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# Constraint and Cost Function Networks: feasibility, optimization and learning.

Thomas Schiex

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# CONSTRAINT & COST FUNCTION NETWORKS: FEASIBILITY, OPTIMIZATION AND LEARNING

*JFPC'2021*



T. SCHIEX (AND PLENTY OF COLLEAGUES)

UNIVERSITÉ FÉDÉRALE DE TOULOUSE, ANITI, INRAE MIAT, TOULOUSE, FRANCE

JUNE 22, 2021



## A Constraint Network $\langle \mathbf{V}, \Phi \rangle$

- a sequence of discrete domain variables  $\mathbf{V}$
- a set  $\Phi$  of  $e$  Boolean functions (or constraints)
- Each  $\varphi_S \in \Phi$  is a truth function from  $D^S \rightarrow \{t, f\}$

## Joint truth function

$$\Phi_{\mathcal{M}} = \bigwedge_{\varphi_S \in \Phi} \varphi_S$$

## The Constraint Satisfaction Problem (NP-complete)

- Is it possible to make  $\Phi_{\mathcal{M}} = t$ ?

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## Languages for domains and constraints

- Constraint Networks: Boolean tables (tensors) for domains and constraints
- Constraint Programming: interval variables, specialized constraints, control

Tables (or tensors) for  $\varphi_S$ 

- A multidimensional table with a Boolean for every tuple in  $D^S$
- Says if it is authorized ( $t$ ) or not ( $f$ )

## Pairwise difference (3 values)

$$\begin{bmatrix} f & t & t \\ t & f & t \\ t & t & f \end{bmatrix}$$



## Languages for domains and constraints

- Constraint Networks: Boolean tables (tensors) for domains and constraints
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## Global constraints

- Names for specific (useful) constraints

## Most famous

`ALLDIFFERENTS`

## Languages for domains and constraints

- Constraint Networks: Boolean tables (tensors) for domains and constraints
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## Application domains: NP and beyond

Excel at the analysis of complex perfectly known systems

Digital circuit verification, scheduling and other resource management problems, planning, software verification, theorem proving,...

Biology?

## Cost Function Network $\langle \mathcal{V}, \Phi, k \rangle$

- a sequence of discrete domain variables  $\mathcal{V}$
- a set  $\Phi$  of  $e$  integer cost functions
- Each  $\varphi_S \in \Phi$  is a numerical function bounded by  $k$  (finite or infinite)

Joint cost function using  $a +^k b = \min(a + b, k)$

$$\Phi_{\mathcal{M}} = \sum_{\varphi_S \in \Phi}^k \varphi_S$$

The Weighted Constraint Satisfaction Problem (decision NP-complete)

- What is the minimum of  $\Phi_{\mathcal{M}}$ ?

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## Global functions

- Names for specific (useful) functions

## Soft difference (3 values)

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

## A useful one

KNAPSACK<sub>S</sub>



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## Costs and constraints

- We assume non negative integer costs
- A constraint is a cost function that maps to  $\{0, k\}$
- $k = 1$  defines a pure Constraint Network

## Optimum preserving operations

- scaling:  $2^{63} \approx 19$  digits. Fixed decimal point numbers ..... ok
- shifting: negative numbers and maximization ..... ok

## Extra assumptions inside the solver

w/o l.o.g.

- CFNs have all unary functions  $\varphi_i, X_i \in \mathcal{V}$
- CFNs have a constant function  $\varphi_\emptyset$

(domains)

## Crucial property

 $\varphi_\emptyset$  is a lower bound of the joint function  $\Phi_{\mathcal{M}}$

## EXAMPLE: MIN-CUT

Graph  $G = (V, E)$  with edge weight function  $w$

- A Boolean variable  $X_i$  per vertex  $i \in V$
- A cost function per edge  $e = (i, j) \in E : \varphi_{ij} = w(i, j) \times \mathbb{1}[x_i \neq x_j]$

A simple graph

- vertices  $\{1, 2, 3, 4\}$
- cut weight 1 or 1.5 (1, 3)
- edge (1, 2) hard

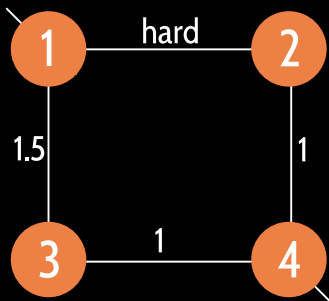
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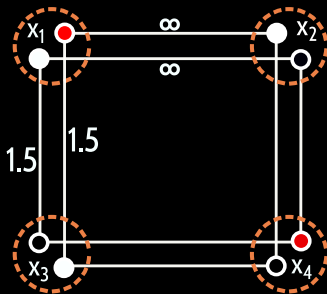
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A simple graph

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## Min-CUT on 4 variables

```
{
  "problem" :{"name": "MinCut", "mustbe": "<100.0"},
  variables: {"x1": ["1"], "x2": ["1","r"],
             "x3": ["1","r"], "x4": ["r"]}
  "functions": {
    "cut12": {"scope": ["x1","x2"], "costs": [0.0, 100.0, 100.0, 0.0]},
    "cut13": {"scope": ["x1","x3"], "costs": [0.0,1.5,1.5,0.0]},
    "cut23": {"scope": ["x2","x3"], "costs": [0.0,1.0,1.0,0.0]},
    "cut34": {"scope": ["x3","x4"], "costs": [0.0,1.0,1.0,0.0]}
  }
}
```

## Min-CUT on 4 variables

```
import pytoulbar2
myCFN = pytoulbar2.CFN(100,1) # ub, resolution (optional)
for i in range(4):
    myCFN.AddVariable("x"+str(i+1),["l", "r"]) # returns an index
myCFN.AddFunction(["x1"], [0,100])
myCFN.AddFunction(["x4"], [100,0])
myCFN.AddFunction(["x1","x3"], [0,1.5,1.5,0])
...
sol = myCFN.Solve() # returns a triple (sol, cost, _)
```



## Definition

- Variables  $X_{ij}$  for cell  $(i, j)$  has domain  $\{1, \dots, 9\}$
- Set  $R_i$  (resp.  $C_j$ ) contains all variables of row  $i$  (resp. column  $j$ )
- Set  $S_i$  contains all variables in sub-cell  $i$
- There is an ALL-DIFFERENT constraint on each of these
- or a clique of pairwise DIFFERENT constraints

