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Multicriteria assessment of conservation agriculture systems

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Conservation agriculture (CA) relies on three fundamental and inseparable pillars: no soil disturbance, diversified crop rotations, and permanent soil cover. Nevertheless, few studies have evaluated the interactive effect of these three fundamental pillars on a multicriteria basis. Here, we mobilize data from the French AGROSYST database, which gathers all farming practices and performances of the 3000 farms involved in the French DEPHY farmers' network. Linear mixed effect models were used to compare the performance (13 indicators) of CA (CAs, N=36) and pseudo-CA systems (pseudo-CAs, N=19, allowing one occasional superficial tillage) to conventional tillage (plowed, CTs, N=135) and superficial tillage (STs, N=90) based systems in similar production situations (climate, soil type, presence of livestock or irrigation, etc.). CAs required (compared to STs and CTs, respectively) more herbicides (+27 and +90%) but slightly less insecticides (-64 and -50%, non-significant), decreased time of traction/ha/year (-25 and -32%), fuel consumption (-21 and -39%), as well as mechanization costs (-20 and -26%), tended to slightly decrease profitability/ha (-7 and -19%, non-significant) due to slightly lower productivity (-19% and -25%) but resulted in better profitability per hour of field traction (+23% and +18%). Pseudo-CAs did not implement the three CA principles since crop rotation were as diverse and cover crop as frequent as in STs and CTs, and tillage occurred, albeit rarely. However, pseudo-CAs used less insecticides (-92 and -83% compared to STs and CTs, respectively), decreased fuel consumption (-25% compared to CTs), and resulted in similar productivity and economic profitability (per hectare and per hour of field traction). Further investigation is required to identify the diversity of responses across production situations, the determinants of multi-performance in given production situations, and to track down the rare innovative systems optimizing multiple performances and solving apparent trade-offs.

KEYWORDS

no-till, direct seeding, cover crop, tillage, crop diversification, cropping system, pesticide use, sustainability

1 Introduction

Agriculture must meet the challenges of producing in quantity and quality, without harmful effects on the environment and human health, while providing suitable revenues for farmers. Agroecological systems aim to reach these objectives through the enhanced mobilization of biological and ecological processes that contribute to crop production (Gliessman et al., 1998; Wezel et al., 2009). Among these agroecological systems, conservation agriculture (CA) places strong emphasis on no-till, permanent soil cover, and diversified crop rotations. The simultaneous implantation of these three pillars of CA contributes to the delivery of multiple ecosystem services (Hobbs et al., 2008; Chabert and Sarthou, 2020). Initiated in the United States in the 1950s, in Europe in the 1960s, then in Latin America in the 1970s (Derpsch, 1998), soil conservation techniques rapidly evolved towards CA with the development of direct seed drills and non-selective, effective and cheap foliar herbicides (aminotriazole, paraquat, glyphosate and glufosinate). Decades after its development by pioneer farmers, CA acreage is increasing exponentially worldwide (Kassam et al., 2019), although very few studies have assessed its performances on a multicriteria basis, including environmental, economic and societal aspects (Craheix et al., 2016). According to Kassam et al. (2019), the adoption of CA has increased because farmers are seeking for a new paradigm to sustainably intensify crop production. They also report that the major drivers which explain the adoption of CA continue to be “the need to increase input factor productivity, yield and total farm output, improved sustainability of production and farm land, better incomes, timeliness of cropping practices, ease of farming and reduction in drudgery, and improved ecosystem services such as clean water, control of erosion and land degradation, carbon sequestration, cleaner atmosphere and the rehabilitation of degraded agricultural lands”. Although some ecosystem services are targeted by farmers adopting CA, they remain to be assessed and quantified. Our systematic review of the scientific literature revealed the existence of 9 meta-analyses where CA systems (*i.e.* implementing simultaneously the three pillars) were compared to reference systems – the latter being different according to studies. These meta-analyses concerned yield (Rusinamhodzi, 2015; Corbeels et al., 2020; Jat et al., 2020; Reich et al., 2021), water use efficiency (Jat et al., 2020), economic sustainability (Jat et al., 2020; Reich et al., 2021), food security (Reich et al., 2021), carbon sequestration (Powlson et al., 2016; Mondal et al., 2020; Dong et al., 2021; Nicoloso and Rice, 2021; Reich et al., 2021), greenhouse gas emission (Zhao et al., 2016; Jat et al., 2020) and soil quality and fertility (Mondal et al., 2020; Nicoloso and Rice, 2021; Reich et al., 2021). They highlight that the effects of CA systems on crop productivity and soil health (carbon sequestration, soil quality, soil structure, soil biological activity) were extensively studied at the expense of other dimensions of cropping system sustainability.

CA systems combine a diverse set of farming practices, which may evolve as the system matures (Derrouch et al., 2020). Stopping tillage (both primary and secondary tillage operations, such as plowing, stubble cultivation, false seed bed practices, mechanical weeding, etc.) reduces traction time and fuel consumption (West and Marland, 2002; Kertész and Madarász, 2014). However, not all crops are suitable for direct seeding (*e.g.* industrial crops such as sugar beet or potato), still requiring shallow tillage for their establishment (*e.g.* ridging), and their abandonment may have severe economic consequences for farmers. Moreover, the implementation of the three pillars of CA and in particular stopping tillage can have negative consequences on crop productivity (Pittelkow et al., 2015), at least in the short term, when cash crop sowing dates/rates, fertilization, and herbicides are not optimized for untilled soil conditions (El-Gizawy, 2009). Nevertheless, the relative performance of CA systems, compared to tillage-based systems, could vary across production situations as studies have also reported positive effects on crop productivity (Scopel et al., 2013; Jat et al., 2020).

In addition, CA systems also face problems in managing weeds (Derrouch et al., 2020), which are no longer regulated by tillage. The set of non-chemical weed management tools is more limited in CA than in tillage-based systems and this is usually reflected by an increase in herbicide use after adoption of CA (Adeux et al., 2019; Derrouch et al., 2020). No-till is expected to reduce weed abundance because weed seeds are maintained on the soil surface, a condition deemed unfavorable to weed seed germination, but this appears to be true only for a restricted set of species (Cordeau et al., 2015). On the other hand, cover crops can suppress weeds through enhanced competition (Osipitan et al., 2019; Smith et al., 2020) and crop diversification can reduce weed abundance through a diversification of selection pressures (Weisberger et al., 2019). CA farmers often claim a decrease in insecticide use in CA, which they explain by the diversity of crops in the rotation and the use of companion plants to limit insect damages (Cadoux et al., 2015). They also report a decrease in fungicide use, which could be explained by the presence of mulch on the soil surface. According to Mulumba and Lal (2008), mulch increases soil water capacity by 18-35% and soil moisture retention from 29 to 70%, conditions deemed to enhance growth and spore germination of fungi. However, mulch also prevents soil particles from being splashed on the crop when rainfall occurs (McCalla and Army, 1961), and hence limits the splash dispersal of inoculum responsible for initial contamination (Teasdale et al., 2002).

Numerous studies have quantified the effect of one of the three pillars of CA, *e.g.* on soil properties (Blanco-Canqui and Wortmann, 2020), carbon sequestration (Powlson et al., 2014), greenhouse gas emissions (Rochette, 2008), belowground diversity and activity (Rincon-Florez et al., 2016) or crop productivity (Pittelkow et al., 2015; Jat et al., 2020). Some studies assessed cropping systems when conservation-agriculture component practices were implemented either separately or in tandem (Craheix et al., 2016; Jat et al., 2020). However, very few studies have evaluated, on a multi-criteria basis, CA systems implementing simultaneously the three

fundamental pillars, (Craheix et al., 2016; Chabert and Sarthou, 2020; Jat et al., 2020) when they are combined into a true CA system (Reicosky, 2015; FAO, 2021). A study using the MASC multi-criteria evaluation tool showed that reducing tillage tended to reduce overall cropping system performance, unless it was combined with crop diversification (Craheix et al., 2016). Such results demonstrate that CA must be seen, studied and quantified as a system that jointly and simultaneously implements the three pillars (Reicosky, 2015). A recent study compared direct seeding systems (CA) to conventional- and reduced-tillage systems and concluded that, despite a high variability in the expression of ecosystem services, provisioning of ecosystem services remained high in CA and that time since conversion drove the delivery of many services (Chabert and Sarthou, 2020). Time since conversion drove performances because farmers take time before finding their own locally adapted combination of practices within the framework of CA and its three pillars (Derrouch et al., 2020). For instance, time is needed to adapt the crop rotation (cash crops, companion crops, cover crops, intercropping, relay-cropping, etc.) and to strictly stop tillage, which may result in occasional shallow tillage operations. In addition, it is not excluded that CA farmers may face high pest pressures such as slugs (Scaccini et al., 2020), voles (Ruscoe et al., 2022) and/or weeds (Derrouch et al., 2021), forcing them to contain these issues with occasional shallow tillage operations, hereafter called pseudo-CA. Therefore, the performances of CA and pseudo-CA systems, relative to reference systems which rely on conventional (*i.e.* plowing) or superficial tillage in the same production context and from a multi-criteria perspective, remains unclear.

