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Evapotranspiration mapping from remote sensing data: uncertainties and ensemble estimates based on multimodel-multidata simulations

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Contexte
☐ ET is a major component of the hydrological cycle, but
→ in many situations, ET and its evolution are not well known
→ there is a lot of uncertainties in ET monitoring
☐ Many models exist, but none looks satisfactory in every situations (season, type of climate, type surfaces
→ ensemble modelling
Ensemble modelling approaches were developed in various field of research (ex. Climate, hydrology, agronomy) assuming they are providing an optimal or suboptimal solution

☐ Work done in the frame of TRISHNA and LSTM mission preparations

Evapotranspiration (ET) can be derived using various models based on thermal infrared data

```
    → uncertainty in Ts: { - instrument - atmosphere}
    → large number of models → diversity of algorithms => uncertainties
    → lots of other data required : { - albedo - vegetation density - meteorological data}
    → time integration { - instantaneous measurements - intermittent data (revisit, clouds) } → daily values => uncertainties
```

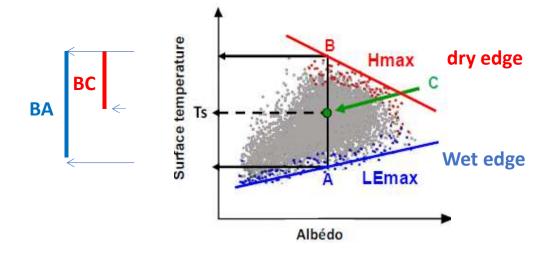
No consensus on a best model => ensemble averaging considering both models and data sources

Many unknowns remain concerning the uncertainties in the derivation of ET, in particular for discriminating uncertainties from input data and models

Evapotranspiration model: EVASPA (EVapotranspiration Assessment from SPAce)

-> Contextual model : ET ~ EF x (Rn – G)

The evaporative fraction EF = BC / BA



```
EF = evaporative fraction <- Ts vs. albedo or NDVI or fraction cover
```

Rn = net radiation <- albedo, emissivity, Ts, solar irradiance atmospheric irradiance

ex: S-SEBI (Roerink et al. 2000)

G = ground heat flux <- Rn, NDVI, fCOVER

Ensemble calculations

 $ET_{ensemble}$ defined as : - median of ET_i (n ensemble members ~ n individual estimates) - weighted average of ET_i with weighting coefficients : a_i

Computed pixels by pixels: $ET_{ensemble} = \sum_{i=1}^{n} a_i ET_i$

The weighting coefficient a_i may be set to:

- to 1/n
- a priori values depending on a previous knowledge on the quality of the models
- values depending on the evaluation of each members against in-situ data

Uncertainty: defined as an indicator of the dispersion of the member values:

- the standard deviation of Eti
- the range

The impact of each input or model uncertainty in the global uncertainty in ET can be derived (one factor at a time variation, anova ...)

Example 1: uncertainty analysis, simple averaging

ESA experiment in Grosseto (Italy) in support of the LSTM program : July 2018

Airborne images in the solar and the thermal domains

Various sources for input data:

- incident radiations,
- LAI,
- fCOVER,
- surface temperature...

Various « models » for

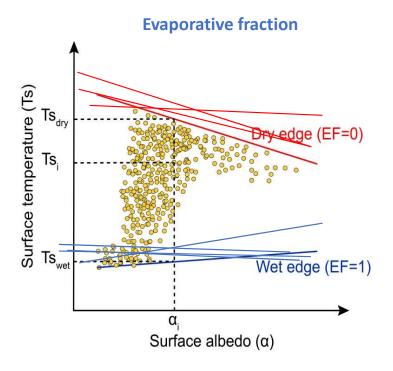
- Ground heat flux
 - Evaporative fraction EF

Agricultural area (~10 X 10 km)





Example 1 : Example of variations (=> uncertainties) in data sources and models



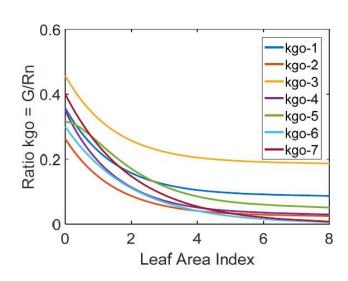
Novice case -> all available data or models are used

