

Supplementary Material for “An inference method for global sensitivity analysis”

Gildas Mazo

Université Paris-Saclay, INRAE, MaIAGE, 78350, Jouy-en-Josas, France
and

Laurent Tournier

Université Paris-Saclay, INRAE, MaIAGE, 78350, Jouy-en-Josas, France

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A Generation of datasets for the estimation of sensitivity indices

Cell fate Boolean model of Section 5.1. The reduced version of 11 variables V_1, \dots, V_{11} presented in Calzone et al. (2010) was used. This model is taken as the reference, where each Boolean variable has the same relative speed. In the reference model, the probabilities of all transitions involving the activation of variable V_j (*i.e.* V_j going from 0 to 1) are multiplied by some weight w_j^+ , and the probabilities of all transitions involving the deactivation of variable V_j (*i.e.* V_j going from 1 to 0) are multiplied by some weight w_j^- . Each row of the probability matrix is then divided by its sum, ensuring the process is still a Markov chain. In the global sensitivity analysis, the inputs are the weights w_j^+ and w_j^- for six chosen variables (C8, RIP1, NFkB, cIAP, MOMP and MPT), leading to the 12 inputs listed in Table 1. Since there is no a priori information about the relative speed of the regulatory processes involved in the cell, all weights are drawn independently. Each input is drawn according to the log-uniform distribution $\log \mathcal{U}(10^{-0.5}, 10^{0.5})$. Thus, for each $i = 1, \dots, n$ and $j = 1, \dots, d$, we independently draw $X_j^{(i)} \sim \log \mathcal{U}(10^{-0.5}, 10^{0.5})$, meaning that $\log X_j^{(i)} \sim \mathcal{U}(\log 10^{-0.5}, \log 10^{0.5})$.

The last step of the simulation consists in the execution of the updated Markov chain from a given initial condition, until it reaches one of the three steady states: apoptosis, necrosis or survival. The chosen initial condition is the same as in Calzone et al. (2010): all variables at 0 except for ATP, cIAP and TNF at 1.

ODE model of Section 5.2. The inputs and their distributions are listed in Table 2. Here again the inputs are drawn independently, since we do not have any a priori information.

We performed $n = 5000$ simulations; among them 13 presented at least one numerical anomaly (for instance the explosion of one variable) and were taken out, leaving a sample of size $n = 4987$. The simulations were carried out with the routine `ode45` of MATLAB. To determine when a steady state had been reached, we tested whether $\Delta N/N$ was below the threshold value 10^{-10} (recall that N denotes total bacterial population: $N = L + S + S^l$). The last step consisted in extracting the logarithms of steady state populations, expressed in CFU *colony*

forming unit. If Y^* designates one of the five populations in steady state, we applied the following transformation:

$$Y = \begin{cases} \log_{10}(Y^*) & \text{if } Y^* > 1, \\ 0 & \text{if } Y^* \leq 1, \end{cases}$$

in order to obtain populations on a logarithmic scale. Very small populations ($Y^* \leq 1$ CFU) were simply ignored as in practice, they are below detection thresholds.

B Proofs

Proof of Proposition 2

We only show the second statement of the proposition. Let A_1, \dots, A_{2^d-1} be some enumeration of the elements of $\mathbf{2}^D \setminus \emptyset$. Since $\text{Var } f(X) = \sum_{i=1}^{2^d-1} \sigma^*(A_i)$, the null hypothesis is equivalent to “ $H_0 : \sum_{i=1}^{2^d-1} c_i \sigma^*(A_i) \leq 0$ ”, which is further rewritten as “ $H_0 : c^\top \sigma^* \leq 0$ ”. Because of Proposition 1, it is clear that under H_0 , it holds that $\lim_{n \rightarrow \infty} P_{H_0}(S_n > r) \leq \lim_{n \rightarrow \infty} P(N > q_{1-\alpha}) \leq \alpha$, where here N is a standard normal random variable.

