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Physiological variable predictions using VIS–NIR spectroscopy for water stress detection on grapevine: Interest in combining climate data using multiblock method

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26 perature (T_a) and wind speed (W_s). First, Partial Least Squares (PLS)
27 models were established to relate spectral data to physiological variables.
28 Then, Sequential Orthogonalized-Partial Least Squares (SO-PLS) was used
29 to predict these physiological variables with two blocks: spectral and climate
30 data. PLS models are obtained for g_s ($R^2= 0.656$, bias= $8.76 \text{ mmol.m}^{-2}.\text{s}^{-1}$,
31 RMSE= $64.7 \text{ mmol.m}^{-2}.\text{s}^{-1}$) and E ($R^2= 0.625$, bias= $-0.02 \text{ mmol.m}^{-2}.\text{s}^{-1}$,
32 RMSE= $0.67 \text{ mmol.m}^{-2}.\text{s}^{-1}$). For E, improved results ($R^2= 0.699$, bias= 0.055
33 $\text{mmol.m}^{-2}.\text{s}^{-1}$, RMSE= $0.614 \text{ mmol.m}^{-2}.\text{s}^{-1}$) are obtained by using climate
34 data with SO-PLS. Generic PLS models achieved good predictive quality
35 despite different coloured berry varieties. Quality of these prediction models
36 could be improved by defining varietal models on a larger data set. Merging
37 spectral data with climate data improves prediction quality of transpiration
38 variable providing insights by adding further information with the aim of
39 improving predictive qualities.

40 *Keywords:* Spectroscopy, Water Stress, Physiological variables, Digital
41 Agriculture, Multivariate Data Analysis, Fusion data

42 **1. Introduction**

43 In recent years, climate fluctuations have been increasingly extreme, af-
44 fecting agricultural production (Lobell et al., 2011). In this context, one
45 of the biggest challenges for agriculture is to adapt agricultural practices to
46 these constraints.

47 Moreover, resulting abiotic stresses may modify crop sensitivity to dis-
48 eases (Mittler, 2006). In the event of a severe and persistent stress episode,
49 the consequence is an inexorable reduction in yield. Therefore, it becomes

50 critical to provide new methods to manage crops in order to avoid episodes
51 of severe abiotic stresses (Olesen et al., 2011).

52 The development of digital agriculture driven by new intelligent sensors
53 is one of the privileged paths to improve farm management (Fountas et al.,
54 2020; Zhai et al., 2020). The increasing adoption of sensors for agriculture
55 provides valuable data driving farm actions such as input use (pesticides,
56 irrigation, fertilisers) or harvest planning.

57 In crop production, soil drying is especially at stake on plant status. In
58 fact, water stress induces several physiological markers on plants (Simonneau
59 et al., 2017). At the leaf level, transpiration and stomatal conductance are
60 two physiological parameters closely related to the plant water status. These
61 physiological variables are highly influenced by multiple environmental fac-
62 tors, such as soil water availability, air humidity, radiation and temperature
63 (Damour et al., 2010).

64 Assessing such physiological parameters in real time with optical instru-
65 ments is a real challenge (Schultz and Stoll, 2010). Thermography has long
66 been studied as an optical instrument that gives an indication of transpi-
67 ration rate (Romano et al., 2011; Zhou et al., 2021). Indeed, a decrease in
68 transpiration, *e.g.* following a soil drying, leads to vegetation warming, which
69 is a consequence of stomatal closure.

70 Alternatively, visible and near-infrared (VIS-NIR) spectroscopy has been
71 widely used to evaluate vegetation status. In this spectral region (VIS-NIR),
72 information is related to both pigments and cell structure parameters (Xu
73 et al., 2019; Ryckewaert et al., 2021) which are parameters altered by wa-
74 ter stress. Moreover, maintaining a high spectral resolution in the VIS-NIR

75 region improves the description of vegetation responses to water stress (Ryck-
76 ewaert et al., 2021). This technology indirectly reveals different properties
77 that can describe water stress such as a decrease in chlorophyll content (Stei-
78 dle Neto et al., 2017) and water content (Zhang et al., 2012) in leaves. The
79 use of VIS-NIR spectroscopy provides the capability to study spectral bands
80 most related to the prediction of physiological variables such as stomatal
81 conductance (Rapaport et al., 2015; Dao et al., 2021).

82 Methodological efforts using chemometrics are expected to further exploit
83 spectral information from the vegetation (Mulla, 2013). A reference regres-
84 sion method called Partial Least Squares (PLS) (Wold et al., 2001) provides
85 models to predict response variables from spectral data. Recently, data fu-
86 sion methods, also called multiblock methods, have been developed to com-
87 bine several data sources. Adding an additional block such as climate data to
88 spectral data can potentially improve the performances of prediction models.
89 The most commonly used multiblock method is Sequential Orthogonalized-
90 Partial Least Squares (SO-PLS) regression (Naes et al., 2011) which sequen-
91 tially exploits information from different blocks *i.e.* types of data. With this
92 method, the association of spectral data with climate data has the potential
93 to improve physiological variable prediction.

