption, which assumes that the wave propagates with no attenuation along the channel. The flood wave celerity c can therefore be expressed as :

$$c = \frac{\partial x}{\partial t} = \frac{\partial Q}{\partial A} \tag{5}$$

Assuming a prismatic channel and vertical river banks over the range of stage variation, the flood wave celerity becomes:

$$c \approx \frac{1}{B} \frac{\partial Q_0}{\partial h} \tag{6}$$

135 where B [m] is the channel width.

¹³⁶ The continuity equation of Saint Venant for quasi-steady flows can be rear-

ranged to show the relationship between the longitudinal and temporal gradients
(see Mansanarez (2016) for details):

$$\frac{\partial h}{\partial x} = -\frac{1}{c} \frac{\partial h}{\partial t} \tag{7}$$

With such approximation, the rating curve model can be expressed as follows, where S_f is expressed from the bed slope, the flood wave celerity and the stage time-gradient:

$$Q = Q_0 \sqrt{1 + \frac{1}{cS_0} \frac{\partial h}{\partial t}} \tag{8}$$

¹⁴² Equation 8 is referred to as the Jones equation in the following.

In the rest of the paper, the channels at gauging stations are approximated by wide and rectangular channels with equivalent conveyance in order to perform the hysteresis diagnosis at large-scale with a minimum of information on the channel geometry. This assumption is acceptable in conditions of floods inducing hysteresis (Le Coz et al., 2014). Then, the hydraulic radius can be approximated by the flow depth : $R_h \approx (h - b)$, where b is the offset of the channel control. Equation 8 becomes:

$$Q = KB(h-b)^{5/3}\sqrt{S_0}\sqrt{1 + \frac{1}{\frac{5}{3}K(h-b)^{2/3}S_0^{3/2}}\frac{\partial h}{\partial t}}$$
(9)

¹⁵⁰ 2.3 Quantification of the hysteresis effect

The hysteresis effect is quantified based on the relative discharge error ϵ between the discharge calculated considering the flow as unsteady (Q) and the discharge calculated assuming a steady flow regime (Q_0) . Combining Equations 1 and 9, ϵ is expressed as follows :

$$\epsilon = \frac{Q - Q_0}{Q_0} = \sqrt{1 + \frac{1}{\frac{5}{3}K(h-b)^{2/3}S_0^{3/2}}\frac{\partial h}{\partial t}} - 1$$
(10)

Analysing Equation 10, the main requirements for detecting stations with hys-

teresis due to flow unsteadiness are : 1) low S_0 , 2) high stage temporal gradients $\partial h/\partial t$ (i.e. stations subject to intense and rapid floods), and 3) rough beds inducing high flow resistances (i.e. low K).

Assuming that $\epsilon \ll 1$ and after a first-order Taylor expansion, Equation 10 can be rearranged as follows :

$$\epsilon \approx 0.3K^{-1}(h-b)^{-2/3}S_0^{-3/2}\frac{\partial h}{\partial t}$$
(11)

To investigate the relative importance of the different factors of Equation 11 in this hysteresis phenomena, i.e. K, S_0 , (h - b) and $\partial h/\partial t$, the relative uncertainty of ϵ is assessed applying the uncertainty propagation law of JCGM (2008) (Joint Committee for Guides in Metrology) to Equation 11 and assuming independent measurement errors :

$$u_{\epsilon}^{\prime 2} = u_{K}^{\prime 2} + \frac{4}{9}u_{(h-b)}^{\prime 2} + \frac{9}{4}u_{S_{0}}^{\prime 2} + u_{\partial h/\partial t}^{\prime 2}$$
(12)

where $u'_X = u_X/X$ is the relative standard uncertainty of the variable X. The sensitivity coefficients in Equation 12 inform about the relative importance of each factor for the hysteresis effect quantification. The bed slope is the most sensitive parameter, with a sensitivity coefficient of 9/4. To a lesser extent, K and $\partial h/\partial t$ are also important; they have a sensitivy coefficient equal to 1. Equation 12 indicates that (h - b) is the less sensitive factor, with a sensitivity coefficient of 4/9.