Proof of Proposition 3

We show that $M^* = \otimes^d M_1^*$. Let ω be the inverse of the one-to-one map that with each $A \in \mathbf{2}^D$ associates $\sum_{i=1}^d b_i 2^{d-i} \in \{0, \dots, 2^d - 1\}$, where $b_i = 1$ if $i \in A$ and $b_i = 0$ otherwise. (Note that ω depends on d . For instance, for $d = 2$, $\omega(3) = \{1, 2\}$ but $\omega(3) = \{2, 3\}$ for $d = 3$.) The arrangement of the components of τ^* described at the beginning of Section 4 implies that

$$\tau_i^* = \tau^*(\omega(i)),$$

for all $i = 0, \dots, 2^d - 1$, where in the left-hand side τ_i^* denotes the i th component (starting at zero) of the dual total index vector and in the right-hand side $\tau^*(\omega(i))$ denotes the dual total index of the set $\omega(i)$. The same holds for σ^* .

We show that M^* in (15) coincides with $\otimes^d M_1^*$ where M_1^* is as in (21). In this proof, d , and hence ω , since it depends on d , are fixed. A few results are collected in the following lemma.

Input	Description: relative probability of
$X_1 = w_1^+$ (C8+)	activation of caspase 8
$X_2 = w_1^-$ (C8-)	deactivation of caspase 8
$X_3 = w_2^+$ (RIP1+)	activation of RIP1
$X_4 = w_2^-$ (RIP1-)	deactivation of RIP1
$X_5 = w_3^+$ (NFkB+)	activation of NFkB
$X_6 = w_3^-$ (NFkB-)	deactivation of NFkB
$X_7 = w_4^+$ (cIAP+)	activation of cIAP
$X_8 = w_4^-$ (cIAP-)	deactivation of cIAP
$X_9 = w_5^+$ (MOMP+)	activation of MOMP
$X_{10} = w_5^-$ (MOMP-)	deactivation of MOMP
$X_{11} = w_6^+$ (MPT+)	activation of MPT
$X_{12} = w_6^-$ (MPT-)	deactivation of MPT

Table 1: Description of the inputs of the Boolean network (part 5.1). Each input is drawn according to the log-uniform distribution $\log \mathcal{U}(10^{-0.5}, 10^{0.5})$.

Input (unit)	Description	Distribution
d (h^{-1})	dilution rate of the mouse gut	$\mathcal{U}(0.1, 0.4)$
r (h^{-1})	maximal growth rate of bacteria	$\mathcal{U}(0.2, 1.5)$
k (CFU/g)	carrying capacity of bacteria	$\log \mathcal{U}(3.5 \cdot 10^9, 10^{10})$
x (h^{-1})	lysis induction rate	$\log \mathcal{U}(10^{-4}, 0.1)$
l (h^{-1})	lytic cells' mortality rate	$\mathcal{U}(0.2, 1.5)$
y (\emptyset)	burst size	$\mathcal{U}(1, 50)$
a ($[\text{PFU/g}]^{-1}h^{-1}$)	adsorption constant	$\log \mathcal{U}(10^{-10}, 10^{-7})$
g (\emptyset)	probability of lysogeny	$\log \mathcal{U}(10^{-4}, 0.7)$
L_0 (CFU/g)	initial lysogens	$\log \mathcal{U}(10^5, 10^7)$
S_0 (CFU/g)	initial susceptible	$\log \mathcal{U}(10^5, 10^7)$

Table 2: Description of the inputs of the ODE system (part 5.2).

Lemma 1. *Let $1 \leq n \leq d$ and $i, j \in \{0, \dots, 2^{n+1} - 1\}$. If $0 \leq i \leq 2^n - 1$ and $2^n \leq j \leq 2^{n+1} - 1$ then the following statements are true:*

- (i) $\omega(i) \subset \omega(j)$ if and only if $\omega(i) \subset \omega(j - 2^n)$.
- (ii) $|\omega(j - 2^n) \setminus \omega(i)|$ is even if and only if $|\omega(j) \setminus \omega(i)|$ is odd.
- (iii) $\omega(i) \not\subset \omega(j)$

We need to show that

$$(\otimes^d M_1^*)_{ij} = \begin{cases} -1 & \text{if } \omega(j) \subset \omega(i) \text{ and } |\omega(i) \setminus \omega(j)| \text{ is odd,} \\ 1 & \text{if } \omega(j) \subset \omega(i) \text{ and } |\omega(i) \setminus \omega(j)| \text{ is even,} \\ 0 & \text{otherwise.} \end{cases} \quad (\text{B.1})$$

Let us show a slightly more general result. Let M_n^* , $n = 1, \dots, d$, be a finite sequence of matrices of increasing size defined by

$$M_1^* = \begin{pmatrix} 1 & 0 \\ -1 & 1 \end{pmatrix}, \quad M_n^* = \underbrace{M_1^* \otimes \dots \otimes M_1^*}_{n \text{ times}} \quad (n = 1, \dots, d).$$