94 The objective of this paper is to study the potential of VIS-NIR spec-
95 troscopy combined with climate data to predict physiological markers of wa-
96 ter stress such as transpiration and stomatal conductance of grapevine plants
97 (*Vitis vinifera* L.).

98 For this purpose, an experimental campaign with precise monitoring of
99 physiological variables has been carried out. First of all, physiological vari-

100 ables are predicted by using spectral data exclusively. Then, spectral and cli-
101 mate data combination is used for predictions using the data fusion method
102 called SO-PLS method.

103 **2. Materials and methods**

104 *2.1. Experimental design*

105 The experiment took place in summer 2020 at "Institut Agro" in Mont-
106 pellier, France (fig. 1). The objective of this experiment was to obtain a
107 water stress gradient on three grape varieties, Syrah, Riesling and Merlot, of
108 different ages (Syrah: two years old; Riesling: three years old; Merlot: four
109 years old) treated with two irrigation conditions also called modalities. Each
110 plant was grafted and pruned to bear only one main axis, then potted in a
111 9L pot filled with 3800 ± 1 g of a dry mixture of 70 % peat and 30 % clay
112 (custom-made potting soil, Klasmann-Deilmann), and staked vertically. The
113 plants were arranged in rows oriented almost north-south with a density of
114 2.8 plants/linear meter along the row. The main branch of each plant was
115 pruned at 22 leaves and all secondary branches were retained.

116 The first irrigation condition, called well-watered (WW), consisted of
117 irrigating the pots several times a day to maintain the weight of each pot
118 at a level that did not constrain plant growth (this level was determined in
119 previous experiments). The second irrigation condition was defined in order
120 to induce a water deficit (WD). This second condition consisted of stopping
121 irrigation during one week. Each modality contained 6 plants per variety,
122 representing a total of 36 pots. The experiment was repeated in its entirety
123 twice with new pots at one-week interval with suspension of irrigation on

124 06/22/2020 for the first experiment, and on 07/06/2020 for the second.



Figure 1: Vine pots used for experimentation

125 *2.2. Physiological measurements*

126 The transpiration of each plant was determined from the weight evo-
127 lution of each pot placed on a strain gauge load cell (Micro Load Cell
128 model CZL635, range 20 kg, mean error ± 70 g), recorded every 30 sec-
129 onds (data logger CR1000 Campbell Scientific, Leicestershire, UK). Transpi-
130 ration rate was given by a linear regression of weight versus time over a 4h
131 time-frame. Transpiration per leaf surface (E), corresponding to water loss
132 through leaves only, was then adjusted to the total leaf area of each plant, es-
133 timated from planimeter measurements (LI-3100C LI-COR Biosciences Inc.,
134 Nebraska, USA), and vein size measurements, which were converted to area
135 from previously established charts.

136 Stomatal conductance was measured with a porometer (Model AP4, Delta-
137 T Devices, Burwell, Cambridge, UK) on young mature leaves with good sun
138 exposure (east side of the row in the morning and west side in the afternoon).

139 This measurement was carried out on one leaf per plant chosen at random
140 three times a day (9am, 11.30am and 3.30pm, UTC+2). The porometer was
141 calibrated before each series of measurements (three times a day).

142 *2.3. Climate data*

143 Four climate parameters were measured: Air temperature (T_a), relative
144 humidity (RH), global radiation (R_g) and wind speed (W_s).

145 T and RH were measured with a capacitive thermohygrometer (HMP35A
146 Vaisala; Oy, Helsinki, Finland) placed in a naturally aspirated radiation
147 shield at 2.5m height. R_g was measured with a PPF sensor (LI-190SB;
148 LI-COR, Lincoln, NE, USA). W_s was measured with a 3-cup anemometer
149 (A100L2, Vector Instruments, Denbighshire, UK). Data were collected every
150 30 seconds, averaged over 1800 seconds and stored in a datalogger (CR10X;
151 Campbell Scientific Ltd, Shepshed, Leicestershire, UK).

152 *2.4. Hyperspectral acquisitions*

153 Hyperspectral images were acquired using a hyperspectral camera (Specim,
154 Specim IQ, Finland) covering the spectral range from 400 nm to 1000 nm
155 with 204 spectral bands. Spectral regions were cut off after 800 nm due to
156 the high level of noise in this experiment. The distance between the camera
157 and vine pots was set to approximately 1 meter. Images were acquired each
158 day for each modality at three different times (8am, 2pm and 4pm, UTC+2)
159 producing a set of 160 hyperspectral images. Camera orientation during im-
160 age capture was defined to minimise direct sunlight. Thus, west side was
161 privileged at 8am and 2pm and east side at 4pm (see fig. 2).