¹⁷² 3 The diagnostic approach

¹⁷³ 3.1 Required data

The diagnosis consists in applying Equation 10 to each hydrometric station, which requires estimates of the flow resistance coefficient K, the bed slope S_0 , the bed elevation b, the stage time series and the time-gradient $\partial h/\partial t$. Figure 2 illustrates the different steps to follow to collect the needed data for each gauging station. The ¹⁷⁸ diagnosis can be easily re-applied as more input data are available.



Figure 2: The framework for diagnosing gauging stations influenced by hysteresis effect due to flow unsteadiness.

The flow resistance coefficient K (or the Manning's coefficient n = 1/K) is 179 generally not documented in national databases. It might be possible to retrieve this 180 information for specific stations from local hydrological services but this is rarely 181 available. As indicated in Figure 2, if not available, defaults values for K need to 182 be assumed. The analysis of Equation 11 showed that discharge error is inversely 183 proportional to K. It is therefore more likely to observe hysteresis at stations with 184 low K values, i.e. rough beds. If no estimate of K is available, we set K = 25 as a 185 conservative but realistic default value. A flow resistance coefficient of 25 represents 186 rough gravel-beds, or beds with bedforms or presence of vegetation (Coon, 1998). 187

An accurate measure or evaluation of the bed slope S_0 is crucial for a good performance of the method (see Equation 12). It may be available at some gauging stations from hydraulic studies or specific topographic surveys. But over a national ¹⁹¹ network, we need to use S_0 estimates from external datasets, e.g. based on Digital ¹⁹² Terrain Models (DTM).

The time-gradient $\partial h/\partial t$ is estimated based on the stage time series h(t) that are 193 automatically and continuously recorded at gauging stations (cf. Figure 2). Those 194 records are then registered in large databases and converted into discharge time 195 series Q(t) using rating curves established from discharge measurements (gaugings) 196 at the stations. The higher gradients $\partial h/\partial t$ are assumed to be found during the most 197 intense floods. The method scans the data to estimate the largest five time-gradients 198 $\partial h/\partial t$ for each specific station. First, the largest five flood peaks are detected from 199 the discharge time series Q(t) for each station over the entire period of available 200 data. Samples of stage time series h(t) are extracted around those extreme events. 201 Data starting 10 days before the flood peak to 20 days after are kept. This duration 202 was defined assuming it was sufficient to capture the flood dynamics at all stations. 203 The resulting stage data are smoothed using a spline function to remove noise and 204 keep only the stage variations reflecting the flood propagation. When the amount 205 of missing data within the recorded stage time series is too large, it is excluded from 206 the diagnosis. The gradient $\partial h/\partial t$ time series are then calculated from the smoothed 207 h(t) and the five maximum values of the gradient over the five events are kept for 208 computing ϵ . 209

It is difficult to set the offset b of the channel control, mostly because it can evolve due to erosion/deposition, and in particular after floods inducing large sediment transport. As a consequence, b is seldom recorded in databases. If not available, we suggest setting $b = h_{min}$ in the framework, where h_{min} corresponds to the lowest stage value of the stage time series of the studied event. Indeed, the cease-to-flow level b of the channel should not be higher than the lowest stage recorded.

²¹⁶ 3.2 Mapping hysteresis effect

Once the parameters K, b, h, S_0 and $\partial h/\partial t$ are identified (see Section 3.1), the discharge error can be computed using Equation 10. The procedure gives five estimates

