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# Daily monitoring of Effective Green Area Index and Vegetation Chlorophyll Content from continuous acquisitions of a multi-band spectrometer over winter wheat

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1           **Daily monitoring of Effective Green Area Index and Vegetation**  
2           **Chlorophyll Content from continuous acquisitions of a multi-band**  
3           **spectrometer over winter wheat**

4  
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36 **Abstract**

37 Green area index (GAI), leaf chlorophyll content (LCC) and canopy chlorophyll content  
38 (CCC) are key variables that are closely related to crop growth. Concurrent and continuous  
39 monitoring of GAI, LCC and CCC is critical to keep consistency among variables and make  
40 decisions for field precision managements. Previous studies have developed several  
41 instruments and algorithms to monitor continuous GAI, while the autonomous monitoring of  
42 three variables simultaneously has been lacking. This study presents a novel algorithm to  
43 retrieve daily GAI, LCC and CCC from continuous directional observations acquired by a  
44 fixed and economic affordable multi-band spectrometer (6 bands covering red, red-edge and  
45 near infrared domains) and a photosynthetically active radiation (PAR) sensor in the field. It  
46 is composed of three main steps, corresponding to three crucial questions when retrieving  
47 variables under natural environments using multi-band spectrometer installed on a near-  
48 surface platform: diffuse fraction in each spectral band, radiometric calibration and diurnal  
49 sun variation of daily acquisitions. First, we estimated diffuse fraction in each spectral band  
50 from the relationship with PAR diffuse fraction based on simulations of the 6S atmospheric  
51 radiative transfer model. Second, we computed the relative value of each band to the  
52 reference of mean of measurements on all six bands from near-surface measurements, in place  
53 of absolute radiometric calibration to limit the influence of changing illumination conditions.  
54 In the third step, we combined PROSAIL canopy radiative transfer model and kernel-driven  
55 models to retrieved GAI, LCC and CCC from artificial neural network using above spectral  
56 diffuse fraction and diurnal multi-angle relative observations. The algorithm was evaluated  
57 over 43 IoTA (Internet of things for Agriculture) systems that were installed in 29 wheat  
58 fields in France from March to May 2019. Results showed that our method provides good  
59 estimates of GAI with root mean square error (RMSE) of 0.54, relative RMSE (RRMSE) of  
60 26.95%,  $R^2$  of 0.86, LCC (RMSE = 12.06  $\mu\text{g}/\text{cm}^2$ , RRMSE = 33.34%,  $R^2 = 0.52$ ) and CCC  
61 (RMSE = 0.23  $\text{g}/\text{m}^2$ , RRMSE = 24.58%,  $R^2 = 0.93$ ). This study shows great potentials for  
62 concurrent estimates of GAI, LCC and CCC from continuous ground measurements. It will be  
63 useful over other vegetations or other near-surface platforms for simultaneous estimations of  
64 biophysical variables.

65 **Keywords:**

66 Green Area Index (GAI), Leaf Chlorophyll Content (LCC), Canopy Chlorophyll Content  
67 (CCC), Daily measurements, Wheat, Near-surface system

## 68 **1 Introduction**

69 The world population is expected to reach about 10 billion by the end of 2050 (FAO,  
70 2017). This will require a huge boost of agricultural production to satisfy the population  
71 needs. To secure food supplies for the future and keep the sustainability of natural resources  
72 involved, agricultural technologies are rapidly evolving towards to a new paradigm-  
73 Agriculture 4.0 (Santos Valle and Kienzle, 2020). Daily, continuous and autonomous  
74 monitoring of crop state using near-surface monitoring system is a key component of this  
75 paradigm (Raj et al., 2021). Farmers could benefit from the daily measurements to monitor  
76 fields remotely, especially for those with inconvenient access. Sudden changes due to pests or  
77 diseases within the field of view of Internet-of-Things (IoT) systems can be promptly detected  
78 and intervened (Ojha et al., 2015). In addition, daily variables estimated from measurements  
79 can feed decision tools for precision fertilization, irrigation and harvest managements  
80 (Lemaire et al., 2021).