## Example

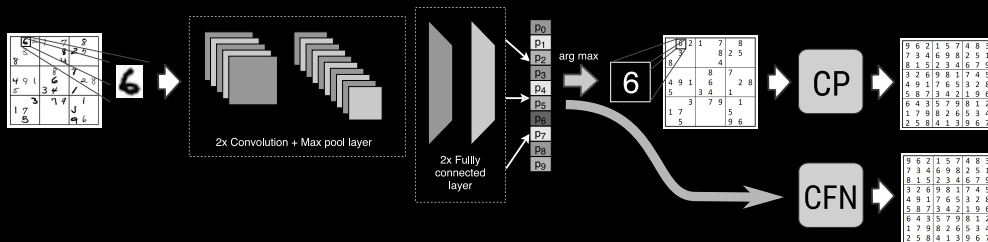
Let's have a look at the `pytoulbar2` code.

```
myCFN = pytoolbar2.CFN(1)    # k = 1, so CSP

for i in range(9):
    for j in range(9):
        vIdx = myCFN.AddVariable("X"+str(i+1)+"."+str(j+1),range(1,10))
        columns[j].append(vIdx)
        rows[i].append(vIdx)
        cells[(i//3)*3+(j//3)].append(vIdx)

for scope in rows+columns+cells:
    addCliqueAllDiff(myCFN,scope)    # Adds a clique of pairwise difference

for v,h in enumerate(grid):
    if h: myCFN.AddFunction([v],[0 if i == h else 1 for i in range(1,10)])
```



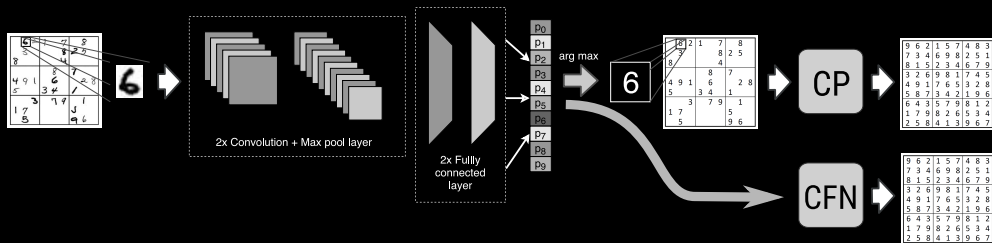
## The Boolean way

Thanks to Tias Gun for the picture above

1. Assign the cell variable with the prediction
2. LeNet has 99.2% accuracy, SAT-Net dataset 36.2 hints (avg): .....74.7% max. accuracy

## The Numbers way

1. Add LeNet output tensor (negated) as a cost function
2.  $(\min \sum -\log) \equiv (\max \prod)$  probabilities ..... >99% acc.



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```
myCFN = pyoulbar2.CFN(1000000,6)