of ϵ for each stations, because the greatest five flood events are analysed (Figure 2). 219 The hysteresis effect is qualitatively assessed based on the resulting ϵ that we 220 choose to present and map in two ways. Firstly, the focus is made on the most 221 critical event per stations inducing the higher relative error ϵ_{max} . The maximal 222 discharge errors ϵ_{max} are mapped by classes to facilitate the qualitative assessment. 223 Four classes are chosen according to usual criteria in hydrometry accounting for the 224 uncertainties of the rating curves and gaugings : 1) negligible deviation between Q 225 and Q_0 (i.e. $\epsilon_{max} \leq 1\%$), 2) low deviation (i.e. $1\% < \epsilon_{max} \leq 5\%$), 3) intermediate 226 deviation (i.e. 5% < $\epsilon_{max} \leq 10\%$), and 4) high deviation (i.e. $\epsilon_{max} > 10\%$), i.e. 227 larger than typical gauging uncertainties, which are generally evaluated to range 7-228 10% depending on the measurement technique. Secondly, the hysteresis effect can be 229 assessed for each station by the number n_{ϵ} representing the number of floods over the 230 selected five for which the discharge error is larger than an arbitrary threshold, set 231 as 10% in our application. The indicator n_{ϵ} is divided into three classes to facilitate 232 the hysteresis assessment using the map: 0 - station not prone to hysteresis, 1 -233 station with low exposure to this effect, from 2 to 5 - station prone to hysteresis 234 effect. 235

The first map produces a general diagnosis and enables to detect all the potentially affected stations. The second map is complementary and gives a refined diagnosis showing the stations that are frequently affected by hysteresis. Those maps can be used as a guide for hydrological services to identify the affected stations and to better manage their stations. The thresholds for the assessment of hysteresis influence can be reviewed to match the requirements of each hydrological service.

²⁴² 4 Application to France's national hydrometry net ²⁴³ work

²⁴⁴ 4.1 Presentation of the data

The framework is applied to France's national hydrometry network. A number of 245 2618 gauging stations are analysed, which corresponds to stations with discharge 246 rating (not stage only), including closed or discontinued stations. The stage and 247 discharge times series required for the method to work come from the national 248 hydrological archive (HYDRO2 database). Estimates for K, b, and S_0 are not 249 available in HYDRO2 database. The flow resistance coefficient was assumed equal 250 to 25 for all the stations as a conservative assumption. Approximates of channel bed 251 slopes are deduced from three datasets using different DTMs for slope extraction 252 with different resolutions and spatial coverages (Figure 3): 253

1. the Global River Slope dataset, GloRS (Figure 3a), which is a worldwide 254 geospatial dataset detailed in Cohen et al. (2018), where the slope is simply cal-255 culated from the elevation depression over the length of a river reach. The slope 256 extraction is made based on the 15arc-sec resolution ($\sim 460 \times 460$ m) SHuttle 257 Elevation Derivatives at multiple Scales (HydroSHEDS) DTM and stream-258 network (see http://hydrosheds.cr.usgs.gov/index.php). The reaches 259 are defined according to the confluence points and to an additional feature-260 splitting procedure, which splits the river segments that are longer than a 261 user-defined distance. A 50-km splitting interval was selected in Cohen et al. 262 (2018), as it exhibits the best correlations to their validation dataset. The 263 reach lengths vary from 156 m to 50 km with a mean length of ~ 17 km in the 264 world dataset. The smallest reach slope detected is 5.3×10^{-5} ; smaller slopes 265 are set to 0. In France, a specific correspondence is made between the reach 266 and the location of the gauging station on the basis of the closest distance 267 between both objects. The station slope is then set equal to the slope of the 268 associated reach. If the distance exceeds 200 m between station and reach, the 269

270

station is excluded. In France, the smallest slope is 2.5×10^{-4} .

2. the theoretical hydrographical network (RHT) (Pella et al., 2012) (Figure 3b), 271 which is a joined and oriented digital river network (see https://ecoflows 272 .inrae.fr/software/). It is derived from the BD Alti[®] 50 m digital eleva-273 tion model of the French Geographic National Institute (IGN) and from the 274 extended hydrological network (RHE) (Pella et al., 2008) corresponding to an 275 oriented simplification of the referential hydrographical network of the IGN, 276 BD Carthage[®]. The final RHT represents a network of 283 639 km with a 277 total of 114 601 reaches associated with different topographic, climatic and 278 hydrologic attributes. Various environmental attributes are available and pre-279 sented in Pella et al. (2012), such as slope estimates, catchment areas, mean 280 discharge, reach width and length for example. The slope is calculated as the 281 difference in elevation between the upstream and downstream ends of the reach 282 divided by the reach length. The lowest reach slope detected in the RHT is 283 equal to 10^{-4} ; smaller slopes are set to 0. The average reach length is 2.5 km 284 and varies from a few meters to more than 40 km. The reach-station associa-285 tion is made by geographical proximity. On average, the distance between the 286 two objects does not exceed 36 m. 287