Figure 2: Camera orientation during hyperspectral image capture: towards west (orange arrows) at 8am and 2pm and east (red arrows) at 4pm. Source: <https://www.geoportail.gouv.fr/>

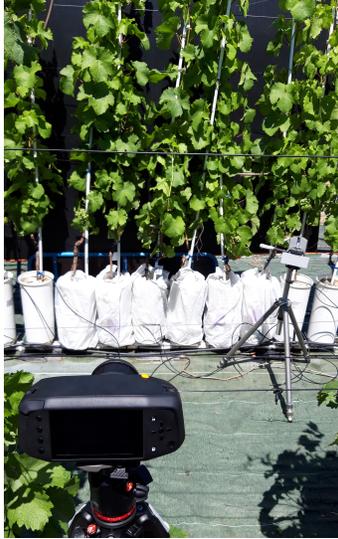


Figure 3: Typical scene where hyperspectral images were acquired. One image corresponded to one of the modalities of the experimental design with 6 pots of vines. The reference is placed in the scene.

162 A white reference (SRS99, Spectralon $\text{\textcircled{R}}$) was used to measure natural in-
 163 cident light ($I_0(\lambda)$) to standardise all measured images from non-uniformities
 164 of all instrumentation components (light source, lens, detector). This refer-
 165 ence was systematically placed in the scene for each image acquisition (see
 166 fig. 3). From these measurements, reflectance ($R_s(\lambda)$) was calculated for
 167 each image:

$$R_s(\lambda) = \frac{I_s(\lambda) - I_b(\lambda)}{I_0(\lambda) - I_b(\lambda)} \quad (1)$$

168 where $I_s(\lambda)$ is the reflected light intensity, $I_b(\lambda)$ the dark current image
 169 recorded by the camera.

170 *2.5. Data analysis*

171 All computations, data processing and multivariate data analysis were
172 performed with MATLAB software v.R2015b (The Mathworks Inc., Nat-
173 ick,MA, USA).

174 *2.5.1. Image preprocessing workflow*

175 The presented workflow was established to generate a spectral database.
176 This workflow was defined in three main steps:

177 The first step was to manually extract an area corresponding to foliage
178 to obtain a reference spectrum \mathbf{s}_{ref} . The second step was to identify, for
179 all images, vegetation pixels that present similar spectra to the reference
180 vegetation spectrum. For this purpose, the Spectral Angle Mapper (SAM)
181 (Kruse et al., 1993) was used as an indicator that describes spectral similarity
182 between two spectra. Expressed in degrees, this indicator calculates the angle
183 formed between \mathbf{s}_{ref} and all spectra of an image in the vector space defined
184 by the wavelengths. For a given pixel i , the SAM between \mathbf{s}_{ref} and \mathbf{s}_i is
185 written as follows:

$$\text{SAM}(\mathbf{s}_{ref}, \mathbf{s}_i) = \arccos \left(\frac{\langle \mathbf{s}_{ref}, \mathbf{s}_i \rangle}{\|\mathbf{s}_{ref}\| \|\mathbf{s}_i\|} \right) \quad (2)$$

186 With $\|\cdot\|$ being euclidean norm. Spectra are similar when angle value is
187 close to 0° . Conversely, the larger the SAM value, the higher the difference
188 between the two spectra. This indicator value has the advantage of being
189 independent of signal intensity.

190 After identifying vegetation-related pixel in one image, the third step
191 was to create a subset of 500 vegetation pixels without any outlier based

192 on their spectra. For this purpose, a principal component analysis (PCA)
193 was applied on all vegetation spectra of one image. Then, Q -residuals and
194 T^2 criteria were computed in order to identify potential outlier spectra. 500
195 pixels were randomly selected excluding outliers.

196 Finally, the 500 collected spectra were averaged by modality (*i.e.* per
197 image) forming a total of 160 spectra.

198 2.5.2. PLS predictions based on spectral data

199 In chemometrics, PLS regression (Wold et al., 2001) is the widely used
200 method to predict a reference variable \mathbf{y} from spectral data \mathbf{X} . \mathbf{X} dimension
201 is $n \times p$ where n is the total number of observations and p the number of
202 variables or wavelengths. \mathbf{y} dimension is $n \times 1$. The final equation of PLS
203 regression can be written as follows:

$$\mathbf{y} = \mathbf{X}\mathbf{b} + \mathbf{r}_X \quad (3)$$

204 Where \mathbf{b} is the vector containing regression coefficients and \mathbf{r}_X is a vector
205 containing residuals of the model.

206 To do so, a model is established between intermediate variables, called la-
207 tent variables computed respectively from \mathbf{X} and \mathbf{y} . The adjustment of these
208 latent variables is performed according to different iterative algorithms. Es-
209 sentially, \mathbf{X} is decomposed into scores represented by a matrix \mathbf{T} of dimension
210 $n \times k$, and into loadings \mathbf{P} of dimension $p \times k$, where k represents the number
211 of latent variables retained for the model. Similarly, \mathbf{y} is decomposed into
212 a matrix of scores \mathbf{U} and loadings \mathbf{q} of dimension $n \times k$ and of $1 \times k$. This
213 intermediate variables can be defined by these equations:

$$\mathbf{X} = \mathbf{T}\mathbf{P}^t + \mathbf{E}_x \quad (4)$$

$$\mathbf{y} = \mathbf{U}\mathbf{q}^t + \mathbf{e}_y \quad (5)$$

214 Where \mathbf{T} and \mathbf{U} are the scores of \mathbf{X} and \mathbf{y} respectively. \mathbf{P} and \mathbf{q} represent
 215 loadings for \mathbf{X} and \mathbf{y} respectively. \mathbf{E}_x and \mathbf{e}_y represent residuals in the
 216 decomposition of \mathbf{X} and \mathbf{y} .