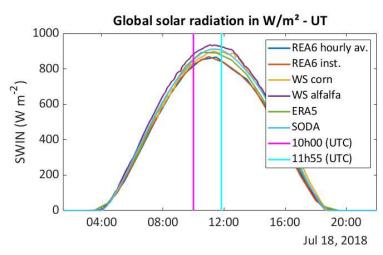
Expert case -> previous knowledge => some of the data sources

and algorithms are dropped

All together, ~400 000 cases (ET_i)

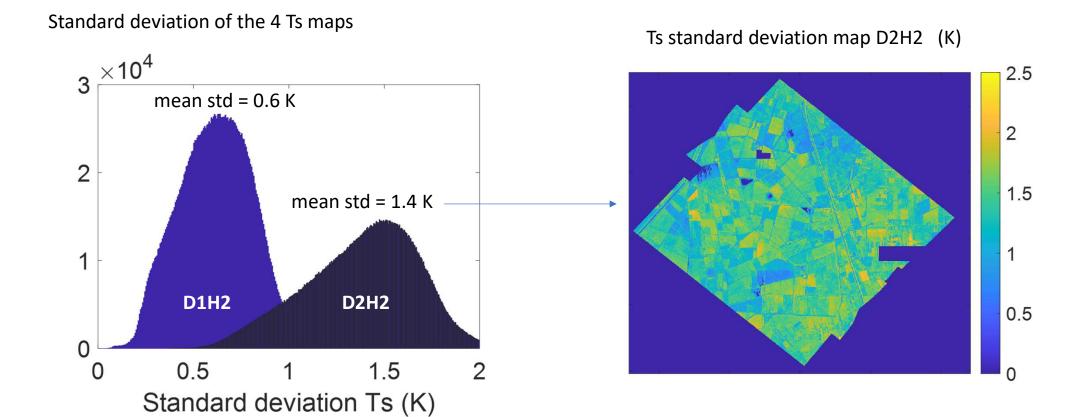
Ground heat flux ratio to Rn





Example 1 : Uncertainty in Ts:

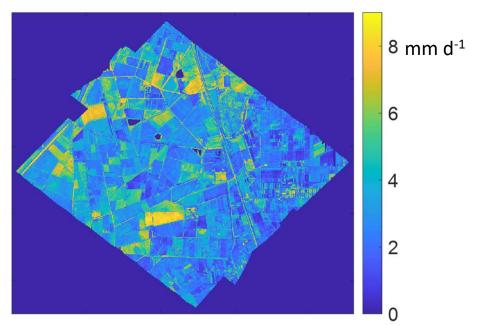
several processings were performed mainly differing in the atmospheric profiles used for the atmospheric corrections