3. the slopes from the hydrological distributed model J2000-Rhône (Branger 288 et al., 2018) (Figure 3c), covering the Rhône River basin (97 800 km²), lo-289 cated Southeast of France. The tool called HRU-delin (Hydrological Response 290 Unit - delineation) combined with a DTM is used to prepare the mesh and 291 generate several inputs for the hydrological modeling, including the creation of 292 river reaches and calculation of their slopes (see https://forge.irstea.fr/ 293 projects/hru-delin). The slope dataset results from the SRTM (Shuttle 294 Radar Topographic Mission) digital elevation data, with a resolution of 90 295 m. The reach lengths are defined by the confluences and the locations of the 296 gauging stations, hence a wide range of lengths, from 90 m to more than 44 297 km with a mean length of ~ 6 km. The slopes are extracted for each reach by 298

computing the difference in altitude between the upstream and downstream 299 pixel of the reach. The minimum slope detected in the dataset is equal to 300 8.3×10^{-5} ; smaller slopes are set to 0. A specific correspondence is made be-301 tween the reach and the location of the gauging station to obtain the S_0 value 302 at the station. The stations are first relocated on the stream network by prox-303 imity and similarity of drainage area. The reaches are then cut at the station 304 position on the stream, so that the end of the reach corresponds to the station 305 location. 306



Figure 3: River slope estimates in France from different datasets : a) GloRS, b) RHT and c) J2000-Rhône.



Figure 4: Comparison of bed slope estimates obtained after extractions from different datasets for 99 gauging stations located in the Rhône basin: a) bed slopes from GloRS versus from RHT, and b) bed slopes from J2000-Rhône versus from RHT.

The GloRS provides slope estimates only for the main rivers, whereas the two other datasets also include S_0 estimates for small rivers and headwater catchments. The values of S_0 differ according to the chosen dataset, but the same general trend is observed, i.e. high and low slopes are detected approximately in the same areas (Figure 3). The slope estimates can vary for more than one magnitude order (Figure 4). Slopes from RHT and J2000 are in closer agreement than slopes from GloRS, which might be explained by differences in the DTM resolution.

314 4.2 Results over France

The diagnostic maps for France's national hydrometry network differ according to 315 the chosen source of S_0 estimates (Figure 5). Slope estimates were available for the 316 2618 gauging stations using the RHT dataset whereas the GloRS and J2000-Rhône 317 datasets provide slope estimates for only 1053 and 298 gauging stations, respec-318 tively. The smallest French rivers are not represented in GloRS dataset, leaving 319 some gauging stations without a slope estimation during the reach-station match-320 ing. The diagnostic maps based on the RHT and J2000-Rhône slope estimates reflect 321 what was initially expected : a greater risk of hysteresis near estuaries (e.g. estuary 322 of the Rhône River) and on large rivers with low-gradient slopes (e.g. Saône River); 323 see Figure 5d. In addition, stations located in mountains (e.g. Alps) are identified 324 as not prone to hysteresis effect. 325

According to the diagnosis, 186 out of 2618 stations (i.e. 7.1%) are prone to 326 substantial hysteresis effect ($\epsilon > 10\%$) based on S_0 estimates from the RHT (Figure 327 6a), whereas only 29 stations out of 1053 (i.e. 2.8%) are prone to hysteresis based on 328 S_0 estimates from the GloRS (Figure 6b). Even if the diagnostic results are different, 329 we can safely say that the hysteresis effect is low in France. Note that some low-330 gradient stations prone to hysteresis might have been missed because their slopes 331 were lower than the threshold value imposed by the used datasets. In addition, 332 further investigation is required to conclude if the detected stations are really prone 333 to hysteresis, such as a specific analysis of gaugings and rating curves at individual 334 stations. 335

³³⁶ 4.3 Profiles of stations prone to hysteresis

The framework results can be used to determine the typical profile of stations prone to hysteresis. Figure 7 presents the needed geometrical and hydraulic conditions (i.e. S_0 and $\partial h/\partial t$) to observe hysteresis at a station. As expected, low bed slope combined with high temporal stage variation are the critical conditions. This is in accordance with the uncertainty analysis made for Equation 10. As shown in



Figure 5: Diagnostic maps of hysteresis influence on 2618, 1053 or 298 gauging stations in France, using a) RHT, b) GloRS or c) J2000-Rhône dataset as input data for river bed slope, respectively. d) Overview of the main rivers and mountains in France.