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    for j in range(9):
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        columns[j].append(vIdx)
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for scope in rows+columns+cells:
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for v, h in enumerate(grid):
    if h: myCFN.AddFunction([v],-MNIST_output(csol,v,h))
```

## CFN compared to a COP approach<sup>1</sup>

- COP (OR-Tools) + global All-Different
- CFN (toulbar2) + pairwise differences

## Tight links with (I)LP

Let's look at the primal connection

---

<sup>1</sup>Maxime Mulamba et al. “Hybrid Classification and Reasoning for Image-based Constraint Solving”. In: *Proc. of CPAIOR'20, also in arXiv preprint arXiv:2003.11001*. 2020, pp. 364–380.

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- CFN (toulbar2) + pairwise differences ..... 0.05"
- 99.6% of all problems are solved backtrack-free by toulbar2
- CFN bounds way tighter than COP bounds [LL12]

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The “local polytope” [Sch76; Kos99; Wer07]

(without eq. (1))

Minimize  $\sum_{i,a} \varphi_i(a) \cdot x_{ia} + \sum_{\substack{\varphi_{ij} \in \Phi \\ a \in D^i, b \in D^j}} \varphi_{ij}(a,b) \cdot y_{iajb}$  such that

$$\sum_{a \in D^i} x_{ia} = 1 \quad \forall i \in \{1, \dots, n\}$$

$$\sum_{b \in D^j} y_{iajb} = x_{ia} \quad \forall \varphi_{ij} \in \Phi, \forall a \in D^i$$

$$\sum_{a \in D^i} y_{iajb} = x_{jb} \quad \forall \varphi_{ij} \in \Phi, \forall b \in D^j$$

$$x_{ia} \in \{0, 1\} \quad \forall i \in \{1, \dots, n\} \quad (1)$$

$nd + ed^2$  variables,  $n + 2ed$  constraints: a strong but expensive bound

- 1 Systematic search and local search
- 2 Pruning and Bounds
- 3 All Toulbar2 bells and whistles
- 4 WCSP solving has made huge progress
- 5 Learning CFN from data

## Systematic tree search

Time  $O(d^n)$ , linear space

- If all  $|D^X| = 1$  obvious minimum
- Else choose  $X \in V$  s.t.  $|D^X| > 1$  and  $u \in D^X$  and reduce to
  1. one query where we set  $X = u$
  2. one where  $u$  is removed from  $D^X$
- Return the minimum

update  $k$  to  $\Phi_{\mathcal{M}}(v)$

## Optimization

Branch and Bound [LW66]

If the  $\underbrace{\text{local lower bound}}_{\varphi_0}$  reaches the  $\underbrace{\text{global upper bound}}_k$

Prune!

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# DEPTH FIRST (CP) OR BEST FIRST (ILP)?

## Hybrid Best First Search [All+15]

Anyspace

- Uses Depth-First Search for a bounded amount of backtracks
- Pending nodes are pushed onto a list of Open nodes
- The next DFS starts from the best Open node
- Tree-decomposition friendly (BTD [GSV06]/AND-OR search [MD09])



## Nice properties

- Good upper bounds quickly (DFS)
- A constantly improving global lower bound (optimality gap)
- Implicit restarts, easy parallelization

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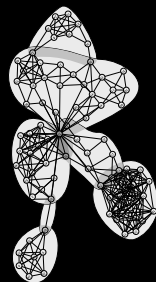


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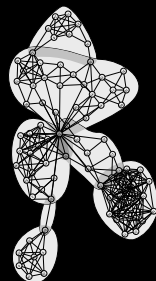
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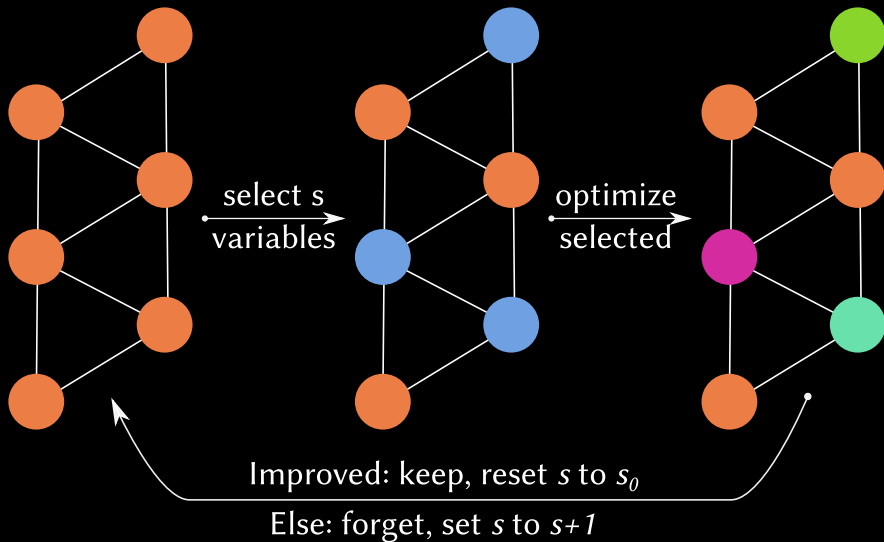
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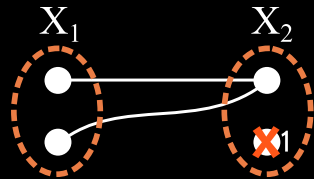
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## Filtering by Arc Consistency (support)

A value  $u \in D^i$  with no value  $v \in D^j$  such that  $\varphi_{ij}(u, v) = 0$  can be deleted, leaving the problem equivalent.



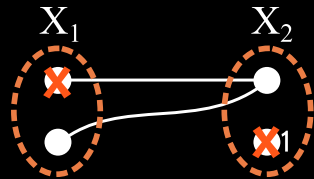
## Properties

- Combine  $\varphi_{ij}$  and  $\varphi_j$
- Project on  $X_i$
- Combine with  $\varphi_i$
- Unique fixpoint (monotonic), polynomial time

(inconsistency detection)

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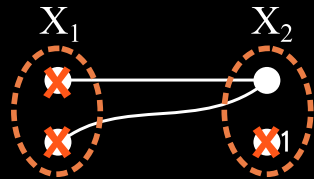
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## Obvious issue

One cannot add functions to the CFN: loss of equivalence, meaningless result

Equivalence Preserving Transformations with  $-^k$   $(\alpha -^k \beta) \equiv ((\alpha = k) ? k : \alpha - \beta)$

- Add the projection to  $\varphi_j$  with  $+^k$
- Subtract it from its source using  $-^k$

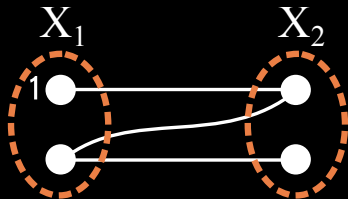


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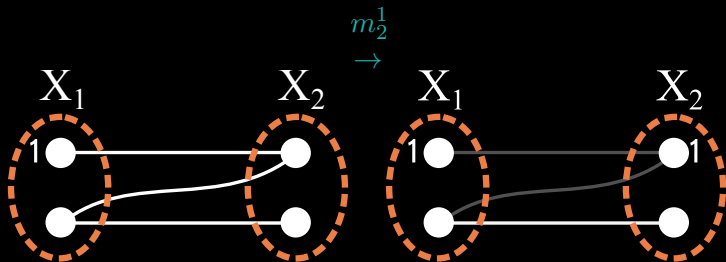
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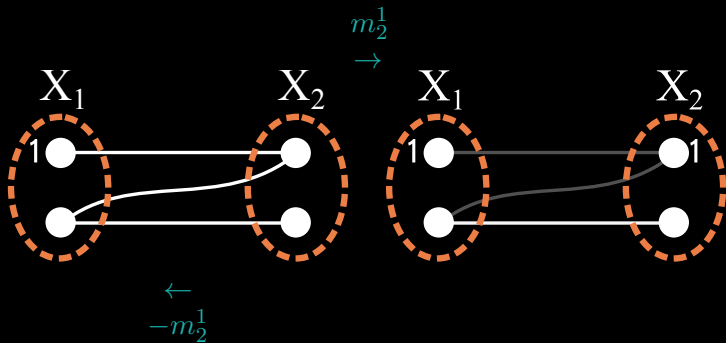
(Loss of) properties

Preserves equivalence but non-monotonic and fixpoints may be non unique (or may not exist)



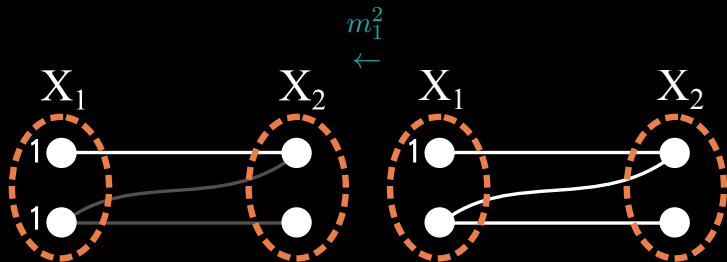
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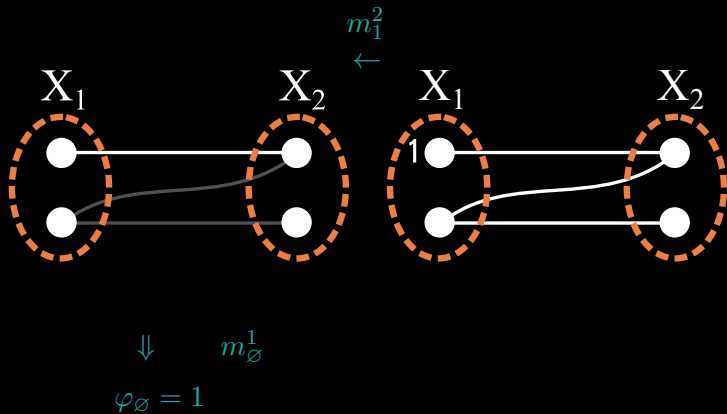
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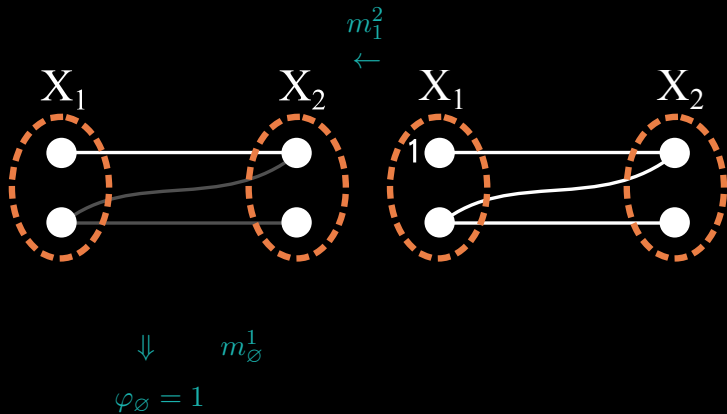
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## The many “soft ACs”

One paper to read: [Coo+10]

- NC+AC+DAC (FDAC): binary & unary (+ direction)[Sch00; Lar02; Coo03] Full Supports
- +Existential AC: EDAC, a star (variable incident functions) [Lar+05] EAC supports
- +Virtual AC: any spanning tree [Coo+08; Coo+10] VAC supports

## Supports provide value ordering heuristics

- EAC:  $\varphi_i(u) = 0$  can be extended for free on  $X_i$ 's star
- VAC:  $\varphi_i(u) = 0$  can be extended for free on any spanning tree [Kol06; Coo+08; Coo+10]

## NC provides reduced cost-based pruning (back-propagation)

If  $(\varphi_\emptyset \stackrel{k}{\neq} \varphi_i(u)) = k$ , NC deletes  $u$



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## Properties

- Proper extension of classical NC/DAC or AC respectively ( $k = 1$ )
- Polynomial time,  $O(ed)$  space (Generalized ACs)
- Incremental, strengthens  $\varphi_\emptyset$  ( $\text{NC} \leq \text{AC} \leq \text{FDAC} \leq \text{EDAC} \leq \text{VAC}$ )
- Stronger bounds than AC in COP [LL12]

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OSAC [Sch76; Co07; Wer07; Co0+10]

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# OPTIMAL SOFT ARC CONSISTENCY (OPTIMIZATION ALONE)

Variables for a binary CFN, no constraints [Sch76; Kos99; CGS07; Wer07; Coo+10]

1.  $u_i$ : amount of cost shifted from  $\varphi_i$  to  $\varphi_\emptyset$
2.  $p_{ija}$ : amount of cost shifted from  $\varphi_{ij}$  to  $\varphi_i(a)$
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## OSAC

$$\begin{aligned} \text{Maximize } & \sum_{i=1}^n u_i && \text{subject to} \\ & \varphi_i(a) - u_i + \sum_{(\varphi_{ij} \in C)} p_{ija} \geq 0 && \forall i \in \{1, \dots, n\}, \forall a \in D^i \\ & \varphi_{ij}(a, b) - p_{ija} - p_{jib} \geq 0 && \forall \varphi_{ij} \in C, \forall (a, b) \in D^{ij} \end{aligned}$$

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## Problems solved [Coo+10; KZ17]

- Tree-structured problems
- Permuted submodular problems (e.g. Min-Cut)

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- CFN Arc consistencies provide fast approximate LP bounds
- and deal with constraints seamlessly

## CFN Local Consistencies

Enhance CP with fast incremental approximate Linear Programming dual bounds

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- 3 All Toulbar2 bells and whistles
- 4 WCSP solving has made huge progress
- 5 Learning CFN from data

## Additional algorithmic ingredients

- Value ordering (for free): existential or virtual supports
- Variable ordering: weighted degree [Bou+04], last conflict [Lec+09], VAC-based [TKK20]
- (On the fly) variable elimination [Lar00]
- Dominance analysis (substitutability/DEE) [Fre91; Des+92; DPO13; All+14]
- Function decomposition [Fav+11]
- Some global cost functions (weighted Regular, All-Diff, Among...) [LL12; All+16]
- Incremental solving, guaranteed diverse solutions [Ruf+19]
- Unified (Parallel) Decomposition Guided VNS/LDS (UPDGVNS [Oua+20])

## More information

[github.com/toulbar2/toulbar2](https://github.com/toulbar2/toulbar2)

[miat.inrae.fr/toulbar2](https://miat.inrae.fr/toulbar2)

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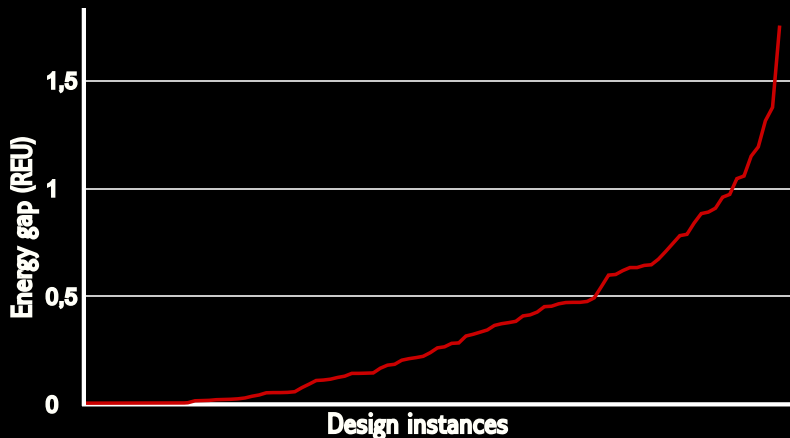
## CPLEX V12.4.0.0