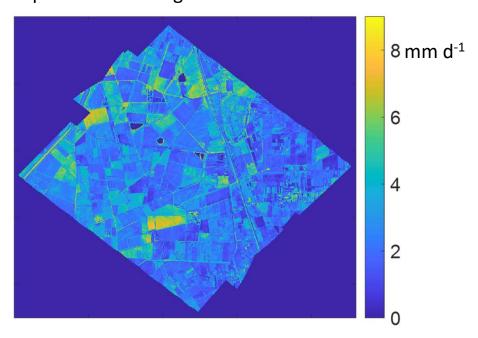
Example 1 : Evapotranspiration map

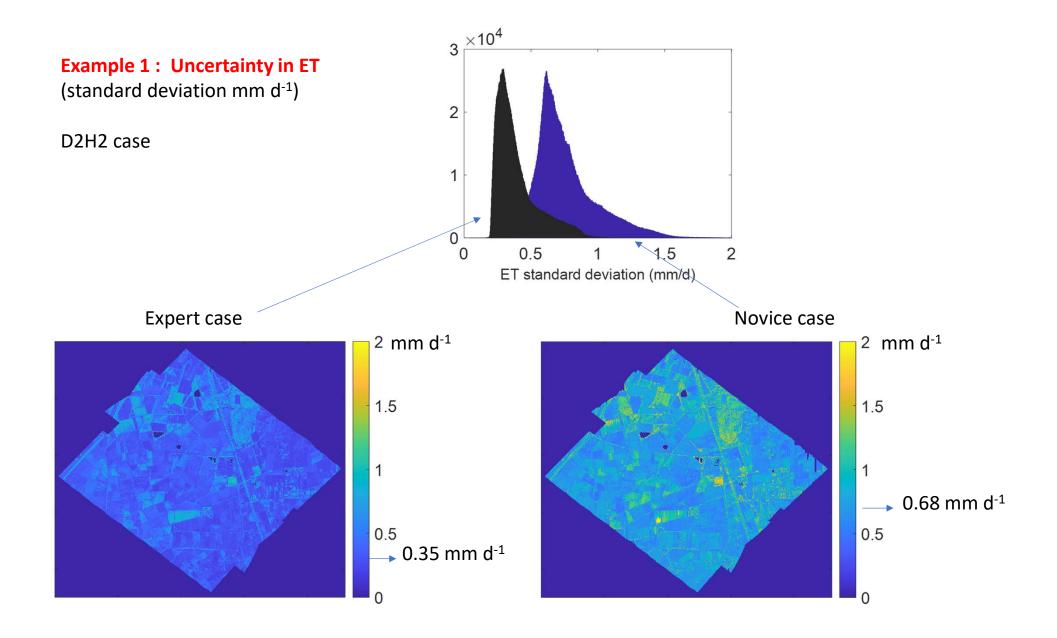
Average of all the calculations for D2H2