Let us show that M_n^* satisfies (B.1) for every $i, j \in \{0, \dots, 2^n - 1\}$ and all $1 \leq n \leq d$. This will show in particular that $M_d^* = M^*$. The proof is by mathematical induction. If $n = 1$ then it is clear that (B.1) holds because $\omega(0) = \emptyset$ and $\omega(1) = \{d\}$. Let $n \geq 1$ and suppose that M_n^* satisfies (B.1) for every $i, j \in \{0, \dots, 2^n - 1\}$. Let us show that M_{n+1}^* satisfies (B.1) for every $i, j \in \{0, \dots, 2^{n+1} - 1\}$. By definition,

$$M_{n+1}^* = M_1^* \otimes M_n^* = \begin{pmatrix} M_n^* & 0 \\ -M_n^* & M_n^* \end{pmatrix}. \quad (\text{B.2})$$

Case $i, j \in \{0, \dots, 2^n - 1\}$: We have that $(M_{n+1}^*)_{i,j}$ is equal to $(M_n^*)_{i,j}$, which satisfies (B.1) by assumption.

Case $i \notin \{0, \dots, 2^n - 1\}$ and $j \in \{0, \dots, 2^n - 1\}$: We have $(M_{n+1}^*)_{i,j} = (-M_n^*)_{i-2^n, j}$. By assumption,

$$(-M_n^*)_{i-2^n, j} = \begin{cases} 1 & \text{if } \omega(j) \subset \omega(i - 2^n) \text{ and } |\omega(i - 2^n) \setminus \omega(j)| \text{ is odd,} \\ -1 & \text{if } \omega(j) \subset \omega(i - 2^n) \text{ and } |\omega(i - 2^n) \setminus \omega(j)| \text{ is even,} \\ 0 & \text{otherwise.} \end{cases}$$

Notice that, compared to (B.1), “1” and “-1” have been interchanged. By Lemma 1, it holds that $\omega(j) \subset \omega(i)$ is equivalent to $\omega(j) \subset \omega(i - 2^n)$. Thus,

it remains to show that $|\omega(i - 2^n) \setminus \omega(j)|$ is even if and only if $|\omega(i) \setminus \omega(j)|$ is odd. But again this is true from Lemma 1.

Case $i \notin \{0, \dots, 2^n - 1\}$ and $j \notin \{0, \dots, 2^n - 1\}$: Here $(M_{n+1}^*)_{i,j} = (M_n^*)_{i-2^n, j-2^n}$. That $(M_n^*)_{i-2^n, j-2^n}$ satisfies (B.1) follows from the same considerations as in the previous case.

Case $i \in \{0, \dots, 2^n - 1\}$ and $j \notin \{0, \dots, 2^n - 1\}$: We know from (B.2) that $(M_{n+1}^*)_{i,j} = 0$. To show that (B.1) is satisfied, it suffices to see that $\omega(j) \not\subset \omega(i)$. But this is true from Lemma 1, since $j > i$.

Proof Proposition 4

We show that $\sigma^{*(d)} = (\otimes^d M_1^*) \sigma^{*(0)}$.

We shall show that, in general,

$$\sigma^{*(j)} = (I_{2^{d-j}} \otimes (\otimes^j M_1^*)) \sigma^{*(0)}, \quad (\text{B.3})$$

for all $j = 1, \dots, d$. The proof is by mathematical induction. Equation (B.3) is true for $j = 1$ because of (23). Suppose that it is true for a given j and let us show it is true for $j + 1$. From (23) and (B.3), we have

$$\begin{aligned} \sigma^{*(j+1)} &= (I_{2^{d-j-1}} \otimes M_1^* \otimes I_{2^j}) \sigma^{*(j)} \\ &= ((I_{2^{d-j-1}} \otimes M_1^*) \otimes I_{2^j}) (I_{2^{d-j}} \otimes (\otimes^j M_1^*)) \sigma^{*(0)} \\ &= ((I_{2^{d-j-1}} \otimes M_1^*) I_{2^{d-j}}) \otimes (I_{2^j} (\otimes^j M_1^*)) \sigma^{*(0)} \\ &= (I_{2^{d-j-1}} \otimes M_1^*) \otimes (\otimes^j M_1^*) \sigma^{*(0)} \\ &= (I_{2^{d-j-1}} \otimes (\otimes^{j+1} M_1^*)) \sigma^{*(0)}. \end{aligned}$$