```
Problem '3e4h.LP' read.  
Root relaxation solution time = 811.28 sec.  
...  
MIP - Integer optimal solution: Objective = 150023297067  
Solution time = 864.39 sec.
```

## tb2 and VAC

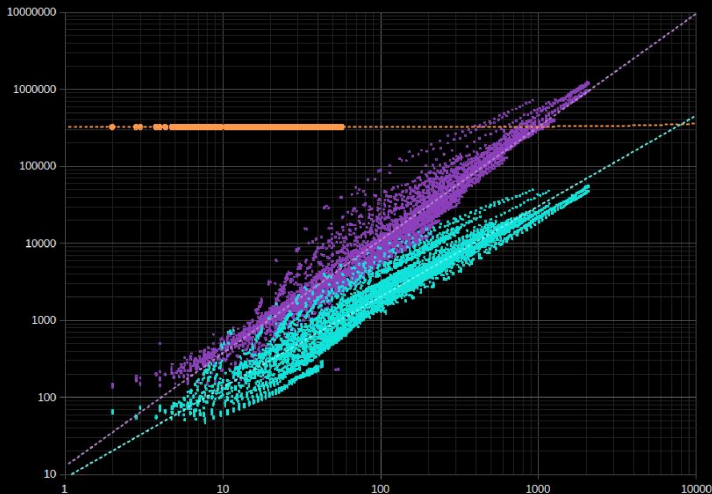
(AC3 based)