Figure 6: Relationship between classes of relative errors due to hysteresis effect ϵ and bed slopes S_0 deduced from a) the RHT and b) from the GloRS datasets. The red numbers indicate the number of stations within the class and the percentage with respect to the total number of stations, respectively.

Figures 6 and 7, stations with high relative discharge errors ($\epsilon > 10\%$) have low bed 342 slopes varying mainly from 10^{-4} to 10^{-3} and high time stage gradient ranging from 343 4×10^{-6} to 10^{-3} m/s. Those values are in accordance with typical values reported in 344 the literature and listed by Muste et al. (2020). Hysteresis is generally considered 345 negligible when $S_0 > 10^{-3}$ and $0 < dh/dt < 3.3 \times 10^{-4} \text{m/s}$ and becomes clearly 346 significant when $S_0 < 10^{-4}$ and $dh/dt > 4.2 \times 10^{-6}$ m/s (Fread, 1975; Muste et al., 347 2020), as observed in Figure 7. Unfortunately, we have limited estimates of S_0 348 smaller than the lower slope threshold of 10^{-4} . 349



Figure 7: Stage temporal variation $\partial h/\partial t$ versus bed slope estimates S_0 deduced from a) GloRS, b) RHT and c) J2000-Rhône datasets for the different gauging stations and associated assessment for hysteresis effect ϵ .

³⁵⁰ 4.4 Sensitivity to slope data

Testing diverse sources of bed slope data enables to evaluate the sensitivity of the 351 diagnosis to those input data. The application over the Rhône basin using the 352 J2000-Rhône data stresses the importance of using such accurate estimates of bed 353 river slopes. Figure 8 shows the three diagnostic maps for the 99 stations shared by 354 the three datasets in the Rhône basin. If the GloRS slope dataset is used as input, 355 no stations are detected as prone to hysteresis; the relative discharge error ϵ being 356 always lower than $\sim 8\%$ (see Figure 9a). Conclusions are significantly different if 357 RHT or J2000-Rhône slope datasets are used. Only 6 and 7 stations are affected 358

by hysteresis according to the diagnosis made with S_0 estimates from RHT and J2000-Rhône datasets, respectively. Two of these stations are common to the two datasets.



Figure 8: Diagnostic maps of hysteresis influence on the 99 gauging stations located in the Rhône basin, France, using slopes estimated from different DTM: GloRS, RHT and J2000-Rhône.

The resulting discharge errors highly depend on the S_0 estimates used for their 362 computation. The discharge errors calculated using the GloRS slope dataset are 363 mostly underestimated compared to those calculated using the RHT slope dataset 364 (see regression line in Figure 9a). There is no obvious bias between ϵ deduced from 365 RHT and J2000-Rhône slope datasets. A large scatter of ϵ values is nevertheless ob-366 served in Figure 9b. The high values of ϵ are realistic, in particular those calculated 367 using J2000-Rhône slope estimates; in that case ϵ does not exceed 48% (Figure 9b). 368 Only one station out of the 99 stations in the Rhône basin has a discharge error 369 that exceeds 100% (ϵ =445% according to the diagnosis made with the RHT slope 370 dataset). For clarity, this point is not presented in Figure 9. This station is also 371 identified as prone to hysteresis by the diagnosis deduced from the J2000-Rhône 372 slope dataset ($\epsilon \approx 15\%$). The out of range value is probably the consequence of a 373 wrong S_0 estimate. Indeed, S_0 differs by more than one order of magnitude com-374

³⁷⁵ pared to S_0 from J2000-Rhône and GloRS datasets. In addition, the consistency ³⁷⁶ of the other input data such as the time stage gradient was verified. Regarding ³⁷⁷ the entire France network, there is only 15 out of 2618 stations (less than 0.6%) ³⁷⁸ with a discharge error higher than 100% and all of these ϵ result from an estimation ³⁷⁹ based on RHT slope dataset. This is encouraging with regard to the use of such a ³⁸⁰ diagnostic approach.