The objective of this study is to assess the economic and environmental performances of CA and pseudo-CA systems, using data from the French DEPHY farm network, a network set up in the early 2010s and made up of 3000 volunteer farmers motivated about pesticide reduction (Lechenet et al., 2016; Lechenet et al., 2017b), albeit without negatively impacting their income. Based on detailed descriptions of the farmers' cropping systems, we identified 36 CA and 19 pseudo-CA systems (named hereafter CAs and pseudo-CAs, respectively) and assessed their multiperformance (13 indicators). They were compared to conventional- and superficial tillage-based systems (named hereafter CTs and STs, respectively) located in the same production situation (defined by similar climate, soil type characteristics and the presence of livestock or irrigation).

2 Material and methods

2.1 The DEPHY network and available data

The DEPHY farm network was set up as part of the ECOPHYTO national action plan in 2010. Two years later, the

network gathered 1900 farms and a new extension phase in 2016 allowed to reach a total of 3000 farms, with over half represented by arable crops or arable crops and livestock. The network is made up of volunteer farmers who are motivated in reducing pesticide use, albeit without negative financial consequences. The network is structured in groups of 10 to 15 farms, geographically close to each other, and led by a crop advisor whom assists farmers in redesigning their pest management strategies. The farming practices are monitored and gathered in the AGROSYST database (Ancelet et al., 2014), and include crop rotation and detailed practices implemented in each crop. The description of farming practices is done either at the plot level with multiple plots per combination of cropping system and farm, or in a more synthetic way. For the latter, the description of the crop rotation and management practices associated to each of its component represents an average of several plots (for a given year or across multiple years), obtained by farmers' questionnaires. Such descriptions are hence supposed to incorporate temporal and spatial variability of farming practices.

For this work, both data sources were used (*i.e.* plot and synthetic descriptions) to characterize cropping systems (see details in Supplementary Tables S1, S2), and compute multiple indicators of performance at the cropping system level, hence considering all the plots of the cropping system whatever the data source – plot or synthetic description – therefore avoiding any bias due to the data source in the computed indicators. The computation of the indicators was done over a three-year period to smoothen potential inter-annual variability due to climatic conditions. In rare cases, a cropping system was described with data collected a given year, but multiple fields were described to ensure the description of the whole cropping system (*i.e.* 6 fields a given year to describe a 6-year rotation). Moreover, CAs and pseudo-CAs were compared with their reference CTs and STs (see section 2.3) over the same time frame (to the best of our ability, see details in Supplementary Tables S1, S2, and at the end of section 2.3), because annual weather conditions influence both pest pressure and crop productivity.

2.2 Identification of CA and pseudo-CA systems

Preliminary analysis of tillage practices identified 36 strict no-till cropping systems (CAs), *i.e.* without any tillage intervention in three successive years on all corresponding plots, and 19 cropping systems with no deep tillage intervention and maximum one shallow tillage (*i.e.* <10cm depth) intervention per plot (or set of plots for the synthetic description) per year across the three-year period (pseudo-CAs). Rolling interventions (regardless of the type of roller) were not considered as tillage interventions. When cropping systems were described over periods longer than 3 years and no change in tillage strategy was identified, only the three most recent years

were retained for analysis, in order to maximize the chances of characterizing systems that passed the initial transition phase, during which practices are known not to be optimal (Derrouch et al., 2020).

The CAs identified were mainly located in the regions Poitou-Charentes, Centre, Bourgogne Franche-Comté and Lorraine, *i.e.* regions with mainly shallow calcareous-clay soils and limited yield potential (Schauberger et al., 2018; Schils et al., 2018), and a few systems in the deeper soils of the Paris basin, Normandy and the South-West (Figure 1). Pseudo-CAs were in the same regions, with the addition of three systems in the South East of France. These systems were located in the major arable regions of France where CA is practiced (Laurent, 2015).

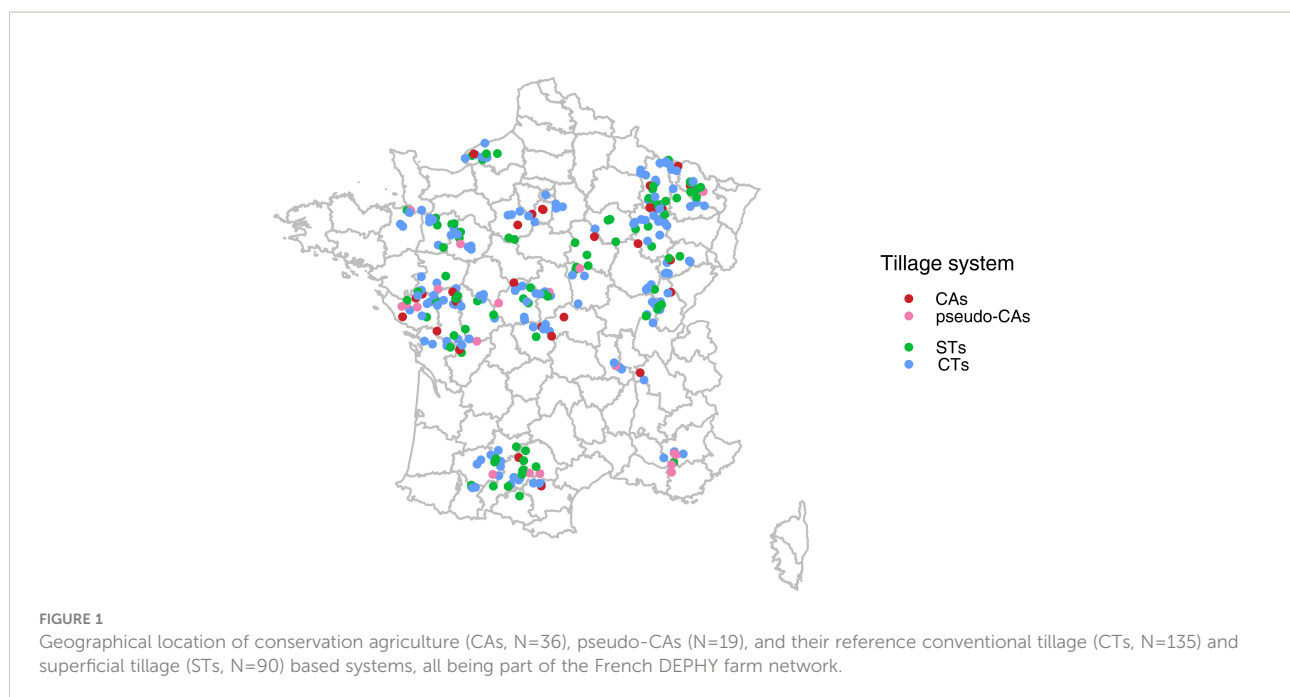
2.3 Identification of reference systems

In order to optimize the comparison of systems in similar production situations (*i.e.* pedo-climatic and economic constraints which go beyond farmers' strategic decisions), reference CTs and STs were searched according to the following rules:

- Similar climate: for each focus CAs or pseudo-CAs, we searched for CTs and STs within a geographical radius of 50 km. This rule not only ensured that the systems were compared in a rather similar climate, even if it is known that rainfall can be more localized, but also maximized the probability of the same socio-technical context (*e.g.* proximity to a sugar factory or other

industry offering outlets for specific crops: beet, field vegetables, etc.).