Novice case – average ET =3.4 mm d⁻¹

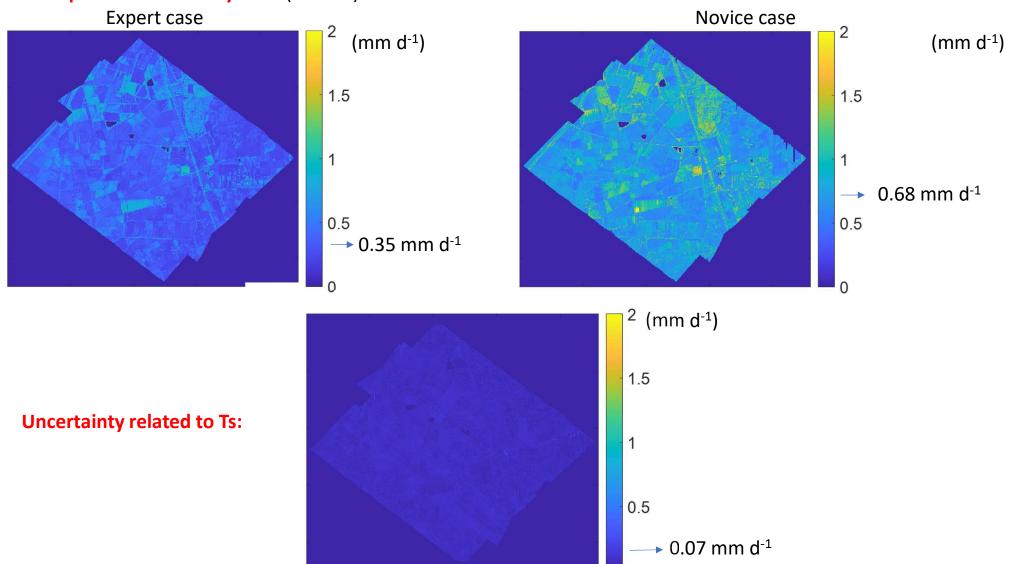


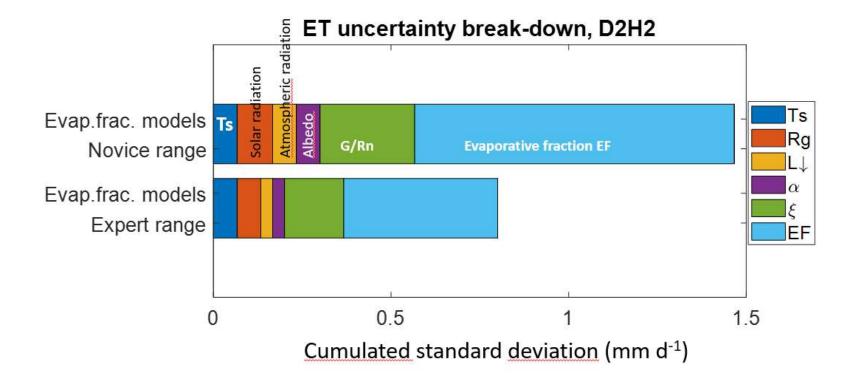
Expert case - average ET =2.8 mm d⁻¹





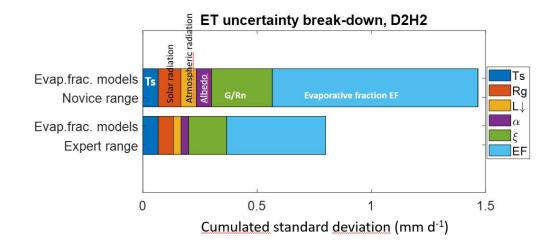
Example 1 : Uncertainty in ET (mm d⁻¹) D2H2 case





Example 1: Summary

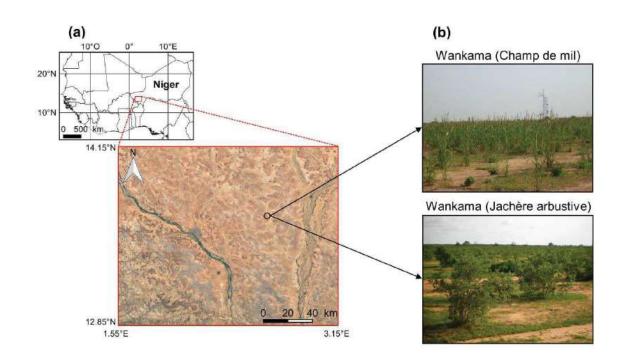
- uncertainty in ET is large, up to 1.5 mm.d⁻¹ (for D2H2 and when expressed as standard deviation)
- uncertainty is significantly lower in the expert case than in the novice case
- ranking of uncertainty sources highlights
- impact of Ts is low
- largest impacts: evaporative fraction, G/Rn ratio
 model formulations have a larger impact than input data



Example 2: application to Niger with MODIS data: Weighted averaging

Sahelian area

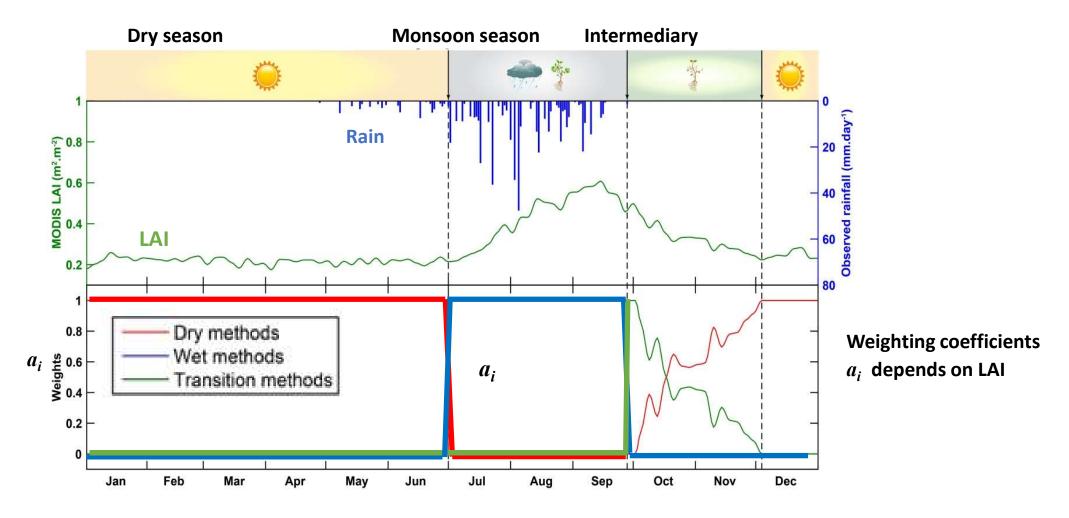
EVASPA -> variations in EF determination as a function of the season (dry, rainy = monsoon, intermediary...)