217 *2.5.3. SO-PLS predictions with both spectral and climate data*

218 SO-PLS (Naes et al., 2011) regression is a multi-block method where
 219 prediction model is built sequentially from each data block. First, the SO-
 220 PLS algorithm started as PLS method with the first block containing spectral
 221 data, as previously described (eq. 3).

222 Then, an orthogonalisation procedure was performed to remove informa-
 223 tion (already exploited from the first regression) on the second block contain-
 224 ing climate data, defined by the matrix \mathbf{Z} . This orthogonalisation, providing
 225 \mathbf{Z}_\perp , can be written as follows:

$$\mathbf{Z}_\perp = \mathbf{Z} - \mathbf{T}(\mathbf{T}^t\mathbf{T})^{-1}\mathbf{T}^t\mathbf{Z} \quad (6)$$

226 Where \mathbf{T} represented scores of \mathbf{X} described eq. 4. Then, a second PLS
 227 model is established between the residual matrix, corresponding to the matrix
 228 \mathbf{r}_X (eq. 3) and the matrix \mathbf{Z}_\perp . This regression is established by following
 229 the same procedure as previously for the regression between \mathbf{X} and \mathbf{y} (eq. 3
 230 4 and 5). At the end of this procedure, a vector \mathbf{c} containing the regression

231 coefficients is obtained. The final equation of the SO-PLS multiblock method
 232 can be written as follows:

$$\mathbf{y} = \mathbf{X}\mathbf{b} + \mathbf{Z}_{\perp}\mathbf{c} + \mathbf{r}_{X,Z} \quad (7)$$

233 With $\mathbf{r}_{X,Z}$, the residual matrix of the SO-PLS model.

234 2.6. Evaluation strategies of prediction models

235 The spectral data set was divided into two independent data sets: a
 236 calibration set of 106 images and a test set. The test set was formed with
 237 the 54 remaining hyperspectral images. This test set was constructed to
 238 reflect all modalities of the experimental design.

239 A cross-validation step was performed to select the number of latent vari-
 240 ables per block using a k-fold validation procedure (Camacho and Ferrer,
 241 2012) performed with five blocks repeated twice. The maximum number of
 242 latent variables was set at 20 for the spectral data and 3 for the climate data.

243 The validation errors were then calculated and used to determine the
 244 optimal number of latent variables. The parameters chosen for the evaluation
 245 of the models are the root-mean-square error (RMSE), the bias and the
 246 coefficient of determination R^2 . These parameters were calculated as follows:

$$Bias = \frac{1}{N} \sum_{i=1}^N (\hat{y}_i - y_i) \quad (8)$$

$$RMSE = \sqrt{\frac{1}{N} \sum_{i=1}^N (\hat{y}_i - y_i)^2} \quad (9)$$

$$R^2 = 1 - \frac{\sum_{i=1}^N (\hat{y}_i - y_i)^2}{\sum_{i=1}^N (y_i - y_m)^2} \quad (10)$$

247 Where \hat{y}_i denotes the predicted value, y_i the observed value, y_m the mean
 248 value and N the total number of observations.

249 3. Results and discussion

250 3.1. Data visualisation

251 3.1.1. Y variables: transpiration and stomatal conductance

252 Value distributions of transpiration (E) and stomatal conductance (g_s)
 253 are shown in figure 4b and figure 4a.

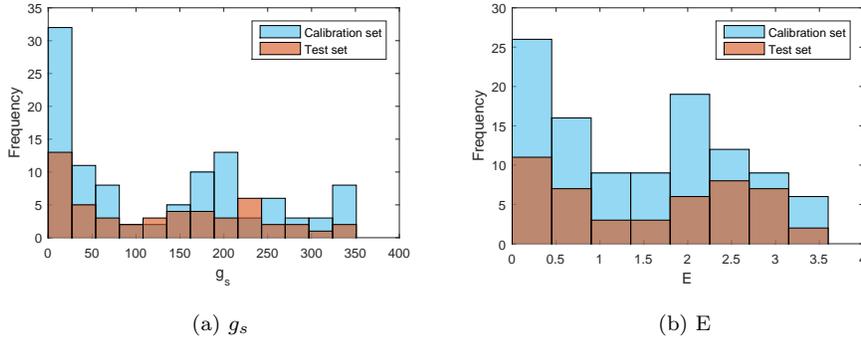


Figure 4: Histograms of response variable values of (a) stomatal conductance g_s ($\text{mmol.m}^{-2}.\text{s}^{-1}$) and (b) transpiration E ($\text{mmol.m}^{-2}.\text{s}^{-1}$).