To show that the computation cost is $\Theta(d2^d)$, notice that each matrix $I_{2^{d-j}} \otimes M_1^* \otimes I_{2^{j-1}}$ is a block-diagonal matrix of the form

$$\begin{bmatrix} M_1^* \otimes I_{2^{j-1}} & & & \\ & \ddots & & \\ & & & M_1^* \otimes I_{2^{j-1}} \end{bmatrix}.$$

Let m_{ij} denote the element at the i th row and j th column of M_1^* ($i, j \in \{1, 2\}$). There are 2^{d-j} block-rows of the form

$$M_1^* \otimes I_{2^{j-1}} = \begin{bmatrix} m_{11} I_{2^{j-1}} & m_{12} I_{2^{j-1}} \\ m_{21} I_{2^{j-1}} & m_{22} I_{2^{j-1}} \end{bmatrix},$$

and, if multiplied by a column vector to the right, each of them leads to $\Theta(\text{nnz}(M_1^* \otimes I_{2^{j-1}})) = \Theta(\text{nnz}(M_1^*)2^{j-1}) = \Theta(2^{j-1})$ arithmetic operations, yielding $2^{d-j}\Theta(2^{j-1}) = \Theta(2^{d-1}) = \Theta(2^d)$ operations per update. Since there are d updates, the proof is complete.

C Building better estimators of the vector of total indices

While the estimator $\hat{\tau}$ in Section 3.1 is conceptually simple and widely used, we can construct more efficient estimators. Efficiency can be improved in two ways: one builds an estimator with a smaller variance or one builds an estimator with the same variance but with a smaller number of function evaluations. We shall do both.

C.1 Estimators with a smaller variance

Let $\hat{\tau}^{(\alpha)}(A) = \alpha\hat{\tau}^{(1)}(A) + (1 - \alpha)\hat{\tau}^{(0)}(A)$, where $\alpha \in [0, 1]$, $A \subset D$ and

$$\begin{aligned}\hat{\tau}^{(1)}(A) &= \frac{1}{n} \sum_{i=1}^n \frac{1}{2} (f(X^{(i)}) - f(X^{(i)\setminus A}))^2, \\ \hat{\tau}^{(0)}(A) &= \frac{1}{n} \sum_{i=1}^n \frac{1}{2} (f(X'^{(i)}) - f(X'^{(i)\setminus A}))^2.\end{aligned}$$

Note that $\hat{\tau}^{(1)}(A)$ is Jansen's estimator mentioned in Section 3.1, that is, $\hat{\tau}^{(1)}(A) = \hat{\tau}(A)$. Note also that $\mathbb{E}\hat{\tau}^{(0)}(A) = \mathbb{E}\hat{\tau}^{(1)}(A) = \tau(A)$ and $\text{Var}\hat{\tau}^{(0)}(A) = \text{Var}\hat{\tau}^{(1)}(A)$. Let $\hat{\tau}^{(\alpha)}$ be the vector formed by stacking all $\hat{\tau}^{(\alpha)}(A)$ with $A \subset D$. If M is a matrix then denote by $\text{tr}(M)$ the trace of M , that is, the sum of its diagonal elements.

Proposition C.1. *The following statements hold:*

- (i) $\mathbb{E}[\hat{\tau}^{(\alpha)}(A)] = \tau(A)$ and $\text{Var}[\hat{\tau}^{(\alpha)}(A)] \leq \text{Var}[\hat{\tau}(A)]$ for every $\alpha \in [0, 1]$;
- (ii) the variance of $\hat{\tau}^{(\alpha)}(A)$ is minimum when $\alpha = 1/2$ and

$$0 \leq \text{Var}[\hat{\tau}(A)] - \text{Var}[\hat{\tau}^{(1/2)}(A)] = \frac{\text{Var}[\hat{\tau}(A)] - \text{Cov}[\hat{\tau}(A), \hat{\tau}^{(0)}(A)]}{2};$$

(iii) $\sqrt{n}(\hat{\tau}^{(\alpha)} - \tau) \xrightarrow{d} N(0, T_\alpha)$, with $T_\alpha = (2\alpha^2 - 2\alpha + 1)T + 2\alpha(1 - \alpha)C$, where T was defined in Proposition 1 and C is the matrix of size $2^d \times 2^d$ given by

$$C(A, B) = \text{Cov} \left[\frac{1}{2}(f(X') - f(X'^{\setminus A}))^2, \frac{1}{2}(f(X) - f(X^{\setminus B}))^2 \right].$$

Moreover, $0 \leq \text{tr}(T) - \text{tr}(T_\alpha) \leq \text{tr}(T) - \text{tr}(T_{1/2}) = \frac{1}{2} \text{tr}(T - C)$ for every $\alpha \in [0, 1]$.