```
loading CFN file: 3e4h.wcsp  
Lb after VAC: 150023297067  
Preprocessing time: 9.13 seconds.  
Optimum: 150023297067 in 129 backtracks, 129 nodes and 9.38 seconds.
```



Optimality gap of the Simulated annealing solution as problems get harder

<sup>2</sup>David Simoncini et al. “Guaranteed Discrete Energy Optimization on Large Protein Design Problems”. In: *Journal of Chemical Theory and Computation* 11.12 (2015), pp. 5980–5989. doi: 10.1021/acs.jctc.5b00594.



DWave approximations

*kcal/mol*

gap > 1.16 90% of the time

> 4.35, 50% of the time

> 8.45, 10% of the time

### Kind words from Protein Designers<sup>3</sup>

The Toulbar[2] package for WCSPs significantly improved the state-of-the-art efficiency for protein design in the discrete pairwise model.

### Kind words from OpenGM2 developpers (image processing)

“ToulBar2 variants were superior to CPLEX variants in all our tests”<sup>4</sup>

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<sup>3</sup>Mark A Hallen and Bruce R Donald. “Protein design by provable algorithms”. In: *Communications of the ACM* 62.10 (2019), pp. 76–84.

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## Data mining, bioinformatics

Given a matrix of arbitrary real numbers, find a subset  $C$  of columns and  $R$  of rows such that the sum of numbers in the submatrix is maximized.

## Dedicated global constraint

Presented in [BSD17; Der+19], dominates MILP and MIQCP.

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```
def generate_model(path):
    m = pandas.read_csv(path, sep='\t', header=None)
    r, c = m.shape
    model = pytoulbar2.CFN(100000, 10, True)
    for i in range(r):
        model.AddVariable("R"+str(i), ["out", "in"])
    for j in range(c):
        model.AddVariable("C"+str(j), ["out", "in"])
    for i in range(r):
        for j in range(c):
            model.AddFunction(["R"+str(i), "C"+str(j)], [0.0, 0.0, 0.0, -m[j][i]])
    return model

(solution, , cost, _) = generate_model(sys.argv[1]).Solve()
```

## The Global Constraint author

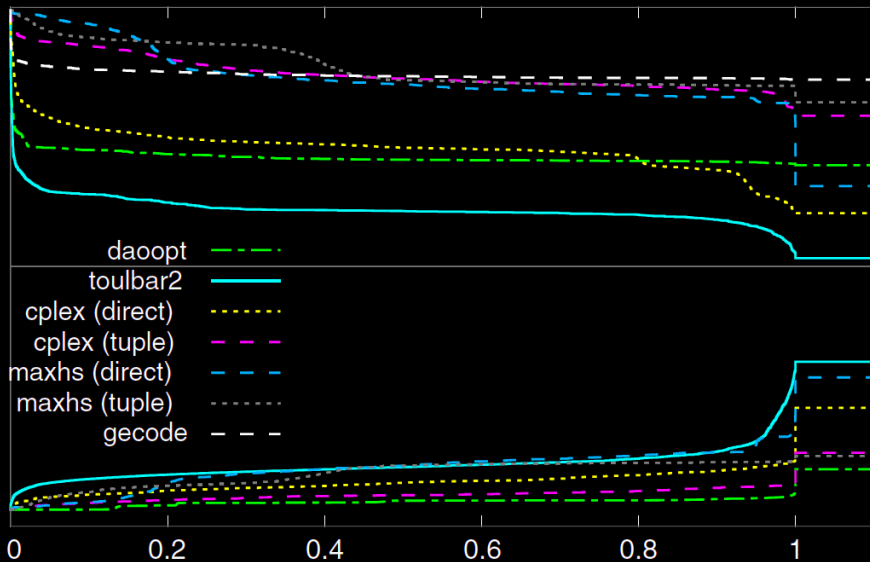
Je n'ai pas vraiment trouvé de cas [...] défavorable pour toulbar2.