81 Leaf area index (LAI), leaf chlorophyll content (LCC) and canopy chlorophyll content  
82 (CCC) are three important variables that are closely related to the crop status. LAI represents  
83 one half of the total green leaf area per unit horizontal ground surface area (Chen and Black,  
84 1992) and it is an essential vegetation structural variable in several functioning processes  
85 (GCOS, 2011). In this study, we focus on Green Area Index (GAI) in place of LAI since we  
86 consider all the green parts of the plants that are involved in photosynthesis, including green  
87 leaves, stems and reproductive organs (Baret et al., 2010). LCC is the amount of chlorophyll *a*  
88 and *b* per unit leaf area ( $\mu\text{g}/\text{cm}^2$  leaf) and CCC is the canopy integrated chlorophyll content,  
89 which can be approximated as multiplication of GAI and LCC. Both are important  
90 physiological indicators and provide indirect estimations of leaf/canopy nitrogen content  
91 (Berger et al., 2020; Croft et al., 2017; Gitelson et al., 2014; Verrelst et al., 2021). In the  
92 context of precision agriculture, continuous and concurrent in-situ observations of GAI and  
93 LCC are key to achieve consistent estimates of CCC and capture crop structure and  
94 physiological status simultaneously (Darvishzadeh et al., 2012; M. Weiss et al., 2020; P.  
95 Zhang et al., 2021).

96 Substantial efforts have been made to develop automatic ground monitoring systems for  
97 observations of these variables. Continuous ground GAI can be measured through  
98 transmittance in a single band, e.g., PASTIS-57 (Fang et al., 2018; Raymaekers et al., 2014)  
99 and 4S (Kim et al., 2019), through above and below canopy photosynthetically active  
100 radiation (PAR)(Rogers et al., 2021), through gap fraction in RGB images (Chen et al., 2022;  
101 Wang et al., 2022), or digital camera traps (Chianucci et al., 2021; Niu et al., 2021; Ryu et al.,

102 2012). However, all these systems focus on GAI estimations solely and do not allow to  
103 provide concurrent continuous estimations of LCC and CCC. As LCC has been demonstrated  
104 to be strongly related to reflectance in red-edge and NIR bands (Gitelson, 2005; Main et al.,  
105 2011), using transmittance from PAR sensors or a single spectral band is not appropriate to  
106 derive accurate estimation of LCC or CCC. Alternatively, LCC estimations using RGB  
107 images was investigated in several studies (do Amaral et al., 2019; Guo et al., 2020; Sánchez-  
108 Sastre et al., 2020; Zheng et al., 2018). Although good correlations between RGB indices and  
109 LCC values were found, the empirical relationships were various and need to be calibrated  
110 depending on the experiment (Baresel et al., 2017; Rigon et al., 2016), limiting their  
111 applications in various locations autonomously.