254 g_s values range from 0 to 350 $\text{mmol.m}^{-2}.\text{s}^{-1}$ (fig. 4a). Values above 250
 255 $\text{mmol.m}^{-2}.\text{s}^{-1}$ correspond to well-watered plants and optimal sun exposition.
 256 Then, a high frequency around 200 $\text{mmol.m}^{-2}.\text{s}^{-1}$ appears. This range of
 257 values corresponds to plants in water deficit and/or to lower sun radiation
 258 at the beginning or end of the day. A majority of low values between 0 and
 259 25 $\text{mmol.m}^{-2}.\text{s}^{-1}$ are observed corresponding to closed stomata. This occurs
 260 when there is a complete cessation of the photosynthetic process. Plants are

261 then considered as stressed and correspond to individuals whose irrigation
262 has been stopped for a long time.

263 E values range from 0 to 4 $\text{mmol.m}^{-2}.\text{s}^{-1}$ (fig. 4b). High values (≥ 2.5
264 $\text{mmol.m}^{-2}.\text{s}^{-1}$) of E correspond to a transpiration level expected when no
265 water stress is applied. Low values, lower than 1, mean that plant transpira-
266 tion is reduced. With such values during the day, the metabolic activity of
267 the plant is considered as suboptimal.

268 For both physiological variables, test sets have similar value distributions
269 than those of the corresponding calibration set and cover the whole range of
270 values.

271 3.1.2. Spectral data

272 The figure 5 shows average spectra obtained by modality (WD and WW)
273 and by grape variety.

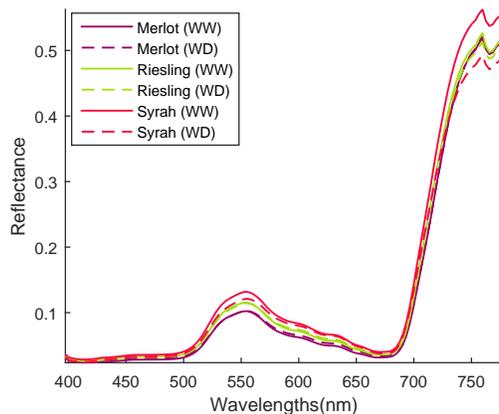


Figure 5: Spectral data, mean spectra per modality

274 These spectra corresponds to typical vegetation spectra (Xu et al., 2019;
275 Ryckewaert et al., 2021) with specific characteristics at 450 nm, 550 nm,

276 650 nm related to pigments (carotenoids, chlorophyll and anthocyanins) and
 277 the red-edge, which corresponds to a slope between the visible and near-
 278 infrared range towards 720 nm.

279 Average spectra are very close to each other regardless the irrigation
 280 regime both for Merlot and Riesling but substantially differ from these of
 281 Syrah. Reflectance values are higher for Syrah over the whole spectrum
 282 when irrigated but lower in the NIR domain when non-irrigated.

283 The spectrum in irrigated condition differs from the spectrum in non-
 284 irrigated condition only for Syrah. The visualisation of average spectra is not
 285 sufficient to observe significant differences between the irrigation conditions
 286 for other varieties.

287 3.2. PLS with one block using spectral data

288 3.2.1. Cross-validation procedure

289 Table 1 shows criterion values obtained with the cross-validation step to
 290 predict variables E and g_s using the PLS method.

Table 1: PLS criteria obtained after the cross validation procedure.

Variable	LV	R_{cv}^2	$bias_{cv}$ (mmol.m ⁻² .s ⁻¹)	$RMSE_{cv}$ (mmol.m ⁻² .s ⁻¹)
g_s	9	0.639	5.41	67.3
E	8	0.625	-0.02	0.67

291 With the PLS method, the cross-validation suggests 8 LV for E and
 292 9 LV for g_s . For g_s , R_{cv}^2 , $bias_{cv}$ and $RMSE_{cv}$ have values of 0.639, 5.41
 293 mmol.m⁻².s⁻¹ and 67.3 mmol.m⁻².s⁻¹ respectively. For E, R_{cv}^2 , $bias_{cv}$ and
 294 $RMSE_{cv}$ have values of 0.625, -0.02 mmol.m⁻².s⁻¹ and 0.67 mmol.m⁻².s⁻¹ re-
 295 spectively. $RMSE_{cv}$ values obtained for the prediction of these two variables

296 are to be compared with the observed values (fig. 4a and 4b).

297 3.2.2. Model evaluation

298 .

299 E and g_s PLS models calibrated with calibration set are applied to the
300 independent test set. Figures 6b and 6a show predicted values according to
301 observed values.