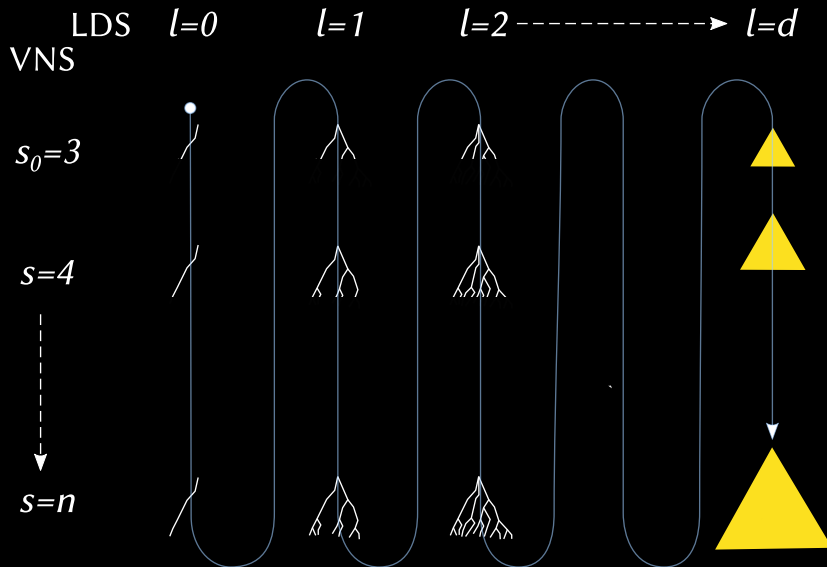
3026 instances of various origins

[genoweb.toulouse.inra.fr/~degivry/evalgm](http://genoweb.toulouse.inra.fr/~degivry/evalgm)

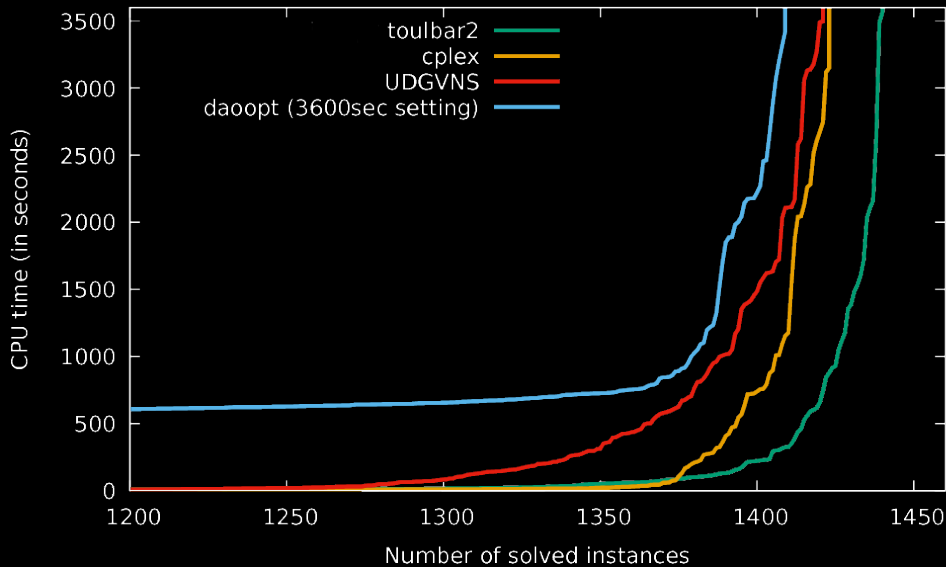
- MRF: Probabilistic Inference Challenge 2011
- CVPR: Computer Vision & Pattern Recognition OpenGM2
- CFN: Cost Function Library (CELAR, SPOT5, bioinformatics)
- MaxCSP: MaxCSP 2008 competition
- WPMS: Weighted Partial MaxSAT evaluation 2013
- CP: MiniZinc challenge 2012/13 (decomposable)

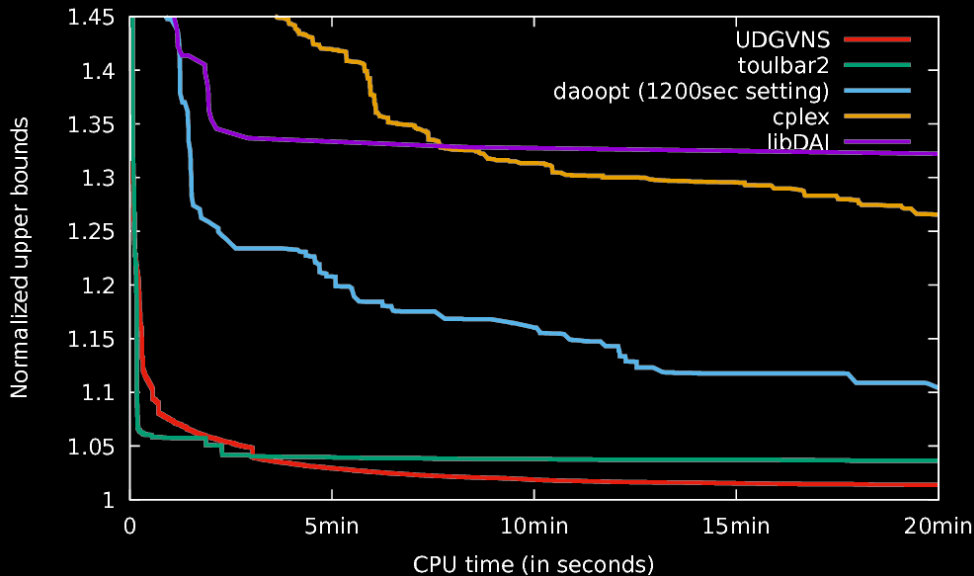
Benchmark	Nb.	UAI	WCSP	LP(direct)	LP(tuple)	WCNF(direct)	WCNF(tuple)	MINIZINC
MRF	319	187MB	475MB	2.4G	2.0GB	518MB	2.9GB	473MB
CVPR	1461	430MB	557MB	9.8GB	11GB	3.0GB	15GB	N/A
CFN	281	43MB	122MB	300MB	3.5GB	389MB	5.7GB	69MB
MaxCSP	503	13MB	24MB	311MB	660MB	73MB	999MB	29MB
WPMS	427	N/A	387MB	433MB	N/A	717MB	N/A	631MB
CP	35	7.5MB	597MB	499MB	1.2GB	378MB	1.9GB	21KB
<b>Total</b>	<b>3026</b>	<b>0.68G</b>	<b>2.2G</b>	<b>14G</b>	<b>18G</b>	<b>5G</b>	<b>27G</b>	<b>1.2G</b>