Evaluation against flux towers and comparison to other ET products

See papers by Allies et al. in Remote Sensing 2021 and Journal of Hydrology 2022

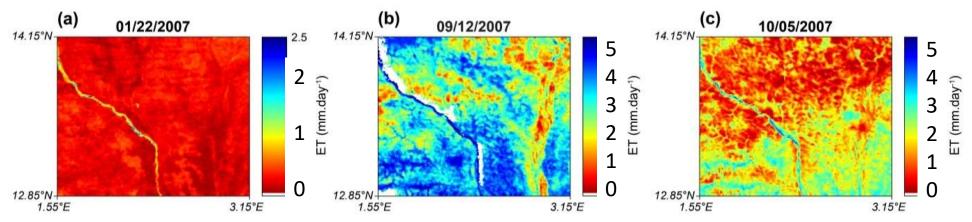
Example 2: EF calculation methods are more or less adapted to each season => a priori definition of the weighting coefficients



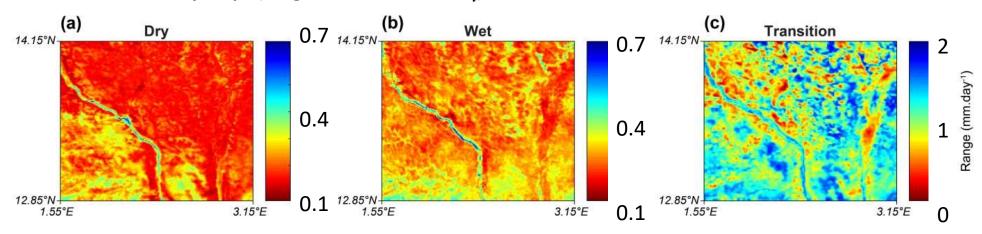
(Allies et al. 2021, Remote Sensing)

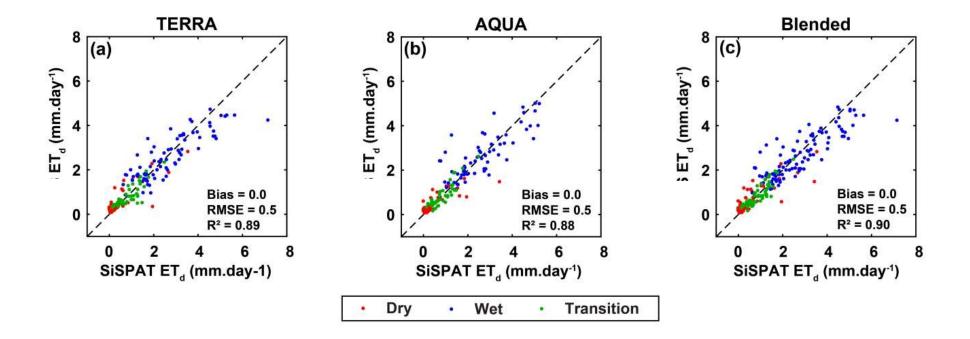
Example 2:

Top: ET maps (average)



Bottom: uncertainty maps (range of estimations ET_i)

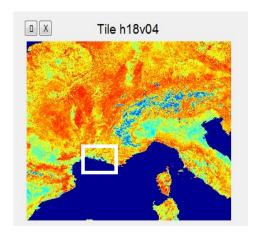




RMSE = 0.5 mm d^{-1}

Example 3: training weighting coefficients using in situ data (« bayesian » model averaging)

ET monitoring in wetlands of the Rhône river delta from MODIS data (sansouire : saltmarsh scrubs in Camargue)



EVASPA -> ensemble members ET_i calculated for various EF methods and incident radiation sources -> 42 members