The proof of Proposition C.1 follows from elementary calculations and the standard delta method. Proposition C.1 implies that $\hat{\tau}^{(1/2)}$ is component-wise more efficient—both at finite and infinite sample sizes—than any $\hat{\tau}^{(\alpha)}$, including $\hat{\tau}$ itself.

C.2 An estimator with a smaller number of function evaluations

Instead of looking for an estimator with a smaller variance as above, we can, in the spirit of Saltelli (2002), turn the problem around and look for an estimator that requires fewer evaluations of function f . Consider the following sampling scheme. For each $i = 1, \dots, n$, draw two independent copies $X^{(i)} = (X_1^{(i)}, \dots, X_d^{(i)})$ and $X'^{(i)} = (X_1'^{(i)}, \dots, X_d'^{(i)})$ and then perform the steps below:

$$\left\{ \begin{array}{l} \text{compute } f(X^{(i)}), f(X'^{(i)}) \\ \text{for } k = 1, \dots, \lfloor d/2 \rfloor \\ \text{for } A \in \mathbf{2}^D : |A| = k \\ \text{compute } f(X^{(i)\setminus A}). \end{array} \right. \quad (\text{C.1})$$

Then, define for every $A \subset D$,

$$\hat{\tau}'(A) = \begin{cases} \frac{1}{n} \sum_{i=1}^n \frac{1}{2} (f(X^{(i)}) - f(X^{(i)\setminus A}))^2 & \text{if } |A| \leq \lfloor d/2 \rfloor \\ \frac{1}{n} \sum_{i=1}^n \frac{1}{2} (f(X'^{(i)}) - f(X_i^{(i)\setminus A^c}))^2 & \text{otherwise,} \end{cases} \quad (\text{C.2})$$

where A^c stands for $D \setminus A$, the complement of A in D . To shorten the notation, denote $Y_{A,B} = (f(X^{\setminus A}) - f(X^{\setminus B}))^2/2$ for every $A, B \subset D$.

Proposition C.2. *The following statements are true:*

(i) it holds that

$$\sqrt{n}(\hat{\tau}' - \tau) \xrightarrow{d} N(0, T'),$$

where T' is the variance-covariance matrix given by

$$T'(A, B) = \begin{cases} \text{Cov}(Y_{\emptyset, A}, Y_{\emptyset, B}) & \text{if } |A| \leq \lfloor d/2 \rfloor, |B| \leq \lfloor d/2 \rfloor, \\ \text{Cov}(Y_{\emptyset, A}, Y_{D, B^c}) & \text{if } |A| \leq \lfloor d/2 \rfloor, |B| > \lfloor d/2 \rfloor, \\ \text{Cov}(Y_{D, A}, Y_{\emptyset, B}) & \text{if } |A| > \lfloor d/2 \rfloor, |B| \leq \lfloor d/2 \rfloor, \\ \text{Cov}(Y_{D, A^c}, Y_{D, B^c}) & \text{if } |A| > \lfloor d/2 \rfloor, |B| > \lfloor d/2 \rfloor. \end{cases}$$

Moreover, it holds $\text{tr}(T') = \text{tr}(T)$, where T is defined in Proposition 1.

(ii) The number of evaluations of f needed to compute the estimator (C.2) is equivalent to $n2^{d-1}$, asymptotically as d goes to infinity.

Proof. The proof of the first statement is a direct application of the central limit theorem. To show the “moreover” part, put $Z(A) = \frac{1}{2}(f(X) - f(X \setminus A))^2$, $Z'(A) = \frac{1}{2}(f(X') - f(X \setminus A^c))^2$ and

$$\tilde{Z}(A) = \begin{cases} Z(A) & \text{if } |A| \leq \lfloor d/2 \rfloor, \\ Z'(A) & \text{otherwise,} \end{cases}$$

for every $A \subset D$. With this notation, $T(A, B) = \text{Cov}(Z(A), Z(B))$ and $T'(A, B) = \text{Cov}(\tilde{Z}(A), \tilde{Z}(B))$. If $|A| \leq \lfloor d/2 \rfloor$ and $|B| \leq \lfloor d/2 \rfloor$ then obviously $T(A, B) = T'(A, B)$. If $|A| > \lfloor d/2 \rfloor$ and $|B| > \lfloor d/2 \rfloor$ then the equality is also true because X and X' play the same role.