- Similar soil type: as information on soil type is poorly informed in the AGROSYST database, we approximated soil type of each system on the basis of the French soil map (Inra, 2018). This French soil database indicates soil typological units (STU) that can be mapped. By intersecting the geographical positions of the systems and the map of soils on a GIS tool, we assigned to each cropping system the most frequent soil type of the city where the farm is located. Only CTs and STs sharing similar soil types with each focus CAs or pseudo-CAs were retained (within the previously established 50km radius).
- Similar years: the same three years were used to describe the focus CAs and pseudo-CAs and their reference CTs and STs (to the best of our ability, see details in Supplementary Tables S1, S2), to maximize the chances that climatic conditions and pest pressures were similar.
- As the presence of livestock on the farm greatly determines practices (Lechenet et al., 2016), focus CAs and pseudo-CAs were only compared with CTs and STs in similar farming contexts (grain-based only or grain-based/livestock mixed farming).
- As access to irrigation is a major driver of performance (*e.g.* increased productivity and/or production costs, possibility to grow certain crops), only CTs and STs with similar access to irrigation (yes/no) to the focus CAs or pseudo-CAs were retained.



- When possible, *i.e.* number of CTs or STs > 6 in the same production situation of the focus CAs or pseudo-CAs, a second filter based on distance was applied in order to keep only the six closest CTs and STs meeting all the other previous conditions.

On the basis of these context variables, we identified clusters of cropping systems sharing the same production situation, with each cluster being composed of a focus CAs or pseudo-CAs and their reference CTs and STs (*i.e.* similar climate, soil type, time frame of description, livestock context, access to irrigation). In a few rare cases, CAs or pseudo-CAs were geographically close and therefore were compared to the same CTs and STs. Each ‘cluster’ therefore comprises one to two CAs (number of clusters with 2 CAs = 3) or pseudo-CAs (number of clusters with 2 pseudo-CAs = 1) and from 0 to 6 reference CTs (on average 3.3 for the comparison with CAs and 3.7 for the comparison with pseudo-CAs) and from 0 to 6 STs (on average 1.8 for the comparison with CAs and 1.9 for the comparison with pseudo-CAs). Thus, a total of 36 CAs or 19 pseudo-CAs were compared to a total 135 CTs and 90 STs, split into 33 and 18 clusters for CAs and pseudo-CAs, respectively (Supplementary Tables 1, 2). The statistical analysis (see details below) allowed us to distinguish the “cluster” effect (*i.e.* effect of soil, climate and socio-technical context) from the effect of farming strategy (*i.e.* CTs, STs, CAs and pseudo-CAs) on each of the indicators considered.

A sub dataset comprising only cropping systems described across common years in a given cluster was also created to explore whether the results were sensible to the inclusion of reference cropping systems described over a slightly different time period.

2.4 Indicators of cropping systems’ performances

Data was extracted from the AGROSYST database, which provides information on crop identity and their order of succession, the sequence of interventions associated to each crop (from harvest of the previous crop to harvest of the studied crop), equipment, inputs (pesticide, fertilizer, seeds, irrigation etc.), dates and doses of application, and crop yield. Then, AGROSYST automatically computes several indicators of performance. In this study, we focused on two types of indicators:

- Indicators which aimed at verifying whether CA and pseudo-CA systems, initially identified based on tillage strategy, actually implemented the other two pillars of CA, *i.e.* crop diversification and permanent soil cover. For each system (CAs, pseudo-CAs, CTs, STs), we calculated the number of different crops in the

rotation (two crops grown and harvested one after another in a given year were counted as 2) and the frequency of summer fallow cover crops. When cropping systems were described through the plot approach, these two indicators were calculated as the average described over the three years of monitoring and for all plots. When the number of plots:years was less than 9 (*i.e.* less than 3 plots described each year), the indicators were not calculated.

- Technical-economic and environmental performance indicators, calculated at the cropping system scale (average of each component of crop rotation). The indicators calculated by AGROSYST were:

The Treatment Frequency Index [TFI, average number of doses at the recommended dose per ha (Gravesen, 2003)], and its different components: total TFI (including seed treatment), Herbicide-TFI, Fungicide-TFI and Insecticide-TFI. It is commonly used in Europe to assess cropping system reliance to pesticides (OECD, 2001; Strehlow et al., 2020). A pesticide application at the reference dose over the whole plot surface yields a value of 1. AGROSYST computes TFI using two different methods: TFI “at crop” for which the reference dose is defined for each combination of commercial product and crop, and TFI “at pest target” for which the reference dose is defined for each combination of commercial product, crop and pest target. For instance, glyphosate is an active ingredient present in many herbicides whose homologated doses depend on the target weed (either annual or perennial weed species). Pearson’s product moment correlation between TFI resulting from both methods were tested (Supplementary Table S3). Furthermore, herbicide TFI was partitioned into glyphosate TFI and herbicide TFI without glyphosate, using the open database of the French E-Phy catalog of plant protection products (ANSES, 2021) to quantify the reliance of systems to this active compound (Antier et al., 2020).

Mechanized work time (h/ha/year), was calculated by AGROSYST using a national reference database (Walter, 2020), according to the work rate of the tools used for each mechanized intervention listed in a given cropping system, accounting for combined operations.

Fuel consumption (L/ha/year), was computed by AGROSYST using a national reference database (Walter, 2020), as a function of the work rate of the equipment, but also of the traction power and the load rate, according to the method recommended by the APCA – Chambres d’Agriculture France (2020).

Economic indicators were also computed: gross product (€/ha/year), operating costs (€/ha/year), mechanization costs (€/ha/year), semi-net margin (€/ha/year, calculated as

gross product – operating costs – mechanization costs) and semi-net margin per hour of field traction (€/h/ha/year). Crop productivity was compared based on winter wheat grain yield (t/ha) as winter wheat was a crop shared by the vast majority of cropping systems. These indicators were calculated by AGROSYST on the basis of 10 price scenarios reflecting price volatility (agricultural products, fertilizers and fuels) between 2005 and 2017. The indicators were calculated for each price scenario and then averaged, which makes it possible to compare the economic performance of cropping systems that were not characterized over the same years.

2.5 Statistical analysis

All response variables presented above were analysed for the four datasets separately (CAs and pseudo-CAs, full dataset or sub dataset comprising only cropping systems described across the exact same time frame within a cluster) with linear mixed models, using the `lme()` function of the R package `{nlme}` (Pinheiro et al., 2017). These models integrated a fixed part (farming strategy, a 3-level factor, *i.e.* CAs/CTs/STs or pseudo-CAs/CTs/STs) and a random part that accounted for the structure of the data (the cluster effect accounting for the production situation effect). This procedure amounts to generalizing a paired t-test (intra cluster comparison) for more than 2 groups, with data for each combination of cluster:farming strategy averaged at the cluster level.

To account for intrinsic variability of performances within each farming strategy and meet one the prerequisites of ANOVA (*i.e.* homoscedasticity of residuals), variance structures were added to the model when required (Pinheiro and Bates, 2006; Zuur et al., 2009). Models with farming strategy as fixed factor and cluster as random effect, differing only by the inclusion or not of a variance structure (*i.e.* `weights=varIdent(form=~1|farming_strategy)`), were compared *via* a likelihood ratio test. The most likely model was retained, re-fitted by restricted maximum likelihood, and then subjected to an analysis of variance in order to test the ‘farming strategy’ fixed effect (F-test).

Contrasts between farming strategies were adjusted using the `{emmeans}` package (Lenth, 2019). The marginal effect of farming strategy is highlighted by least squares means. The coefficient of determination (R^2), indicating the proportion of variance explained by the statistical model, is also presented as a diagnostic tool. For mixed models, it is divided into R^2_m (the proportion of variance explained by the fixed effects, farming strategy), and R^2_c (the proportion of variance explained by the whole model, fixed + random effects). All variables (except for intercrop frequency and semi-net margin) were log transformed.

3 Results

3.1 Multicriteria performance of CA systems

3.1.1 Compliance with CA pillars

With an average of 5.1 crops in the rotation (Table 1; Figure 2), CAs were significantly more diversified than their reference CTs (4.3) or STs (4.4). However, only the difference between CAs and CTs remained significant when the sub dataset comprising only common years was used (Supplementary Table S4). Frequency of fallow cover crops was also significantly greater in CAs than in reference systems (Table 1; Figure 2). Focusing on the sub dataset comprising only common years yielded a similar ranking among farming strategies but no significant farming strategy effect or significant differences between treatments were revealed (Supplementary Table S4). Overall, strict no-till was accompanied by the implementation of the other two CA pillars (Table 1), *i.e.* crop diversification and soil cover, although some systems deviated from this general trend, with less crops and/or cover crops than CTs and STs of the same cluster (Figure 2).