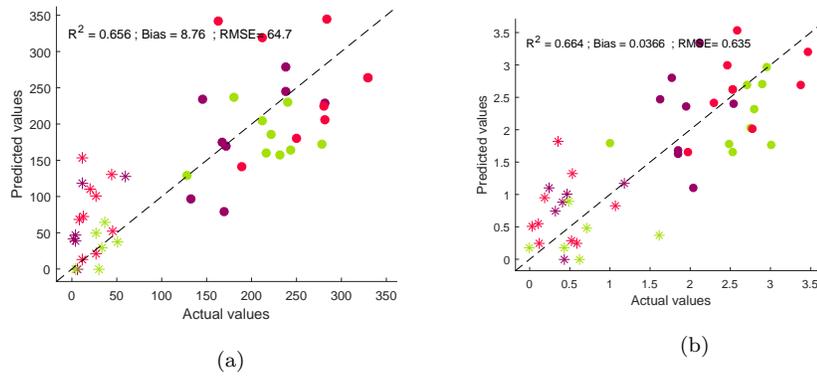


Figure 6: PLS-model evaluation on the test set of (a) stomatal conductance g_s ($\text{mmol.m}^{-2}.\text{s}^{-1}$) and (b) transpiration E ($\text{mmol.m}^{-2}.\text{s}^{-1}$). Symbol indicates irrigation condition: ● well-watered and * without irrigation. Colour identifies varieties: red: Merlot; green: Riesling; violet: Syrah.

302 Figure 6a shows criterion values obtained for g_s prediction. The separation
303 between the irrigated and non-irrigated modalities is clearly observed.
304 For this variable, criteria ($R^2 = 0.656$, bias= $8.76 \text{ mmol.m}^{-2}.\text{s}^{-1}$, RMSE= 64.7
305 $\text{mmol.m}^{-2}.\text{s}^{-1}$) are close to the calibration model with a larger bias (tab.
306 1). Some observed values below $50 \text{ mmol.m}^{-2}.\text{s}^{-1}$ seem more difficult to pre-
307 dict. On the other hand, above $50 \text{ mmol.m}^{-2}.\text{s}^{-1}$, satisfying predictions are
308 obtained.

309 As previously observed, separation between the irrigated and non-irrigated
 310 modalities is clearly identified for E. Criteria values obtained for E prediction
 311 are 0.664 for R^2 , $-0.0366 \text{ mmol.m}^{-2}.\text{s}^{-1}$ for the bias and $0.635 \text{ mmol.m}^{-2}.\text{s}^{-1}$
 312 for the RMSE. These values are close to values obtained during the cross-
 313 validation procedure (tab. 1).

314 Error values of these two variables are sufficient to identify occurrence of
 315 water stress on plants.

316 It is interesting to note that the error is of the same nature for irrigated
 317 plants, at the beginning of desiccation, or in more severe desiccation, *i.e.* in
 318 the complete range of variation of the studied variables.

319 3.2.3. Regression coefficients: contribution of the different wavelengths to 320 models

321 Figure 7 shows regression coefficients (B-coefficients) of the two PLS mod-
 322 els to predict g_s (fig. 7a) and E (fig. 7b).

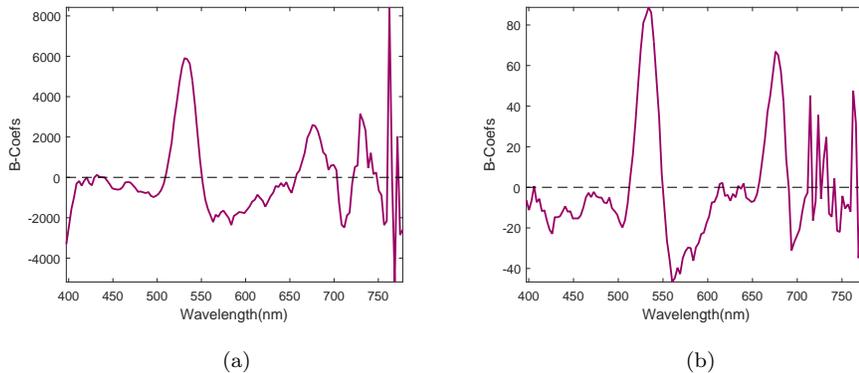


Figure 7: Regression coefficients of the PLS-models predicting (a) stomatal conductance g_s and (b) transpiration E.

323 Regression coefficients are given by PLS models according eq. 3. These

324 coefficients provide the contributions of wavelengths or spectral regions con-
325 sidered in the PLS model.

326 For g_s , a very high peak is observed around 531 nm. At this wavelength,
327 spectra are sensitive to anthocyanin content (Ryckewaert et al., 2021). Thus,
328 difference observed in the stomatal conductance values is probably related
329 to a difference in anthocyanin content in leaves. An acute metabolic use of
330 anthocyanins or a disturbance in the xanthophyll cycle seems to occur when
331 water status deteriorates. Besides, high values of these regression coefficients
332 are also observed around 680 nm. This spectral region is known to be related
333 to chlorophyll content (Ryckewaert et al., 2021). As a consequence, the
334 combination of spectral information related to chlorophyll and anthocyanin
335 contents seem to be important for stomatal conductance predictions.

336 Negative peaks are also visible. A negative peak is visible at 714 nm,
337 corresponding to the middle of the red-edge slope (fig. 5). Another negative
338 contribution can be found in the spectral region at 570 nm. This wave-
339 length is often used as a reference to 533 nm to compute the Photochemical
340 Reflectance Index. Beyond 750 nm, regression coefficients vary rapidly some-
341 times with abrupt reversals of sign, suggesting the complexity or the absence
342 of a significant interpretation.