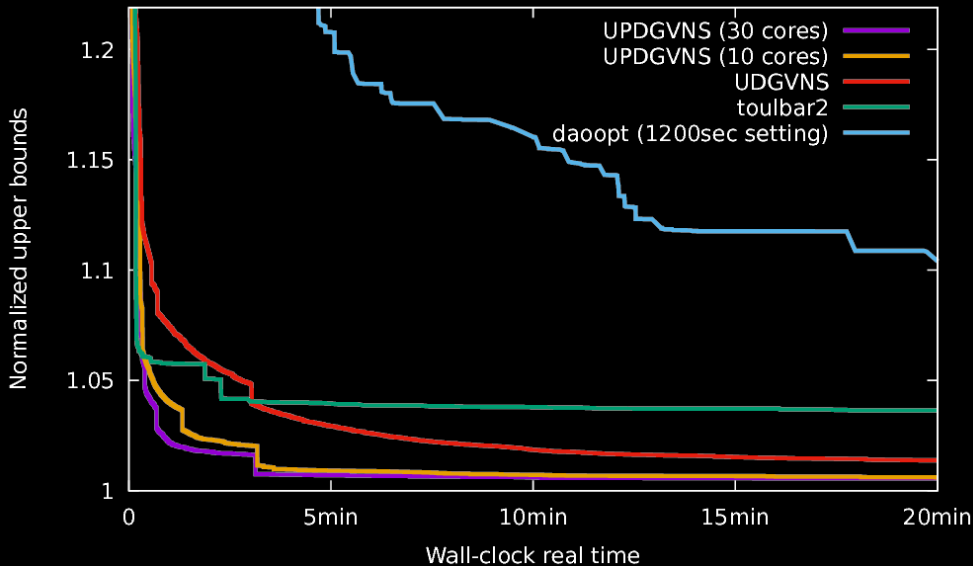












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### Definition (Learning a pairwise CFN from high quality solutions)

Given:

- a set of variables  $V$ ,
- a set of assignments  $E$  i.i.d. from an unknown distribution of high-quality solutions

Find a pairwise CFN  $\mathcal{M}$  that can be solved to produce high-quality solutions

# WHAT DOES LEARNING A CFN MEANS EXACTLY?

We use the language of pairwise tensors/tables

- There are at most  $\frac{n(n-1)}{2}$  pairwise functions  $\frac{81 \times 80}{2} = 3240$
- Each with  $|D^i| \times |D^j|$  costs in  $\mathbb{R}$  (differentiability) 81
- For the Sudoku, 262,440 parameters to learn.

## Maximum likelihood estimation

- $E$  a set of i.i.d. assignments of  $V$
- Interpret costs as energies ( $\propto -\log(\text{probabilities})$ )
- Maximize the probability of observing the samples in  $E$

## Maximum loglikelihood $\mathcal{M}$ on $\mathcal{M}_\ell$

$$\begin{aligned}
 \mathcal{L}(\mathcal{M}, E) &= \log\left(\prod_{v \in E} P_{\mathcal{M}}(v)\right) = \sum_{v \in E} \log(P_{\mathcal{M}}(v)) \\
 &= \sum_{v \in E} \log(\Phi_{\mathcal{M}}(v)) - \log(Z_{\mathcal{M}}) \\
 &= \underbrace{\sum_{v \in E} (-C_{\mathcal{M}^\ell}(v))}_{\text{-costs of } E \text{ samples}} - \underbrace{\log\left(\sum_{t \in \prod X \in V D^X} \exp(-C_{\mathcal{M}^\ell}(t))\right)}_{\text{Soft-Min of all assignment costs}}
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## Algorithms and data-sets

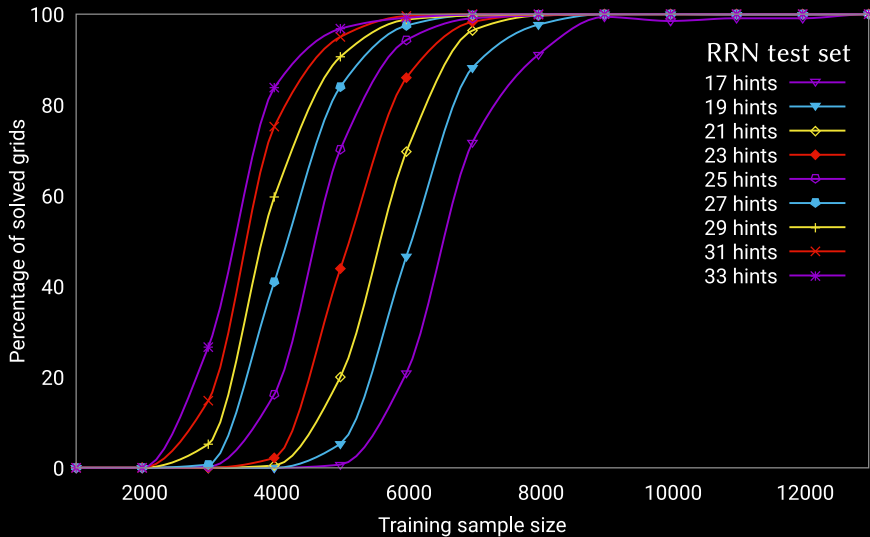
- PE-MRF [Par+17] with L1-norm Regularization
- Validation set from the SAT-Net paper<sup>5</sup> (36.2 hints)
- Validation set from the RRN paper<sup>6</sup> with 17-34 hints.