112 Continuous and concurrent measurements of GAI, LCC and CCC require data from  
113 multiple spectral bands. Several automated field spectroscopy systems composed of high or  
114 ultra-high resolution spectrometers were developed to collect canopy reflectance and canopy  
115 sun-induced fluorescence signals (Campbell et al., 2019; Cogliati et al., 2015a; Grossmann et  
116 al., 2018a; Yang et al., 2018). However, these high-resolution spectrometers are designed for  
117 studying the SIF signal, which requires very accurate calibration and fine spectral resolution,  
118 with a cost ranging from 900\$ to 8000\$. Additionally, they are mounted on a tripod (Cogliati  
119 et al., 2015b) or towers (Campbell et al., 2019; Grossmann et al., 2018b; Yang et al., 2018),  
120 making them not practical when removing them for field management purposes. Therefore,  
121 the recent advances of low-cost and portable multi-band spectrometers provide an attractive  
122 option for assessing vegetation status by measuring the radiation reflected by the canopy  
123 autonomously in multiple wavebands ranging from visible to near infrared (NIR) (Fletcher  
124 and Fisher, 2018). The very low price of the sensor (e.g., less than 10\$ from the  
125 manufacturer) makes it possible to put several systems in the field to better capture the spatial  
126 heterogeneity. Additionally, this type of device can be easily installed in the field without  
127 requiring any specific knowledge from the user. Despite these advantages, only few studies  
128 attempted to use these sensors (Garrity et al., 2010; Heusinkveld et al., 2023; Kim et al.,  
129 2022). Relatively few investigations have been devoted for simultaneous estimation of GAI,  
130 LCC and CCC from similar multi-band spectrometers, especially under natural environment.  
131 Unlike the experiments in laboratory with controlled environment, the varying illumination  
132 conditions (e.g., totally clear, sparse clouds or overcast) are inevitable in natural environment.  
133 They may have significant impact on the observations, and proper attention must be paid to  
134 possible calibration issues when using radiative transfer model or vegetation indices to  
135 retrieve canopy traits. Indeed, three crucial questions need to be solved when retrieving

136 variables under natural environments using multi-band spectrometer installed on a near-  
137 surface platform.

138 (1) Contribution of the direct and the diffuse component of the irradiance in each spectral  
139 band: retrieving vegetation variables from radiative model inversion requires to compute  
140 the reflectance (Fang et al., 2019; Jay et al., 2017; J. Wang et al., 2022). Natural irradiance  
141 is actually composed of a direct component and a diffuse component, which should be  
142 taken into account when using near-surface monitoring systems (Durand et al., 2021;  
143 Schaepman-Strub et al., 2006). Although some studies have investigated the partitioning  
144 of the radiation into its diffuse and direct components in the full solar domain, applicable  
145 with a reasonable accuracy everywhere at the Earth's surface (Gueymard and Ruiz-Arias,  
146 2016; Yang and Gueymard, 2020), only few of them considered the PAR using data  
147 driven approaches calibrated on a single site experiment (Jacovides et al., 2010; Ma Lu et  
148 al., 2022; Spitters et al., 1986) or semi-empirical models (Oliphant and Stoy, 2018).

149 (2) Radiometric calibration: absolute radiometric calibration is a critical step to convert the  
150 radiance measured from spectrometer into reflectance, to limit the influence of changing  
151 illumination conditions. In the field, it can be achieved by performing radiance  
152 measurements over a Spectralon reference panel or a gray carpet with known reflectance  
153 placed close to the target (Cao et al., 2019; Li et al., 2021b; Peltoniemi et al., 2005;  
154 Sandmeier, 2000). However, this method is difficult to implement for continuous multi-  
155 band spectrometer monitoring in natural environments, because some calibration errors  
156 may be caused when the reference gets dirty and/or when its reflection properties change  
157 over time (Peltoniemi et al., 2005; Roosjen et al., 2017). When accurate radiometric  
158 calibration is not available, studies from Verger et al., (2014) and Jay et al., (2019)  
159 showed that using the ratio of the signal measured in a given band to the average of all  
160 measured bands or a single band, is an effective solution for retrieving vegetation  
161 variables.

162 (3) Diurnal variation of the sun position over the day: multiple sun viewing angles are  
163 available through continuous measurements in few minutes or hours steps. Many field  
164 instruments rely on the angular variations of the gap fraction either using the variation of  
165 the viewing or solar directions (Yan et al., 2019; Yin et al., 2017). This has also been  
166 investigated for multispectral observations from satellite and drones (Dorigo, 2012; Duan  
167 et al., 2014; Roosjen et al., 2018; Roujean and Lacaze, 2002; X. Zhang et al., 2021). But  
168 exploiting the dense diurnal sun variations of daily acquisitions using multi-band  
169 spectrometer has not been yet explored at our knowledge.