Figure 9: Comparison of discharge errors ϵ calculated using the slope estimates from different datasets for 99 gauging stations located in the Rhône basin: a) using GloRS versus RHT, and b) using J2000-Rhône versus RHT. Marginal boxplots detail the distribution of the data. Red solid and dotted lines represent the perfect agreement and the threshold of $\epsilon = 10\%$, respectively. Blue line refers to a linear regression line with its grey envelop corresponding to the confidence interval.

³⁸¹ 4.5 Limit of the diagnostic approach

The main limit of the proposed framework is therefore related to the difficulty to es-382 timate the bed slope massively and accurately. Slope calculation is scale-dependent 383 and is thus sensitive to the spatial resolution of the DTM as well as the reach length. 384 The key to have a good diagnostic performance is to use local estimation of bed slope. 385 In the best case scenario, the slope should be evaluated over the length where the 386 channel characteristics control the stage-discharge relation, but such a length is hard 387 to identify and especially is site-specific. Such diagnosis is thus challenging, because 388 we need to perform a diagnosis at large-scale (e.g. over country) of individual local 389 objects (stations). No dataset at the local scale for the slope estimates exists, so 390

we extract them from large-scale datasets that were not developed for local studies. 391 The splitting procedure for the reaches in the datasets is most often not suitable 392 for our purpose, though accurate for hydrological studies. The reach length is often 393 too long to capture the accurate value of the bed slope at the station. For exam-394 ple, the average reach length associated to the 1053 stations in the GloRS dataset 395 is 27 km, whereas it is equal to 4 km and 6.1 km, for the 2618 and 298 stations 396 in the RHT and J2000-Rhône datasets, respectively. Using such input data in the 397 framework gives nonetheless a good overview of the global dynamics around the 398 station in conditions of intense floods. In our framework, we mix data from different 399 scales: averaged bed slopes over variable-length reach and local information at the 400 station such as, the stage time series and geometrical characteristics. If there is any 401 doubt about the value of ϵ at a specific station, we recommend measuring directly 402 and locally the river bed slope around the station. The discharge error can then be 403 re-calculated with good S_0 estimate. If the station is detected as prone to hysteresis 404 effect, an adjusted stage-discharge relation should be used for discharge prediction 405 rather than the standard rating curve, such as for example Equation 8, or variant 406 models as those reported in Petersen-Overleir (2006); Mansanarez (2016). 407

408 5 Conclusion

A diagnostic method is proposed to detect the gauging stations prone to hystere-409 sis due to flow unsteadiness over a given hydrometry network. It uses well-known 410 hydraulic concepts related to unsteady flows, such as the Jones equation, and sim-411 ple data, i.e. easily measurable or estimable parameters on the field, such as those 412 generally present in national hydrological databases. The final output is a map as-413 sessing the hysteresis effect at all the stations from the studied area through the 414 relative discharge error between the discharge calculated with the steady flow rating 415 curve and the actual discharge. The application of the method to France's national 416 hydrometry network highlights the importance of using reliable bed slope estimates 417 to produce a robust diagnosis. The major limit of the method is to have access 418

to accurate local bed slopes. The diagnostic maps obtained using three different 419 inputs of bed slope estimates show that in France the hysteresis effect due to flow 420 unsteadiness is low for the majority of the gauging stations; 7.1% of the 2618 gaug-421 ing stations are potentially affected by hysteresis according to the diagnosis made 422 with the slope estimates from RHT dataset. However, the diagnostic results differ 423 depending on the source (and accuracy) of the slope estimates. In the future, partic-424 ular attention should be paid to measuring accurately the river bed slopes near the 425 gauging stations and therefore refining the rating curves in case of unsteady flows 426 with specific gauging campaigns. 427

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436 Competing interests

⁴³⁷ The authors declare that they have no competing interests.

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