---

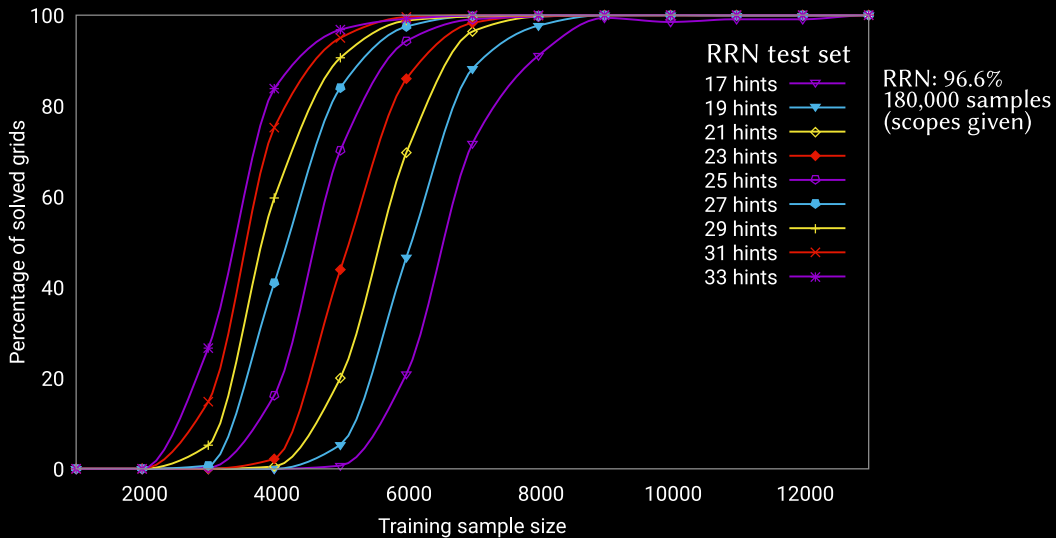
<sup>5</sup>Po-Wei Wang et al. “SATNet: Bridging deep learning and logical reasoning using a differentiable satisfiability solver”. In: *ICML '19 proceedings, arXiv preprint arXiv:1905.12149*. 2019.

<sup>6</sup>Rasmus Palm, Ulrich Paquet, and Ole Winther. “Recurrent relational networks”. In: *Advances in Neural Information Processing Systems*. 2018, pp. 3368–3378.

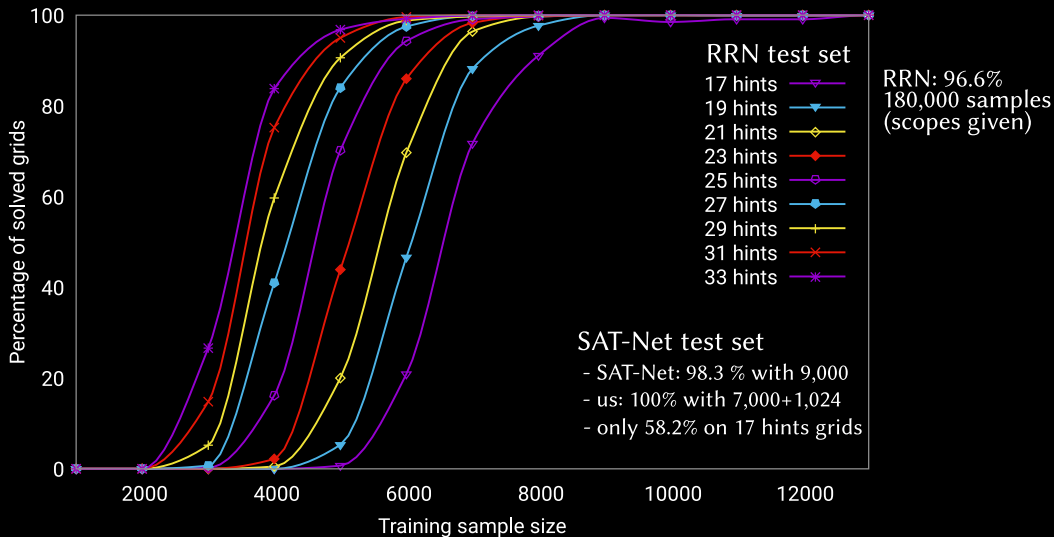
# LEARNING HOW TO SOLVE THE SUDOKU



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## Learning from uncertain DL output is possible

- LeNet has 99.2% accuracy on handwritten digits
- Argmax decoding: 74.7% of the learning data-set would be incorrect
- Important to accept probabilistic information as input (PE-MRF)

## Comparing with SAT-Net

- SAT-Net (9,000 samples): .....63.2%
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## NOT ONLY SUDOKUS OF COURSE...

See our CP2020 paper<sup>7</sup>

We show how it can learn user preferences and combine them with configuration constraints on Renault dataset (thanks to H. Fargier (IRIT)).

---

<sup>7</sup>Céline Brouard, Simon de Givry, and Thomas Schiex. “Pushing data into CP models using Graphical Model Learning and Solving”. In: *Principles and Practice of Constraint Programming–CP 2020*. Springer, 2020.

## CFN/WCSP solving has made important progress

- Fast approximate LP-bounds (tighter than COP) subsuming AC
- Free value ordering heuristics
- Reduced-cost-based filtering (cost backpropagation)
- Structure aware search with improving optimality gap

## CFN can be learned from data and combined with constraints

- Shares with ILP the capacity of dealing with fine grained numerical information
- Tractable learning with probabilistic input (DL/ML connection)
- With the (adjustable) power of (exact) solvers



## Directions for improvement

- Global cost function and non monotonicity
- Interval variables and “arithmetic” filtering
- Unify CFN and COP: cost variables, multiple criteria
- Stronger incremental bounds
- Parallel search, conflict learning
- Try to minimize average tardiness in scheduling
- Improve CFN learning (sample size, (global) constraints)
- ...

THANK YOU ALL FOR YOUR ATTENTION!

And to all CFN/toulbar2 contributors

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M. Sanchez (PostDoc)	E. Rollon (UPC, Spain)	P. Meseguer (CSIC, Spain)
G. Verfaillie (ONERA, ret.)	JH. Lee (CU. Hong Kong)	C. Bessiere (LIMM, Montpellier)
JP. Métivier (GREYC, Caen)	S. Loudni (GREYC, Caen)	M. Fontaine (GREYC, Caen)
D. Simoncini (PostDoc, UT1)	C. Viricel (PhD)	C. Terrioux (LSIS)
P. Jégou (LSIS)	A. Ouali (GREYC)	Y. Lebbah (GREYC)
L. Loukil (GREYC)	P. Boizumault (GREYC)	Mario (CU. Hong-Kong)
M. Lemaître (CERT)	L. Lobjois (CERT)	B. Hurley (Insight)
B. Neveu (INRIA, Sophia)	G. Trombettoni (INRIA)	...

Questions?

- [ALL+14] David Allouche et al. “Computational protein design as an optimization problem”. In: *Artificial Intelligence* 212 (2014), pp. 59–79.
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