170 Under this context, the objective of this study is to find solutions to those three questions  
171 in order to develop a synthetic and practical algorithm to generate daily GAI, CCC and LCC  
172 from continuous ground measurements. We first present a method to partition the PAR  
173 incident radiation into its direct and diffuse component using a data driven approach. Then,  
174 we establish relationships between the diffuse fraction in the PAR domain and each spectral  
175 bands using the 6S radiative transfer model (Vermote et al., 1997). Then they were used in  
176 simulation of hemispherical-directional reflectance factor (HDRF) through a kernel-driven  
177 model (Roujean et al., 1992) and PROSAIL model (Jacquemoud et al., 2009). Both  
178 observations and simulations were converted into relative terms as a substitute of absolute  
179 radiometric calibration. Kernel parameters were calculated from the kernel-driven model and  
180 diurnal relative multi-band spectrometer measurements. The Artificial Neural Network  
181 (ANN) algorithm was employed to retrieve GAI, LCC and CCC from kernel parameters and  
182 geometric configurations. Using continuous multi-band spectrometer observations from IoTA  
183 (Internet of Things for Agriculture) systems over several wheat fields in France, we studied  
184 the robustness and accuracy of this algorithm. To evaluate the accuracy and uncertainties, we  
185 compared estimated diffuse fraction on each waveband, GAI, LCC and CCC with  
186 corresponding reference measurements.