3.1.2 Pesticide use

Results were very similar whether TFI was computed using the ‘at crop’ or ‘at pest target’ methods (see Table 1 for values ‘at pest target’, Supplementary Table S5 for values ‘at the crop’ method, and Supplementary Table 3 for correlations between both methods). Total TFI (Figure 3) of CAs was not different from that of STs, but higher (significant difference, +52% ‘at the pest target’ TFI method) than that of CTs (Table 1). However, only the difference between CAs and CTs remained significant when focusing on the sub dataset comprising only common years (Supplementary Table S4). The difference was mainly explained by higher herbicide use in CAs than CTs (+0.9 herbicide TFI point, +90%, Table 1 and Figure 3) and STs (+0.4 herbicide TFI point, +27%, only in the case of the full dataset, Supplementary Table S4). Few CAs resorted to less herbicides than STs (up to -2 herbicide TFI points) and CTs (up to -0.8 herbicide TFI points) of the same cluster. CAs relied more on the use of glyphosate (0.26 glyphosate TFI point, Table 1) than STs and CTs, but glyphosate use was overall low (Figure 3). Herbicide TFI without glyphosate was similar in CAs and STs but higher than in CTs (Table 1 and Figure 3). However, only the difference between CAs and CTs remained significant when focusing on the sub dataset comprising only common years (Supplementary Table S4). There was a trend towards lower insecticide use in CAs (Figure 3) compared to STs (-64%) and CTs (-50%), but the difference was not significant (Table 1). Fungicide use was similar between the three types of systems (Table 1 and Figure 3).

TABLE 1 Comparison of indicators between conservation agriculture systems (CAs) and their reference conventional tillage (CTs) and superficial tillage (STs) based systems, while accounting for production situation effects.

Indicators	nb cluster (max = 33)	numDF	denDF	F	p- value	Farming strategy						R ² m [‡]	R ² c [‡]
						CAs		STs		CTs			
						n (max = 36)	Mean (se)	n (max = 58)	Mean (se)	n (max = 109)	Mean (se)		
Number of crops (including secondary crops)	33	2	163	3.87	0.0230	36	5.1 (0.3) a	56	4.4 (0.2) b	106	4.3 (0.2) b	0.03	0.28
Frequency of occurrence of cover crops	33	2	163	3.09	0.0034	36	0.21 (0.04) a	56	0.12 (0.03) b	106	0.13 (0.02) b	0.02	0.18
Total TFI	33	2	163	3.63	0.0287	36	3.2 (0.3) a	57	3.0 (0.3) a	105	2.1 (0.3) b	0.09	0.63
Herbicide TFI	33	2	163	11.86	<0.0001	36	1.9 (0.1) a	57	1.5 (0.1) b	105	1.0 (0.1) c	0.26	0.65
Glyphosate TFI	28	2	122	74.94	<0.0001	30	0.26 (0.02) a	36	0.06 (0.02) b	86	0.01 (0.00) c	0.84	0.84
Herbicide w/o Glyphosate	28	2	122	7.79	0.0007	30	1.58 (0.13) a	36	1.36 (0.16) a	86	0.88 (0.14) b	0.26	0.83
Insecticide TFI	33	2	163	1.86	0.1583	36	0.05 (0.03) a	57	0.14 (0.05) a	105	0.1 (0.05) a	0.02	NA
Fungicide TFI	33	2	163	0.01	0.9949	36	0.5 (0.1) a	57	0.5 (0.1) a	105	0.5 (0.1) a	0.00	0.36
Field traction time (h/ha/year)	26	2	111	5.32	0.0062	29	3.0 (0.3) b	44	4.0 (0.3) a	66	4.4 (0.3) a	0.07	0.11
Fuel consumption (L/ha/year)	24	2	111	13.04	<0.0001	27	56.9 (5.2) c	43	72.1 (5.7) b	67	93.6 (6.3) a	0.15	0.27
Gross product (€/ha/year)	25	2	109	10.82	<0.0001	28	807 (46.6) b	39	994 (52.6) a	69	1082 (46.6) a	0.12	0.27
Winter wheat yield (t/ha)	27	2	124	5.43	0.0055	30	6.24 (2.67) b	43	7.14 (2.39) b	80	6.98 (1.88) b	0.07	NA
Mechanization costs (€/ha/year)	25	2	118	10.35	<0.0001	28	212 (14.4) b	43	265 (16.3) a	74	288 (15.4) a	0.10	0.37
Operational costs (€/ha/year)	33	2	157	1.21	0.3013	36	325 (18.9) a	56	349 (18.5) a	100	324 (14.4) a	0.01	0.29
Semi-net margin (€/ha/year)	20	2	81	1.01	0.3696	23	497 (82.8) a	29	537 (79.4) a	51	616 (63.7) a	0.02	NA
Semi-net margin per hour of field traction (€/h/ha/year)	20	2	76	0.98	0.3797	23	204 (47.5) a	29	134 (17.6) a	46	144 (17.9) a	0.02	NA

‡The coefficient of determination (R²) indicates the proportion of variance explained by the statistical model, and is divided into R²m (the proportion of variance explained by the fixed effect, farming strategy), and R²c (the proportion of variance explained by the whole model, fixed + random effects, the latter being the cluster effect). NA, not applicable.

Significant (p<0.05) farming strategy effects are shown in bold. Farming strategies sharing the same letter for a particular indicator are not significantly different at p < 0.05. The Treatment Frequency Indices (TFI) are those computed with “at the pest target” method (the reference dose is defined for each combination of commercial product, crop and pest target); results “at the crop target” method are provided in [Supplementary Table 5](#).

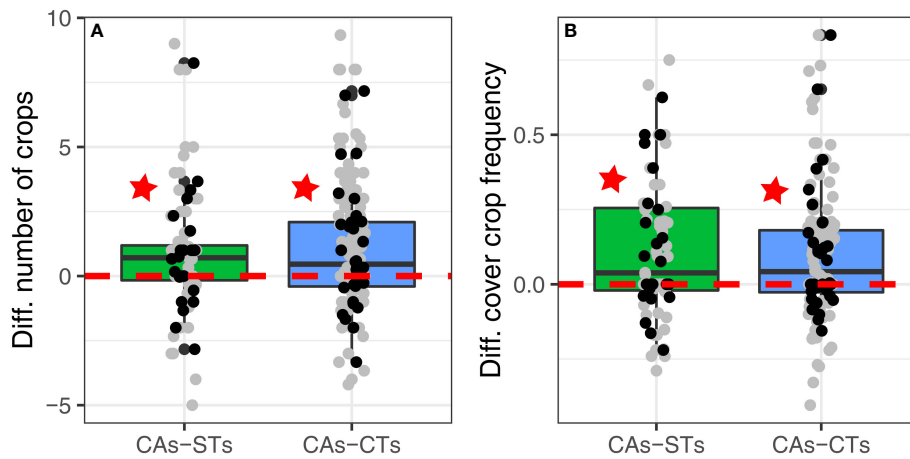


FIGURE 2 Distributions of the differences in response variables between conservation agriculture systems (CAs) and their reference conventional tillage (CTs, blue boxplots) and superficial tillage (STs, green boxplots) based systems for: the number of crops (A) and the frequency of fallow cover crops (B). Grey dots represent individual differences between systems. Black dots represent average differences per cluster. Red stars indicate significant differences between CAs and its reference system (either CTs or STs) at $p < 0.05$, cluster accounting for the production situation included as a random effect in the model (see details in Table 1).