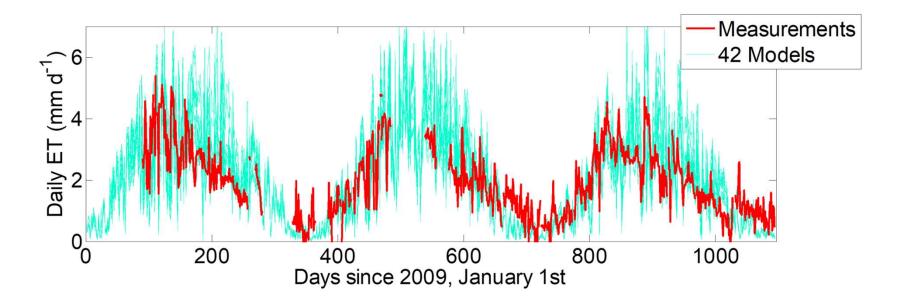
3 years dataset (2009 – 2011)

+ 20 year dataset for application in hydrological modelling

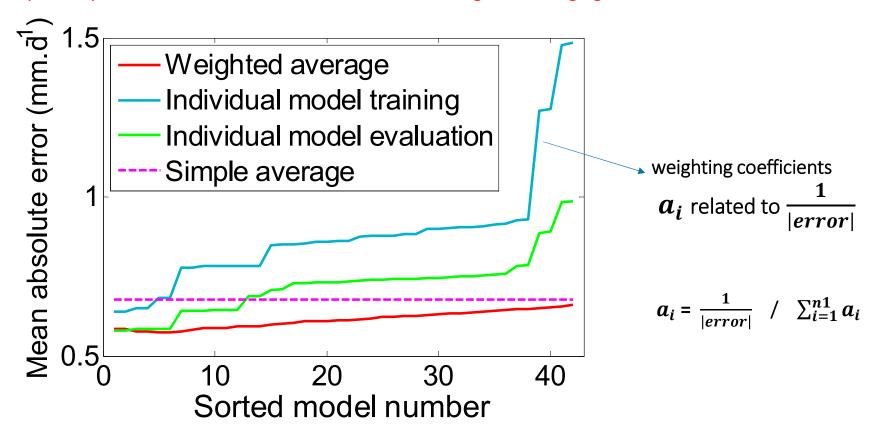


Example 3: Evapotranspiration estimations compared to in situ data

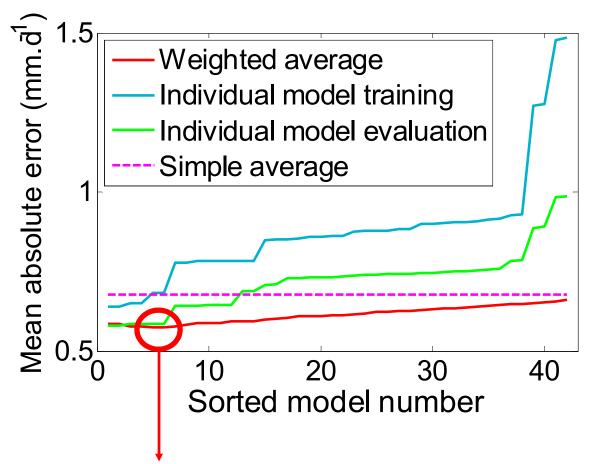
- MODIS data (Ts, albedo, NDVI)
- several EF models
- several incoming radiation 42 estimations of ET



Example 3: Evapotranspiration ensemble members evaluation, sorting and averaging



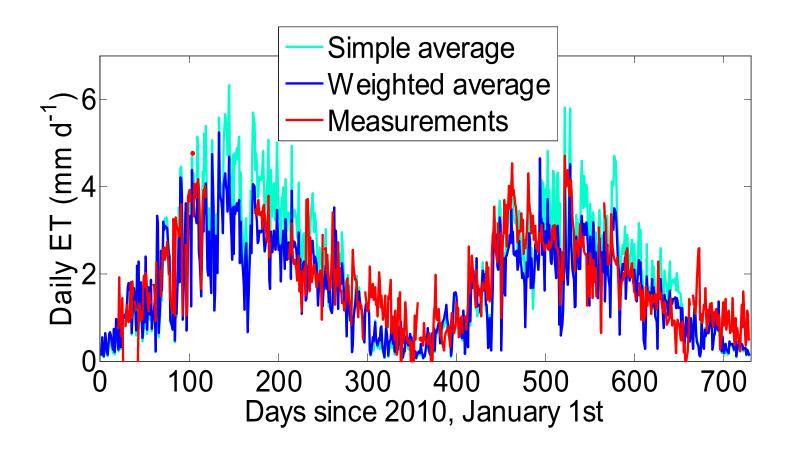
Example 3: Evapotranspiration ensemble members evaluation, sorting and averaging