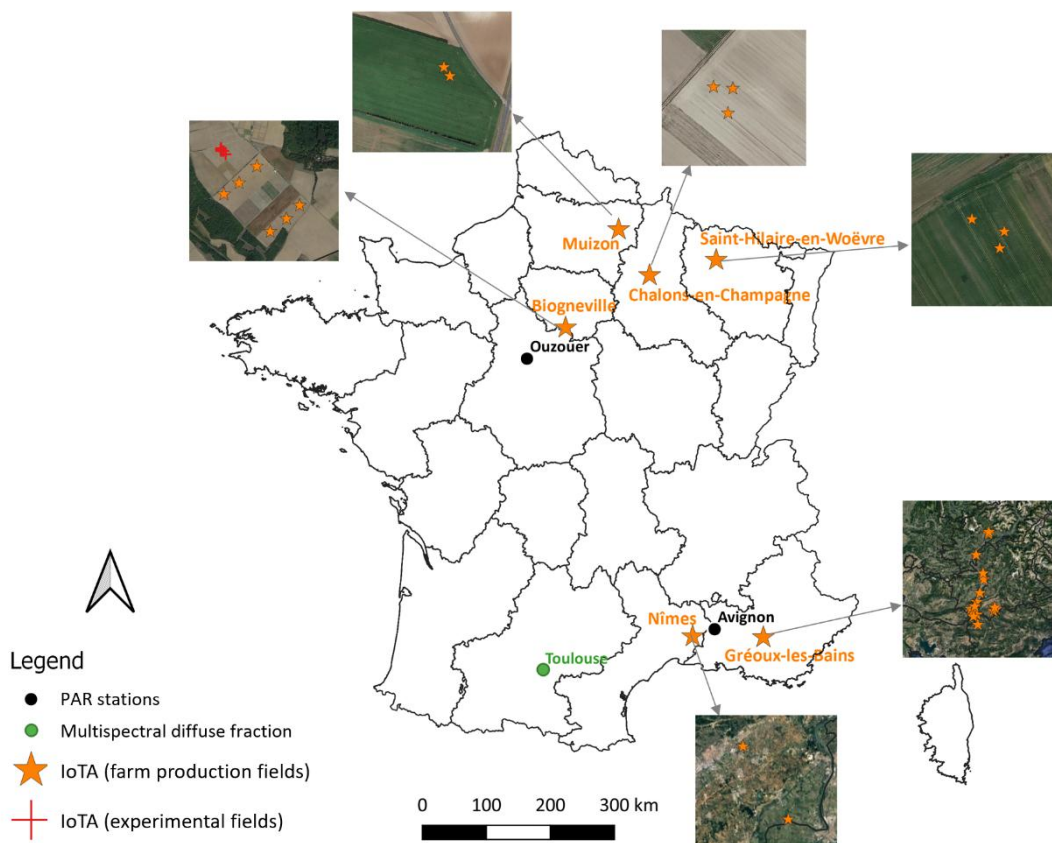
## 187 2 Experiments and measurements

### 188 2.1 Study area

189 The experiments were conducted in 2019 in winter wheat fields of six areas close to the  
190 following French cities: Gréoux-les-Bains (43.75 °N, 5.88 °E), Nîmes (43.8 °N, 4.36 °E),  
191 Boigneville (48.3 °N 2.4 °E), Muizon (49.27 °N, 3.89 °E), Chalons-en-Champagne (49.0 °N,  
192 4.4 °E) and Saint-Hilaire-en-Woëvre (49.1 °N, 5.7 °E) (Fig. 1). The Gréoux and Nîmes sites  
193 are characterized by a typical Mediterranean climate, with a maximum average temperature of  
194 20 °C (Meteo France). The Boigneville site has a more continental climate, with maximum  
195 average temperature of 15 °C. In Muizon, Chalons-en-Champagne and Saint-Hilaire-en-  
196 Woëvre, the climate is temperate and humid and the maximum average annual temperature is  
197 around 13°C.

198 In total, 43 IoTA systems were installed (Table S1). Six of them were located in small  
199 experimental fields of  $10 \times 2 \text{ m}^2$  size where wheat was fertilized with different amounts of  
200 nitrogen. The remaining 37 sensors were installed in farm fields, with a size around  $800 \times 200$   
201  $\text{m}^2$ . In the four northern sites, seven winter soft wheat (*Triticum aestivum*) cultivars were

202 grown. In the two southern sites, the fields were sown with three winter durum wheat  
 203 (*Triticum durum*) cultivars. The sowing dates varied from end of October to beginning of  
 204 November due to different planting practices and local weather. The IoTA measurement  
 205 campaign started from the end of March (beginning of growth) to mid- May 2019 (maximum  
 206 GAI) for most of the systems. Few of them were maintained on the field until the harvest date  
 207 (Table S1). The systems were placed sufficiently far from the field border so that no border  
 208 effect could impact the signal.  
 209



210  
 211 Fig. 1. The location of IoTA systems on production fields (orange stars) and experiment fields  
 212 (red crosses), PAR measurements (black filled circles) and spectral diffuse fraction  
 213 measurements (green filled circles) in 2019. Google Earth satellite were loaded from QGIS  
 214 and they do not represent images during the measurements.  
 215