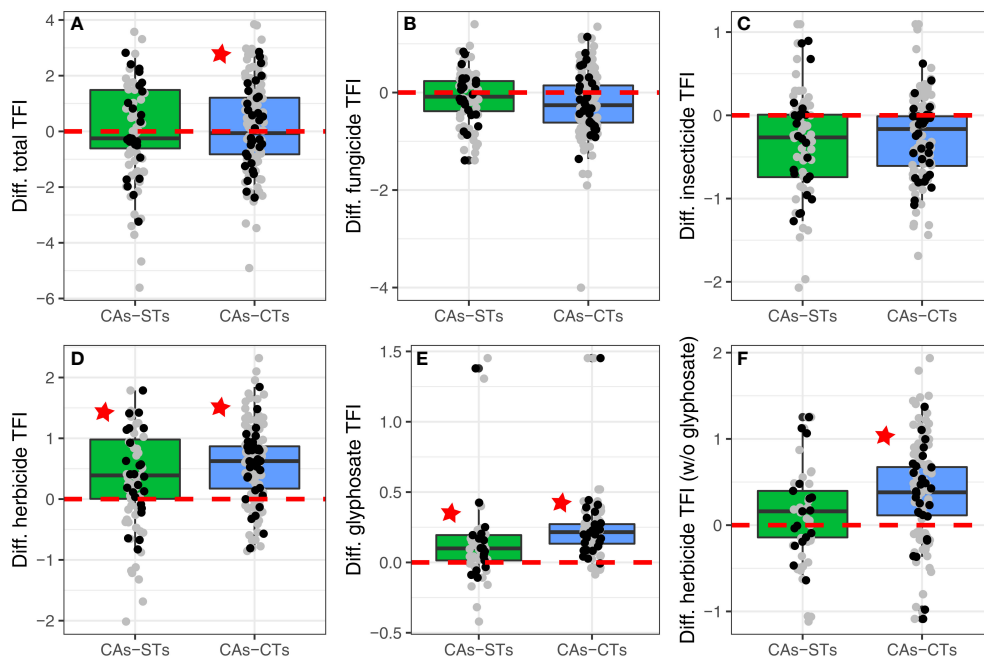


FIGURE 3 Pesticide use in conservation agriculture (CAs). Distributions of the differences in response variables between conservation agriculture systems (CAs) and their reference conventional tillage (CTs, blue boxplots) and superficial tillage (STs, green boxplots) based systems for: total treatment frequency index (total TFI including seed treatments, A), fungicide TFI (B), insecticides TFI (C), herbicide TFI (D), glyphosate-based herbicide TFI (E), and herbicide TFI without glyphosate (F). The TFI are those computed with “at the pest target” method. Grey dots represent individual differences between systems. Black dots represent average differences per cluster. Red stars indicate significant differences between CAs and its reference system (either CTs or STs) at $p < 0.05$. Cluster was included as a random effect in the statistical models to account for production situation effects (see details in Table 1).

3.1.3 Technical and economic indicators

With respectively 3 h/ha/year and 57 L/ha/year on average (Table 1), traction time and fuel consumption were clearly reduced in CAs compared to STs (-25 and -21%, respectively) and CTs (-32 and -39%, respectively, Figure 4). Nevertheless, the differences between CAs and STs were less obvious for both variables when focusing on the sub dataset comprising only common years (Supplementary Table S4). Gross product was 19% and 25% significantly lower in CAs than in STs and CTs, respectively (Table 1 and Figure 4). Focusing on the sub dataset comprising only common years yielded a similar ranking among farming strategies but no significant farming strategy effect or significant differences between treatments were revealed

(Supplementary Table S4). The lower gross margin was partly compensated by significantly lower mechanization costs in CAs compared to STs (-20%, only in the case of the full dataset, Table 1 and Figure 4) and CTs (-36%). However, lower mechanization cost was sufficient to compensate for the loss of gross products, as the semi-net margin did not differ (Table 1) between strategies (Figure 4). Winter wheat productivity was lower in CAs than STs (-13%) and CTs (-11%) indicating that reduced gross product was partly due to reduced yield of some crops (Table 1). The semi-net margin per hour of mechanized work did not significantly differ between the three strategies (Table 1 and Figure 4) despite a clear advantage of CAs over STs (+52%) and CTs (+42%).

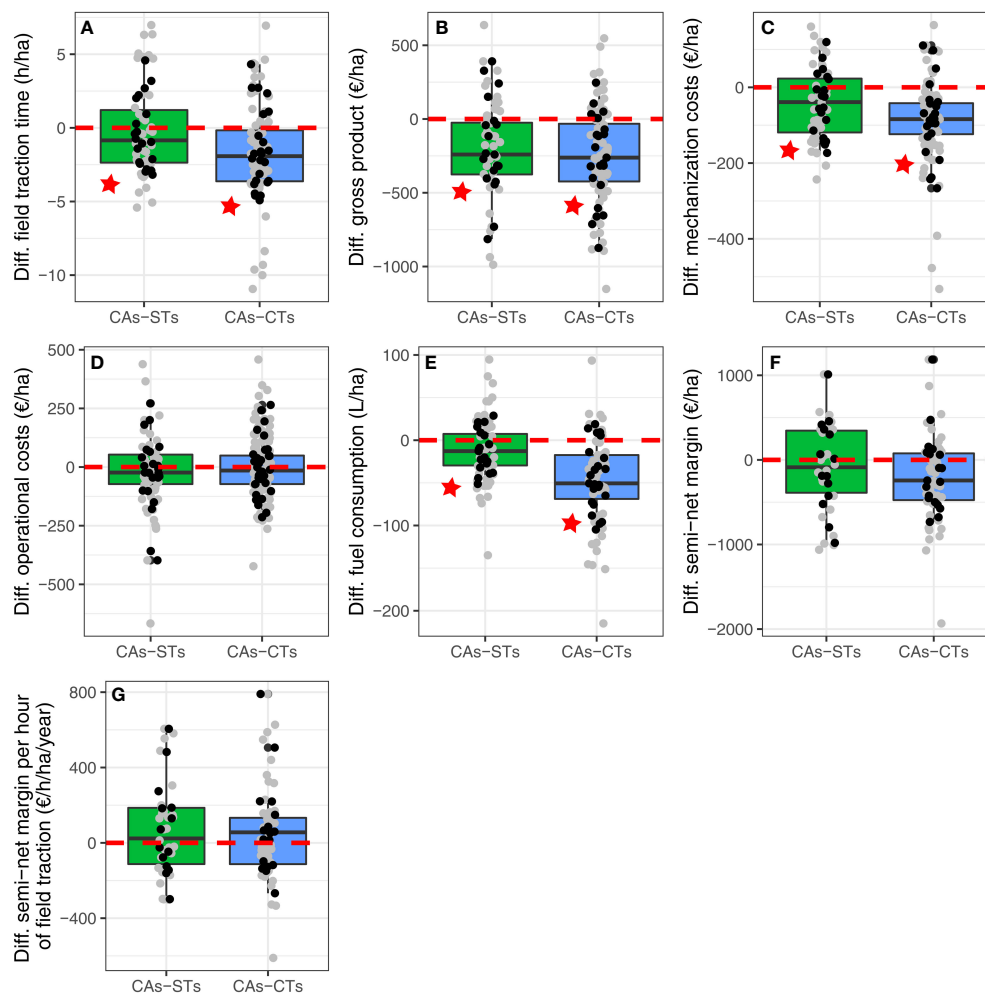


FIGURE 4

Technical and economic performances of conservation agriculture systems (CAs). Distributions of the differences in response variables between CAs and their reference conventional tillage (CTs, blue boxplots) and superficial tillage (STs, green boxplots) based systems for mechanized work time (h/ha/year, A), gross product (€/ha/year, B), mechanization costs (€/ha/year, C), operating costs (€/ha/year, D), fuel consumption (L/ha/year, E), semi-net margin (€/ha/year, F) and semi-net margin per hour of field traction (€/h/ha/year, G). Grey dots represent individual differences between systems. Black dots represent average differences per cluster. Red stars indicate significant differences between CAs and its reference system (either CTs or STs) at $p < 0.05$. Cluster was included as a random effect in the statistical models to account for production situation effects (see details in Table 1).

3.2 Multicriteria performance of pseudo-CA systems

3.2.1 Compliance with CA pillars

Pseudo-CAs did not resort to a more diversified crop rotation than the reference systems (Table 2 and Figure 5). The frequency of fallow cover crops was higher in pseudo-CAs than in the reference systems, but these differences were again not significant (Table 2 and Figure 5). Hence, pseudo-CAs tended to implement the two other pillars of CA but the difference with their CTs and STs counterparts was not as clear as with CAs (section 3.1.1).