To show the second statement, notice that the outputs needed in the top row of (C.2) are precisely those computed in (C.1). The outputs needed in the bottom of (C.2) also have been computed in (C.1), since $|A| \geq \lfloor d/2 \rfloor + 1$ implies $|A^c| \leq d - \lfloor d/2 \rfloor - 1 \leq \lfloor d/2 \rfloor$. But the number of simulations in (C.1) is clearly 2^{d-1} , which has to be multiplied by n to get the final number of evaluations. □

According to Proposition C.2, the estimator $\hat{\tau}'$ is as efficient as $\hat{\tau}$ but requires only half the number of function evaluations of $\hat{\tau}$.

D Supplementary figure

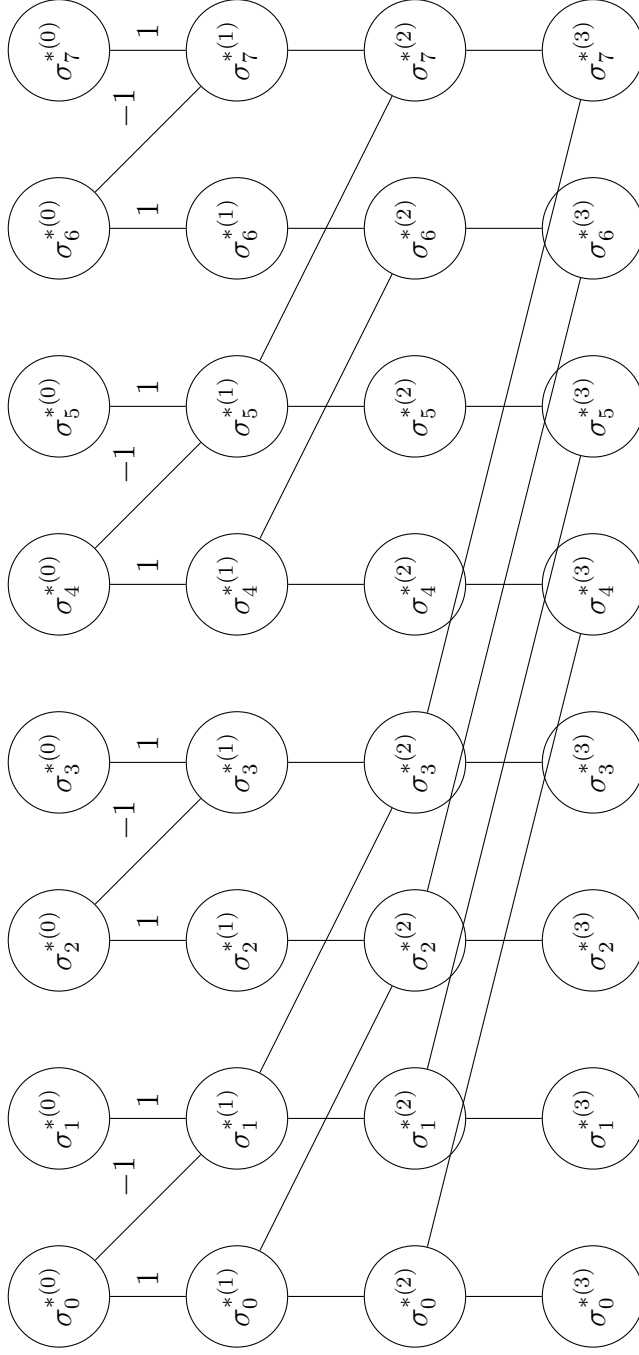


Figure 1: Flow diagram of the algorithm (23) with $d = 3$ and M_1^* as in (21). Here $\sigma_i^{*(j)}$ is the i th element of the vector $\sigma^{*(j)}$ and hence coincides with $\sigma^{*(j)}(a_{i,1} \cdots a_{i,d})$ in the main text. Although not shown for improved readability, all vertical and diagonal lines have weights 1 and -1 , respectively.