## 216 2.2 Ground measurements

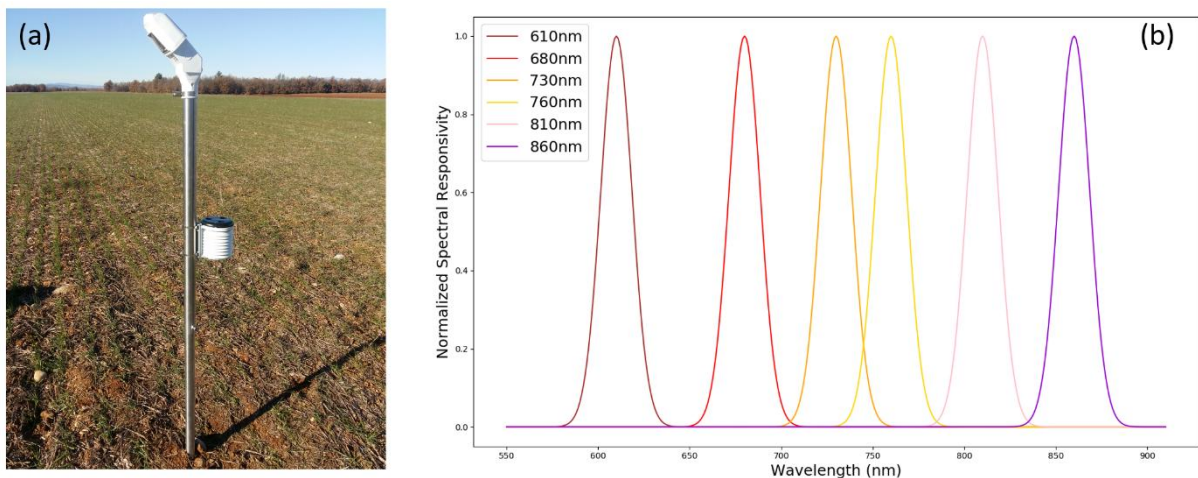
### 217 2.2.1 IoTA systems

218 The IoTA system, developed by the HIPHEN and Bosch companies, is an autonomous  
 219 system equipped with a miniature multispectral spectrometer, an upward looking



220 hemispherical PAR sensor, a meteorological sensor, as well as a RGB camera (Fig. 2a)  
221 (Velumani et al., 2020). It is powered by a battery that can provide continuous power support  
222 of 4 months. The multi-band spectrometer (AS7263 from AMS) is characterized by six  
223 wavebands, centered in the red (610 nm, 680 nm), red-edge (730 nm, 760 nm) and near  
224 infrared (810 nm, 860 nm) domains, with a full-width at half-maximum of 20 nm (Fig. 2b).  
225 More details about the spectrometer can be found in the producer website  
226 (<https://ams.com/as7263>).

227 The head of the IoTa was located 1.5 m above the ground, which roughly corresponded  
228 to a height of 0.5 m above canopy during the peak growth stage, (e.g., maximum height). It  
229 was oriented at a zenith angle of 45° from the vertical, with a ±20° field of view to allow  
230 enough spatial sampling, and positioned so that the azimuth direction was perpendicular to the  
231 row in the field in order to maximize the amount of vegetation seen by the sensor (Baret et al.,  
232 2010). The PAR sensor points vertically upwards to measure the downward flux radiation.  
233 Canopy reflected radiation and downwelling PAR were measured simultaneously every 15  
234 minutes during the whole campaign. The measurements were transferred automatically to a  
235 cloud storage system through a Global System for Mobile Communications (GSM) network.



236  
237 Fig. 2. (a) Illustration of an IoTa system installed in Gréoux (ID: FS-11, 43.797°N, 6.11°E,  
238 Table S1). The photo was taken at 12:37 on 11/12/2018. The head part inclined at 45° hosts  
239 the multi-band spectrometer and one RGB camera as described by Velumani et al., (2020) to  
240 monitor wheat phenology, in particular wheat heading. The cylinder box attached to the  
241 vertical pole was installed sensors to measure PAR, temperature and moisture. (b) Normalized  
242 spectral responsivity of each waveband of multispectral spectrometer.

## 243 2.2.2 PAR diffuse fraction

244 In this study, we used multi-year direct and diffuse PAR measurements acquired in  
245 meteorological weather stations located close to the experimental sites: Avignon (43.91 °N,  
246 4.88 °E) near Gréoux-les-Bains and Nîmes, and Ouzouer (47.92 °N, 1.53 °E) near Boigneville  
247 (Fig. 1). Measurements were continuously acquired every 15 minutes with a BF3 sunshine  
248 sensor (Delta-T Devices Ltd, 2002). After removing outliers (negative values and diffuse  
249 PAR larger than total PAR), we kept 89116 valid measurements performed between 2001 and  
250 2019 in the Avignon site and 10149 valid measurements performed in 2016 in the Ouzouer  
251 site. The PAR diffuse fraction was computed as the ratio of the diffuse PAR to the total PAR.