3.2.2 Pesticide use

Overall, herbicide and insecticide use varied between farming strategies but pseudo-CAs showed significant differences with the reference systems only for insecticide use (-91 and -80% compared to STs and CTs, Table 2 and Figure 6). As observed for CAs, results were very similar when using TFI calculated with the TFI 'at crop' and 'at pest target' methods (see Table 2 for "at pest target" values, Supplementary Table S5 for "at crop values", and Supplementary Table 3 for correlations between both methods). Total TFI of pseudo-CAs (Figure 6) was intermediate between STs (highest) and CTs (lowest), but was not significantly different (Table 2). Nevertheless, focusing on the sub dataset comprising only common years yielded a significant difference between STs and CTs only (Supplementary Table S6). The differences were again mainly due to herbicides (Table 2 and Figure 6), with herbicide TFI in pseudo-CAs being lower than in STs (-7%) and higher than in CTs (+40%), but no significant differences were observed. However, focusing on the sub dataset comprising only common years revealed significantly higher herbicide use in pseudo-CAs and STs than in CTs (Supplementary Table S6). Pseudo-CAs and STs relied similarly on the use of glyphosate but more than CTs, although glyphosate use was overall low (Table 2 and Figure 6). Interestingly, herbicide TFI without glyphosate in CAs was not significantly different from either STs or CTs, though it was respectively higher and lower for the case of CAs. (Table 2 and Figure 6). Significantly higher herbicide TFI without glyphosate in pseudo-CAs and STs than in CTs was nevertheless identified when focusing on the sub dataset comprising only common years (Supplementary Table S6). Insecticide TFI (Figure 6) in pseudo-CAs was extremely low, close to 0, and significantly lower than those of the reference systems (Table 2). Fungicide TFI were about 0.3 and not significantly different between farming strategies (Table 2, Figure 6). Focusing on the sub dataset comprising only common years highlighted a significant difference between pseudo-CAs and CTs (Supplementary Table S6).

3.2.3 Technical and economic indicators

There were no differences between pseudo-CAs and STs for any of the technico-economic indicators studied (Table 2). However, fuel consumption in pseudo-CAs (-25%) and STs (-17%) was significantly lower than for CTs (Table 2 and Figure 7). Only the difference between pseudo-CAs and CTs remained significant when focusing on the sub dataset comprising only common years (Supplementary Table S6). Gross product, winter wheat yield, operating costs and semi-net margin (per hour of mechanized work or not) did not vary by farming strategy, for the full as well as the reduced dataset (Table 2; Figure 7 and Supplementary Table S6).

4 Discussion

4.1 Multicriteria performances of CA and pseudo-CA

The study confirmed and quantified assumptions often made about CA, usually backed up by farmers' observations. Our study is original with respect to the rare studies assessing CA based on multiple indicator of performances conducted in France (Craheix et al., 2016; Chabert and Sarthou, 2020). Indeed, Craheix et al. (2016) included systems implementing occasional superficial tillage in their definition of CA, which we describe here as pseudo-CA following the classification of tillage types of Reicosky (2015). In addition, Craheix et al. (2016), identified and classified systems based on tillage strategy as we did, but did not check the implementation of the third CA pillar, *i.e.* permanent soil cover, often considered by pioneers as the first to be implemented in the system. Contrary to Craheix et al. (2016), which indicated that crop rotation in CA helped in controlling weeds but not insect pests and diseases, our results showed that CAs resorted to more herbicides, whether glyphosate-based or not, but slightly less insecticides than the reference superficial (STs) and conventional (CTs) tillage based systems. Tillage, even superficial, remains a major weed management tool, although it shows the disadvantage of stimulating new cohorts after the destruction of the initial community (Teasdale et al., 1991; Cordeau et al., 2017). This could explain why non-glyphosate based herbicide TFI was similar in CAs and STs and slightly higher (even though not significantly) in STs than in pseudo-CAs in our study. However, CAs relied more on glyphosate than STs and CTs because even under no-tillage, perennial and even annual weeds still emerge and maintain populations over time (Trichard et al., 2013) and remain a main concern for CA farmers (Derrouch et al., 2020). Overall, the use of glyphosate-based herbicide was low (*i.e.* 0.26 and 0.13 TFI points for CAs and pseudo-CAs, respectively), corresponding to a reference

TABLE 2 Comparison of indicators between pseudo-conservation agriculture systems (pseudo-CAs) and their reference conventional tillage (CTs) and superficial tillage (STs) based systems, while accounting for production situation effects.

Indicators	nb cluster (max = 18)	numDF	denDF	F	p- value	Farming strategy						R ² m [‡]	R ² c [‡]			
						pseudo-CAs		STs		CTs						
						n (max = 19)	Mean (se)	n (max = 35)	Mean (se)	n (max = 67)	Mean (se)					
Number of crops (including secondary crops)	18	2	99	2.45	0.0913	19	4.6 (0.4)	a	34	3.7 (0.3)	a	66	3.8 (0.3)	a	0.03	0.26
Frequency of occurrence of cover crops	18	2	97	0.73	0.4867	19	0.18 (0.04)	a	34	0.13 (0.03)	a	64	0.15 (0.04)	a	0.01	0.35
Total TFI	18	2	98	1.13	0.3266	19	2.2 (0.4)	a	33	2.4 (0.6)	a	66	1.9 (0.4)	a	0.02	0.54
Herbicide TFI	18	2	98	3.43	0.0365	19	1.3 (0.1)	ab	33	1.4 (0.1)	a	66	0.9 (0.1)	b	0.16	0.60
Glyphosate TFI	16	2	88	9.35	0.0020	17	0.13 (0.06)	a	31	0.05 (0.02)	a	58	0.01 (0.00)	b	0.13	0.31
Herbicide w/o Glyphosate	16	2	88	2.38	0.0979	17	1.13 (0.12)	ab	31	1.29 (0.16)	a	58	0.87 (0.15)	b	0.15	0.69
Insecticide TFI	18	2	98	5.66	0.0047	19	0.008 (0.005)	b	33	0.09 (0.05)	a	66	0.04 (0.02)	a	0.09	NA
Fungicide TFI	18	2	98	0.30	0.7438	19	0.3 (0.2)	a	33	0.4 (0.1)	a	66	0.3 (0.1)	a	0.00	NA
Field traction time (h/ha/year)	16	2	90	3.57	0.0323	17	3.3 (0.5)	ab	32	3.3 (0.4)	b	59	4.1 (0.5)	a	0.04	0.46
Fuel consumption (L/ha/year)	14	2	80	4.15	0.0192	14	60.8 (9.0)	b	29	67.5 (5.3)	b	53	80.9 (7.4)	a	0.04	0.26
Gross product (£/ha/year)	17	2	88	0.76	0.4708	18	976 (78)	a	34	987 (66.7)	a	55	1055 (63.4)	a	0.01	0.28
Winter wheat yield (t/ha)	13	2	78	1.86	0.1629	13	7.4 (2.96)	a	32	7.38 (2.91)	a	48	6.96 (3.22)	a	0.03	NA
Mechanization costs (£/ha/year)	14	2	71	0.39	0.6798	14	258 (32.2)	a	24	241 (21.8)	a	49	250 (23.2)	a	0.00	0.43
Operational costs (£/ha/year)	18	2	93	1.89	0.1565	19	279 (24.7)	a	31	339 (26.6)	a	63	311 (20.0)	a	0.03	0.26
Semi-net margin (£/ha/year)	14	2	60	2.01	0.1426	14	578 (102.2)	a	22	528 (84.7)	a	40	717 (66.4)	a	0.05	NA
Semi-net margin per hour of field traction (£/h/ha/year)	13	2	59	0.51	0.6035	13	148 (17.4)	a	22	191 (45.9)	a	39	171 (29.4)	a	0.05	0.05

‡The coefficient of determination (R²) indicates the proportion of variance explained by the statistical model, and is divided into R²m (the proportion of variance explained by the fixed effect, system type), and R²c (the proportion of variance explained by the whole model, fixed + random effects, the latter being the cluster effect). NA, not applicable.

Significant (p<0.05) farming strategy effects are shown in bold. Farming strategies sharing the same letter for a particular indicator are not significantly different at p < 0.05. The Treatment Frequency Indices (TFI) are those computed with “at the pest target” method (the reference dose is defined for each combination of commercial product, crop and pest target); results “at the crop target” method are provided in [Supplementary Table 5](#).