343 In the case of E (fig. 7b), two positive peaks are observed around 533 nm
344 and 675 nm. These peaks are located at the same wavelengths previously
345 observed (fig. 7a). However, slight differences are noticeable for the variable
346 E such as a change in ratio between peak values at 533 nm and 675 nm or a
347 sign change occurring at a lower wavelength (before 700 nm for E coefficients
348 and after 700 nm for g_s coefficients). Negative peaks are also visible as

349 described for g_s around 570 nm. Other negative coefficients are visible in
350 the carotenoid region, around 426 nm. This result could be related to the
351 decrease in concentration of some carotenoids with increasing water stress as
352 reported in other works (Salazar-Parra et al., 2015). In the same figure (fig.
353 7b), noise seems to appear in the near-infrared region between 700 and 800
354 nm.

355 The anthocyanin and chlorophyll contents are the two pigments most
356 closely related to the values obtained for transpiration E and stomatal con-
357 ductance g_s .

358 When experiencing sudden water deficit, stomatal conductance changes
359 very rapidly. A complex relationship between anthocyanin and chlorophyll
360 occurs as a response to this water stress and is linked to stomatal conductance
361 to regulate the photosynthetic process. These results are consistent with the
362 well-known effect of water stress on stomatal closure (and the resulting de-
363 crease in transpiration), but also on chlorophyll degradation and xanthophyll
364 cycling (Doupis et al., 2020). The stability of the model for predicting g_s or
365 E from hyperspectral data therefore depends *a priori* on the stability of the
366 relationships between g_s or E and pigment concentrations. The behaviour of
367 the model for the three varieties, suggests a similar evolution of their phys-
368 iological characteristics, that influence the reflectance spectrum in response
369 to the water regime.

370 3.3. SO-PLS using a second block with climate data

371 3.3.1. Cross-validation procedure

372 Table 2 shows results of optimal parameters obtained with cross-validation
373 step for the prediction of variables g_s and E using the SO-PLS multi-block

374 method.

Table 2: Number of latent variables (LV) obtained after cross validation procedure for the first block (spectral data) and the second block (climate data).

Variable	LV 1 st block (spectral data)	LV 2 nd block (climate data)	R _p ²	bias _p (mmol.m ⁻² .s ⁻¹)	RMSE _p (mmol.m ⁻² .s ⁻¹)
<i>g_s</i>	9	0	0.639	5.41	67.3
E	8	3	0.684	0.02	0.613

375 Regarding *g_s* model, cross-validation suggests 9 latent variables for the
376 first block and 0 for the second block corresponding respectively to spectral
377 data and climate data. Information from the second block does not improve
378 the *g_s* prediction model. SO-PLS parameterisation then corresponds to the
379 PLS model calculated previously using only the spectral data (table 1).

380 This result is surprising because radiation level is known to influence
381 stomatal opening (Jones, 2013). However, considering the environmental
382 conditions of the measurements, only relatively high level of radiation (ex-
383 posed leaves and sunny days) were encountered. Therefore, the stomatal
384 conductance was not driven by this factor during experiments.

385 Regarding E model, the number of latent variables retained is 8 for the
386 first block and 3 for the second block. In this case, both blocks are exploited
387 to estimate the prediction model. The climate data seem to provide addi-
388 tional information to the spectral data for transpiration prediction. This
389 result is consistent with the fact that transpiration depends on the one hand
390 on *g_s* and on the other hand on the evaporative capacity of the air, which
391 is itself determined by relative humidity, temperature, radiation and wind
392 speed (Jones, 2013).

393 From a theoretical point of view, a relationship was primarily expected

394 between VIS-NIR signature and leaf water status (with possible, additional
395 influences of changes in leaf pigment composition and other constituents dur-
396 ing soil drying). Considering that stomatal conductance fairly well correlates
397 with leaf water status (Damour et al., 2010), our observation that stom-
398 atal conductance also correlated with VIS-NIR characteristics is in line with
399 the theoretical expectation. Regarding transpiration, which is roughly equal
400 to the stomatal conductance multiplied by the evaporative demand (mostly
401 vapour pressure deficit), a stronger influence of climate on the relationship
402 with VIS-NIR characteristics could also be expected.

403 *3.3.2. Model evaluation*

404 As mentioned before, SO-PLS model of g_s corresponds to PLS model
405 previously studied in section 3.2.2 (fig. 6a and 7a).