## 252 2.3 Validation datasets

### 253 2.3.1 Reference measurements of effective GAI, LCC and CCC

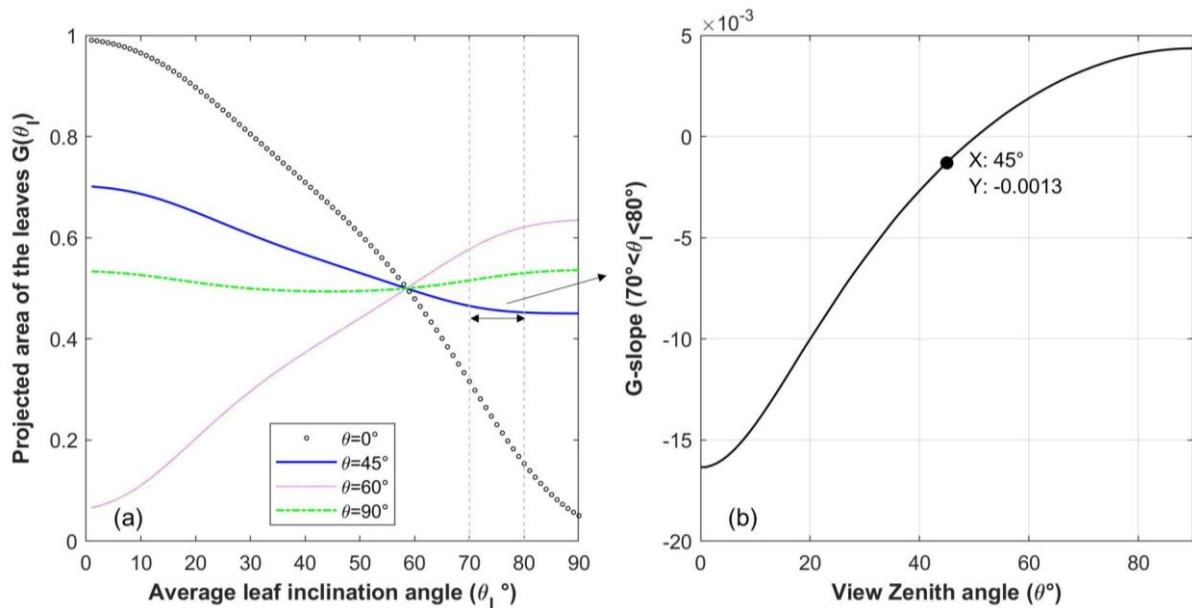
254 Reference effective GAI measurements were collected using downward-looking RGB  
255 cameras (Table S1) inclined at 45° zenith angle at around 1.5 m above the top of canopy,  
256 facing perpendicularly to the row. To maintain the 45° zenith direction during the acquisition,  
257 the cameras were mounted on a vertical monopod equipped with a spirit level. Three to five  
258 photos were taken in the area surrounding each IoT system, which was considered sufficient  
259 regarding the strong homogeneity of the sampled area. Although the segmentation algorithm  
260 is robust against illumination conditions (Madec et al., 2023; Serouart et al., 2022), all photos  
261 were taken between 10 am to 3 pm local time in order to reduce possible shadow impacts.

262 GAI was then estimated after applying a semantic segmentation to the images in order to  
263 separate the green vegetation from the background and inverting the Poisson model that  
264 relates the gap fraction  $GF$  in a direction  $\theta$  to GAI:

$$265 \quad GF(\theta) = \exp\left(-\frac{G(\theta_l, \theta) \cdot GAI}{\cos(\theta)}\right) \quad (1)$$

266 Where  $\theta$  is the view zenith angle,  $\theta_l$  is the average leaf inclination angle, and  $G(\theta_l, \theta)$  is  
267 the mean projection of a unit foliage area. We used the same methodology as Baret et al.  
268 (2010) who took advantage of a view zenith direction at 57.5° to get a direct gap fraction-GAI  
269 relationship which is independent of the leaf inclination (Weiss et al., 2004). However, for  
270 such high viewing angles, it is difficult to obtain accurate classification results for dense  
271 canopies ( $GAI > 3$ ) due to some saturation effects which prevent from discriminating  
272 accurately the green material from the background. Therefore, a lower viewing angle of 45°  
273 was preferred as it eases the image segmentation and still allows assuming that the G-function