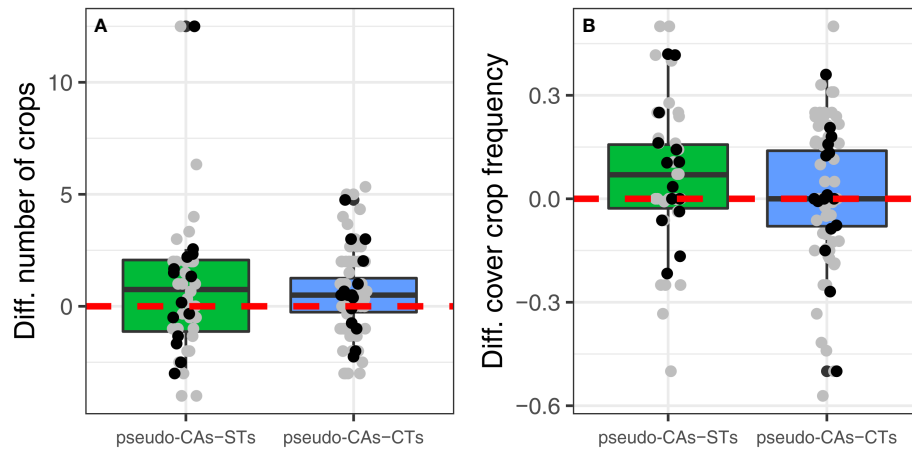


FIGURE 5

Distributions of the differences in response variables between pseudo-conservation agriculture systems (pseudo-CAs) and their reference conventional tillage (CTs, blue boxplots) and superficial tillage (STs, green boxplots) based systems for: the number of crops (A) and the frequency of summer fallow cover crops (B). Grey dots represent individual differences between systems. Black dots represent average differences per cluster. Red stars indicate significant differences between pseudo-CAs and its reference system (either CTs or STs) at $p < 0.05$, cluster accounting for the production situation included as a random effect in the model (see details in Table 2).

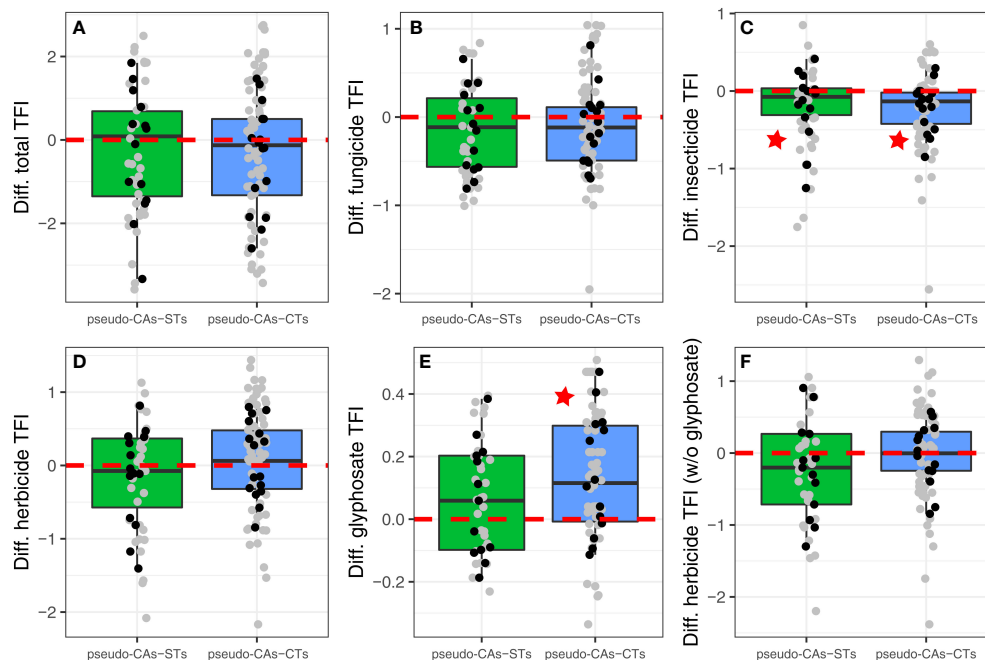


FIGURE 6

Pesticide use in pseudo-conservation agriculture (pseudo-CAs). Distributions of the differences in response variables between pseudo-CAs and their reference conventional tillage (CTs, blue boxplots) and superficial tillage (STs, green boxplots) based systems for: total treatment frequency index (total TFI including seed treatments, (A), fungicide TFI (B), insecticide TFI (C), herbicide TFI (D), glyphosate-based herbicide TFI (E), and herbicide TFI without glyphosate (F). The TFI are those computed with "at the pest target" method. Grey dots represent individual differences between systems. Black dots represent average differences per cluster. Red stars indicate significant differences between pseudo-CAs and its reference system (either CTs or STs) at $p < 0.05$, cluster accounting for the production situation included as a random effect in the model (see details in Table 2).

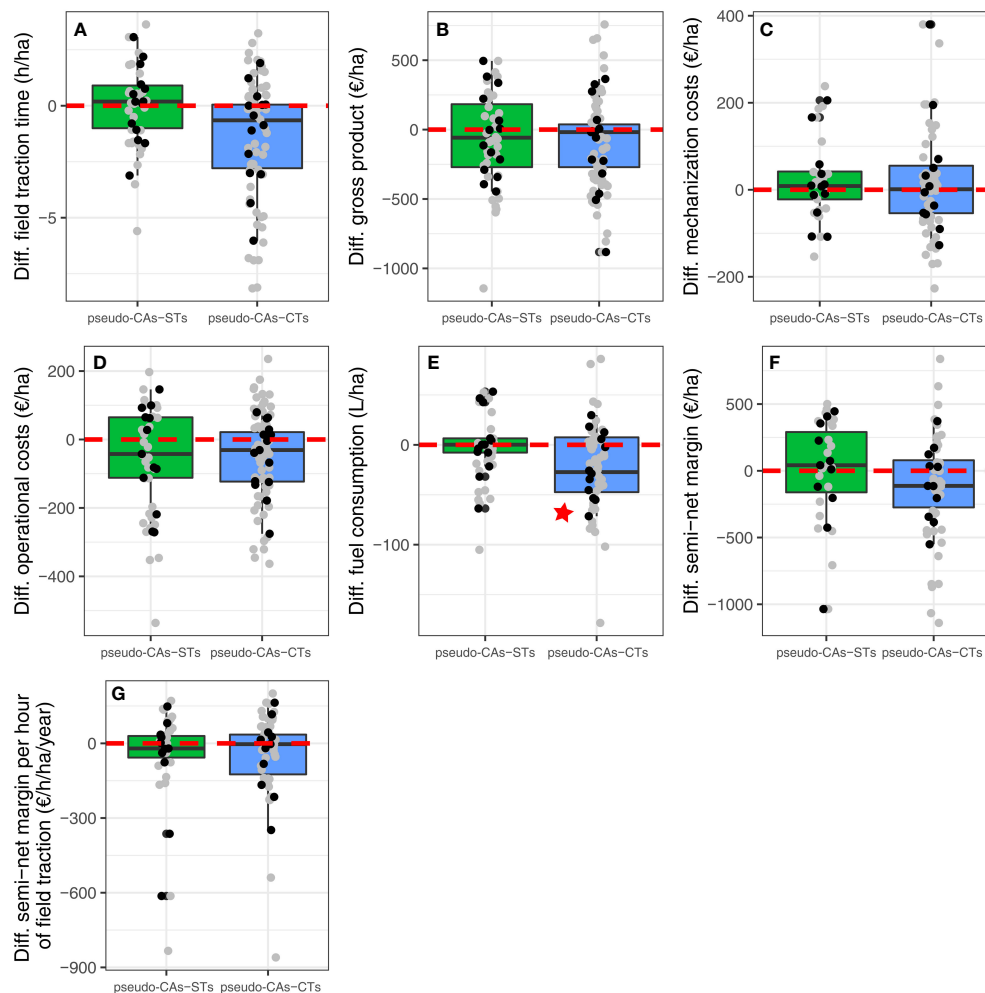


FIGURE 7

Technical and economic performances of pseudo-conservation agriculture systems (pseudo-CAs). Distributions of the differences in response variables between pseudo-CAs and their reference conventional tillage (CTs, blue boxplots) and superficial tillage (STs, green boxplots) based systems for mechanized work time (h/ha/year, **A**), gross product (€/ha/year, **B**), mechanization costs (€/ha/year, **C**), operating costs (€/ha/year, **D**), fuel consumption (L/ha/year, **E**), semi-net margin (€/ha/year, **F**) and semi-net margin per hour of field traction (€/h/ha/year, **G**). Grey dots represent individual differences between systems. Black dots represent average differences per cluster. Red stars indicate significant differences between pseudo-CA and its reference system (either CTs or STs) at $p < 0.05$. Clusters were accounted for as random effects in the model, cluster accounting for the production situation included as a random effect in the model (see details in [Table 2](#)).

dose applied every four years or a fourth of the reference dose applied each year on all plots of a given cropping system for CAs.