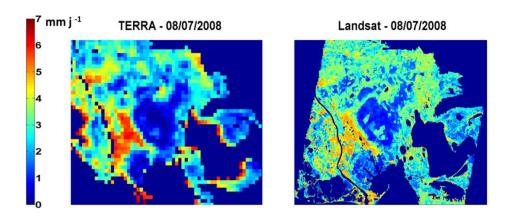
Best results in the training phase obtained by combining the 6 best members

 $RMSE = 0.57 \text{ mm d}^{-1}$

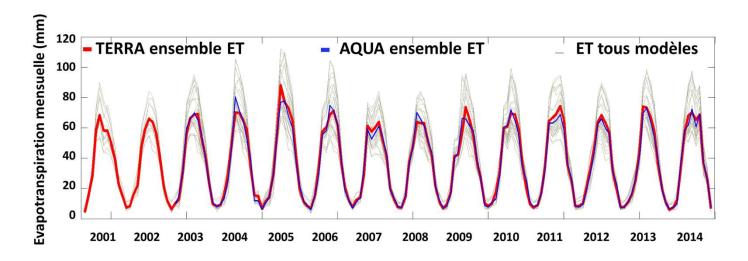
Example 3: Evaluation of ensemble ET and weighted ensemble ET



Applications to the whole area



Monthly ET obtained over the Crau aquifer (600 km²) for MODIS TERRA and MODIS AQUA data:



Summary

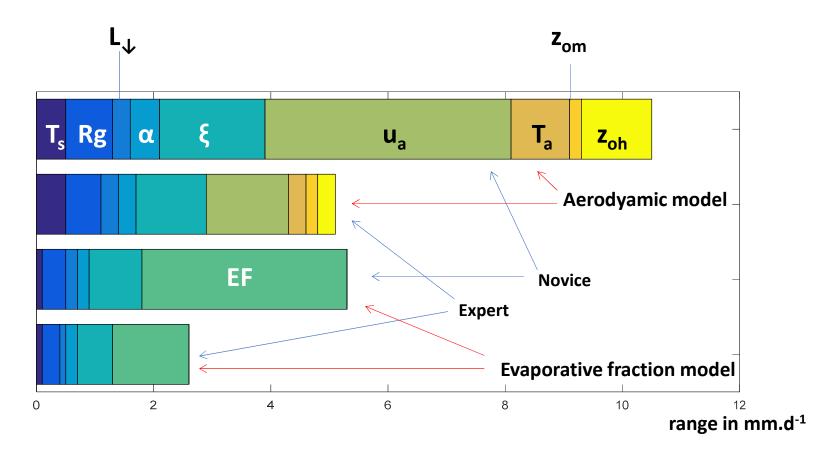
Ensemble modelling applied to multi-data source – multi-model (or algorithm) may be used for:

- monitoring ET
- providing uncertainty in the estimates (however this uncertainty is only epistemic and does not include estimation errors)
- providing information on the main uncertainty factors:
 - -in all analysed cases, surface temperature was not the main limitation in ET estimations

 - -for contextual models, the main sources of uncertainty concern algorithm (EF and ground heat flux) -for other models, including aerodynamic equations, meteorological forcing of wind speed and air temperature have also a strong impact (not shown here)

The EVASPA algorithm is a simple algorithm that will be the basis for implementing ET products in the frame of the **TRISHNA** program

Ranking of uncertainty sources



Uncertainty ranking for D2H1 (July 20th morning)