406 SO-PLS results for E prediction are shown in figure 8.

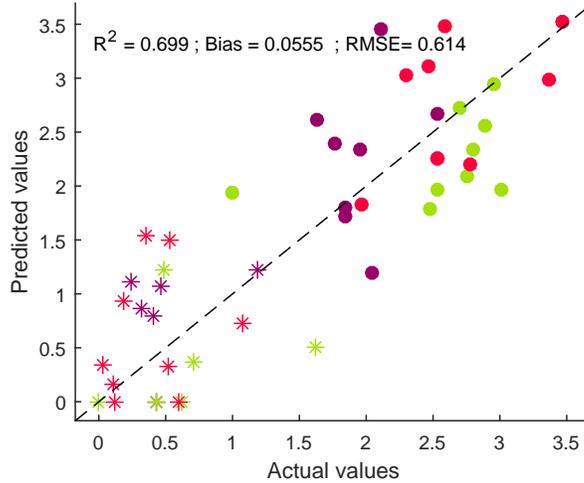


Figure 8: Model evaluation on a test set for the prediction of transpiration E (mmol.m⁻².s⁻¹). Symbol indicates irrigation condition: ● well-watered and * without irrigation. Colour identifies varieties: red: Merlot; green: Riesling; violet: Syrah

407 R², bias and RMSE criteria obtained have values of 0.699, 0.0555 mmol.m⁻².s⁻¹
 408 and 0.614 mmol.m⁻².s⁻¹, respectively. These criteria are improved compared
 409 to the results obtained with PLS method (fig. 6b). Including the second block
 410 corresponding to climate data in the model improves the E prediction. In a
 411 perspective of use for agronomic diagnosis, it is worth noticing that the same
 412 model is used for all three grape varieties tested here, despite the slightly
 413 different spectral signature of Syrah.

414 3.3.3. Regression coefficients for each block

415 Figures 9a and 9b show regression coefficients for spectral and climate
 416 data, respectively.

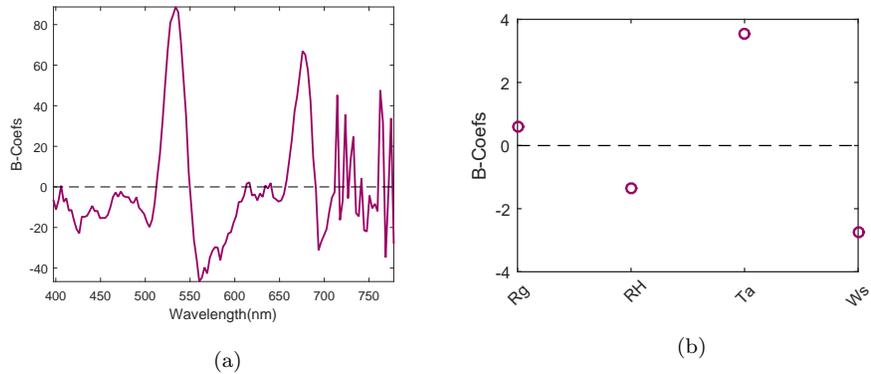


Figure 9: Regression coefficients of SO-PLS model to predict transpiration E (a) for the first block (spectral data) and (b) for the second block (climate data)

417 These vectors show variables involved in E prediction. For the first block
 418 corresponding to spectral data (fig. 9a), the same coefficients are obtained as
 419 previously (fig. 7b). Indeed, models are established with 8 latent variables
 420 in both cases.

421 Coefficients obtained from the second block show non-zero values for all
 422 four climate variables: radiation (Rg), relative humidity (RH), temperature
 423 (Ta) and wind speed (Ws). These parameters are then taken into account in
 424 the prediction model.

425 Both coefficients related to Rg and Ta have positive signs while those of
 426 RH and Ws have negative signs. This shows that for given spectral charac-
 427 teristics, an increase of Rg or Ta induces an increase of E . This result could
 428 be expected as the evaporative capacity of the air increases with Rg and
 429 Ta. It can be noted, however, that Rg has a lower impact compared to Ta.
 430 This was probably due to a lower range of variation of Rg at the time of our
 431 measurements (as commented above). Conversely, increasing values of RH

432 and W_s will tend to decrease transpiration. This result was also expected
433 for RH, because when RH increases, the evaporative capacity of the air de-
434 creases. The effect of wind is more complex, because, on the one hand, it
435 decreases leaf temperature, which reduces transpiration. But, on the other
436 hand, it increases aerodynamic conductance, which increases transpiration.
437 It seems that the first effect dominates here. This effect should be tested un-
438 der other radiation conditions (especially lower level of radiation on leaves)
439 and other wind speed ranges.

440 Furthermore, absolute values of these coefficients show the impact of the
441 associated variables in the prediction model. Thus, T_a and W_s have a greater
442 impact than R_g and RH on transpiration.

443 **4. Conclusion**

444 This article proposed a study of prediction models established from spec-
445 tral data, for two major variables related to water stress, namely stomatal
446 conductance g_s and transpiration E . Despite different coloured berry vari-
447 eties (one white and two red), generic PLS models achieved good predictive
448 quality. Quality of these prediction models could be improved by defining
449 varietal models on a larger data set. Combining predictions of these two
450 variables is a promising solution to assess plant water stress.

451 In addition, merging spectral data with climate data improves prediction
452 quality of the transpiration variable. Moreover, if additional information
453 from other sensors is available, multi-block methods could improve predictive
454 qualities of physiological variables. The proposed methodology enables to
455 consider coupling spectral point acquisitions with connected objects in the

456 field in order to improve the prediction of agronomic variables.

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