Our results also showed that stopping tillage in CA allows to decrease time of traction/ha/year, fuel consumption, as well as mechanization costs. It tended to slightly decrease profitability per hectare (due to slightly lower productivity), as also observed worldwide ([Pittelkow et al., 2015](#)). However, the ranking of systems was reversed when focusing on profitability per hour of field traction. CA was as profitable per hours of field traction as the other systems. CA is an innovative type of agriculture, at odds with some of the traditional pillars of farming, and thus requires training, field observations, a new organization of the work time, a more in depth selection of seeds and suppliers,

management of seed stocks, etc., which is not accounted for in field traction time.

These conclusions draw general lessons based on averages across different production situations, but mask a great diversity of interactions between farming strategy and cluster (a “unique” production situation). It is sometimes in particularities that we observe more nourishing lessons ([Verret et al., 2020](#); [Salembier et al., 2021](#)). For example, our results showed that few CAs used less herbicides (herbicide TFI) than their reference CTs and STs located in the same production situation. We hypothesize that specific elements of the production situation (region, soil type, market outlet) and/or differences in initial pest pressure could explain the large variability of responses across clusters, but

argue that our dataset was not designed to investigate these hypotheses compared to other studies [e.g. see [Lechenet et al. \(2017a\)](#)]. For example, stopping tillage represents a strong disturbance of the ecological habitat for weeds and it is only after a transition phase estimated by some studies at 5-6 years that weed management becomes optimal, when CA farmers optimized their choices of crops and cover crops ([Derrouch et al., 2020](#)). Finally, it is possible that the economic profitability per hectare (and/or per hour of work) is more favorable to CAs in areas of low to intermediate productivity, on shallow clay-limestone soils with limited yield potential. Our analysis highlighted lower winter wheat productivity for CAs than reference systems in the same production situation, as shown by [Pittelkow et al. \(2015\)](#), and may partly explain why gross products were lower in CAs. However, this conclusion cannot be drawn for all crops in all production situation and an in-depth analysis of the differences between the clusters, *i.e.* the production situation, would allow to verify this hypothesis, but even larger datasets would be required ([Munier-Jolain and Lechenet, 2020](#)).

4.2 Values of exploring big data sets

CAs and pseudo-CAs were here initially selected according to their tillage strategy (no-till in CAs and less than one superficial tillage per year across the 3-year period for pseudo-CAs). However, our analysis showed that CAs, contrary to pseudo-CAs, implemented the principles of crop diversification and soil coverage, two of the three pillars of CA ([Reicosky, 2015](#); [Kassam et al., 2019](#); [FAO, 2021](#)), and often considered as those implemented first during the transition phase ([Derrouch et al., 2020](#)). Pseudo-CAs did not implement the three CA principles since crop rotation were as diverse and cover crop as frequent as in STs and CTs, and tillage occurred, albeit rarely. The present study demonstrates once again the great value of large datasets documenting detailed agricultural practices implemented across a wide array of production situations ([Larsen and Noack, 2017](#); [Lechenet et al., 2017a](#); [Munier-Jolain and Lechenet, 2020](#)). Their analysis makes it possible to produce agronomic knowledge that is primordial for supporting farmers' agro-ecological transition, *i.e.* the adaptation of practices to increase cropping system multi-performance ([Munier-Jolain and Lechenet, 2020](#)). The method developed here is original, different from the data mining approaches (CART, Random Forest) that are becoming common for the analysis of large agronomic datasets ([Tittonell et al., 2008](#); [Williams et al., 2009](#)). We studied differences in indicators of performance between systems within the same production situations, with reference systems neighboring the targeted CAs and pseudo-CAs. As all the systems in the same

cluster share the same production context [type of soil, type of climate, technical-economic context, etc., *i.e.* all the elements of the context that are undergone by farmers and which cannot be modified by their farming strategy ([Lechenet et al., 2017a](#))], the approach allows to compare systems without confounding effect of the production situation, ensuring to highlight the effect of farmers' strategies.

4.3 Avenues for future research on multicriteria assessment of conservation agriculture

It was not possible in this study to refine the analyses by increasing the range of available indicators. For example, and despite an increasing interest in this question ([Dang et al., 2015](#); [Blanco-Canqui and Wortmann, 2020](#); [Cordeau et al., 2020](#)), the use of strategic tillage in fields implementing CA principles for years remains to be assessed from a multicriteria perspective. Pseudo-CAs consists of the implementation of superficial occasional tillage either for strategic (planting root crops such as sugar beet or potato, which require tillage) or tactical reasons (contain pest issues such as slugs, voles and/or weeds). However, implementing superficial tillage after a no-till phase is generally considered to be risky for weed management since the no-till phase of the rotation concentrates the weed seedbank in the top soil layer ([Swanton et al., 2000](#)) and then shallow tillage stimulates germination, leading to high infestations ([Cordeau et al., 2020](#)). This is not the case for the 'rotational no-till' strategies, which alternate long no-till phases with plowing ([Mirsky et al., 2013](#)), but whose performance on a wide range of indicators, as we did here, remain unknown ([Cordeau et al., 2020](#)).

Finally, this study compared cropping systems based on performances averaged over multiple plot and years. The DEPHY Farm network was set up in the early 2010s and is made up of volunteer farmers who are motivated in reducing pesticide use, albeit without negative financial consequences, and are thus engaged in changing their farming practices. Thus, performances are expected to change over time as farmers optimize new practices aiming at reducing pesticide use, even in CA and pseudo-CA. It would therefore be interesting to analyze the trajectories of performances to identify pathways allowing farmers to achieve multi-performance as fast as possible. CA remains a new and evolving form of agriculture in France as it is worldwide, constantly innovating, and already very different from how it was implemented by pioneers several decades ago ([Laurent, 2015](#)). Ensuring the continuation of the DEPHY farmers' network will allow future research to dig into performance trajectories, instead of averaged performances of moving strategies.

5 Conclusion

Based on the analysis of 13 indicators of technical, economic and environmental performances, computed on 280 cropping systems implementing conservation agriculture (CAs), pseudo-CAs (implementing occasional shallow tillage operations), conventional tillage (CTs, *i.e.* plowing-based) and superficial tillage (STs) based strategies, we found that CAs (i) require more herbicides but slightly less insecticides, (ii) decrease time of traction/ha/year, fuel consumption, as well as mechanization costs, (iii) tend to slightly decrease profitability per hectare (due to slightly lower productivity) but similar profitability per hour of field traction. Further analysis is needed to identify the determinants of multi-performance in a given production situations and track down innovative systems optimizing multiple performances and solving apparent trade-offs, such as tillage intensity and herbicide use and/or limited productivity.

Data availability statement

The raw data supporting the conclusions of this article will be made available by the authors, upon request.

Author contributions

GA, SC, NM-J designed the study. SC and NM-J funded the study. GA and NM-J requested the data from the DEPHY Network. GA, MG, SL, and EC coded different functions necessary for data analysis. GA prepared the data and performed all preliminary and final analyses, with help of MG. All authors were involved in the interpretation of the results and contributed to writing the original version of the manuscript and improving the subsequent ones.

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agriculture without glyphosate”), which was financed by the French Ministry in charge of Agriculture and Food (Ministère de l'Agriculture et de l'Alimentation), with financial contributions from the special purpose account “Développement agricole et rural”. The authors also wish to acknowledge financial support from INRAE, ANR PPR SPECIFICS project (ANR-20-PCPA-0008), and the European Union’s Horizon 2020 research and innovation program under grant agreement (no. 727321-IWM PRAISE).

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Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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Supplementary material

The Supplementary Material for this article can be found online at: <https://www.frontiersin.org/articles/10.3389/fagro.2022.999960/full#supplementary-material>

Available at: <https://www.data.gouv.fr/fr/datasets/donnees-ouvertes-du-catalogue-e-phy-des-produits-phytopharmaceutiques-matieres-fertilisantes-et-supports-de-culture-adjuvants-produits-mixtes-et-melanges/>.

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