274 is almost constant for wheat. Indeed, although wheat cultivars may present a range of leaf  
 275 inclination types between erectophile and planophile depending on the phenological stage, the  
 276 overall green material inclination (e.g. culms) was demonstrated to be erectophile (from  $70^\circ$   
 277 to  $80^\circ$ ), by Barillot et al. (2019). For this specific range, Fig. 3 shows that  $G(\theta_l, \theta)$  can be  
 278 assumed constant (G-slope = -0.0013).  
 279



280 Fig. 3. (a): Variation of the mean projection of the unit foliage area (G-function) with the  
 281 average leaf inclination (assuming an ellipsoidal leaf inclination distribution). (b): Slope of  
 282 the G-function for erectophile canopies ( $70^\circ < \theta_l < 80^\circ$ ) as a function of the view zenith  
 283 angle  $\theta$ .  
 284

285 The semantic segmentation of the gap fraction images relies on a deep learning approach  
 286 developed on wheat and described and evaluated by Serouart et al. (2022). This method was  
 287 composed of two steps. A U-net model was first trained over a large dataset to separate  
 288 vegetation from background. Then, a support vector machine was used to classify the  
 289 vegetation masks into green and non-green components. The training dataset of each step is  
 290 independent using wheat at different phenological stages in a variety of environments and  
 291 under different illuminations. The gap fraction of each RGB image was calculated as the ratio  
 292 of the number of non-green pixels to the total number of pixels in the image. The RGB  
 293 images used to derive the GAI were cropped so that the original vertical field of view was  
 294 restricted to  $45^\circ \pm 5^\circ$  to meet the constant-G assumption while ensuring enough spatial  
 295 sampling while the original horizontal field of view was restricted to  $\pm 20^\circ$  to meet the IoTA

296 characteristics (examples were shown in Fig. S1). This allowed us to remove blurred objects  
 297 at the border of image when the distance of the sensor to the vegetation is large. By  
 298 considering the image cropping in this study, we finally computed the equivalent coefficient  
 299 to derive GAI from the gap fraction (Eq. (3)), the latter being obtained from the segmented  
 300 cropped image as the ratio between the number of background pixels and the cropped image  
 301 size:

$$302 \quad \mathbf{GAI} = -\frac{\cos\theta}{G(\theta_l, \theta)} \ln(\mathbf{GF}(\theta)) \quad (2)$$

303 For  $\theta_l$  between  $70^\circ$  and  $80^\circ$ , and view zenith angle  $\theta$  between  $40^\circ$  and  $50^\circ$  (camera  
 304 inclination angle is  $45^\circ$  and we crop the images from the center to  $\pm 5^\circ$ ), Eq. (2) is  
 305 reformulated as:

$$307 \quad \mathbf{GAI} = -\frac{1}{\int_{70}^{80} \int_{40}^{50} \frac{G(\theta_l, \theta)}{\cos\theta} d\theta d\theta_l} \ln(\mathbf{GF}(\theta)), \text{ where } \int_{70}^{80} \int_{40}^{50} \frac{G(\theta_l, \theta)}{\cos\theta} d\theta d\theta_l = \mathbf{0.65} \quad (3)$$

308

309 GAI of each image was computed and mean value was used in the validation.

310 The leaf chlorophyll content was measured using the SPAD device (Minolta, 2009) with  
 311 a minimum of 15 leaves randomly located at the top of the canopy per sample within the field  
 312 of view of the IoTA during March 28 to June 18 in 2019. The SPAD measurement dates were  
 313 different among fields, but generally every 10 to 20 days on key growth stages. These SPAD  
 314 raw readings should be converted into content of chlorophyll ( $\mu\text{g}/\text{cm}^2$ ) using relationships  
 315 with absolute LCC measured in laboratory. Since there was no absolute LCC measurement in  
 316 this study, we proposed an ensemble method to compute the reference. First, we applied  
 317 multiple equations in literatures (Table S2) to convert our SPAD readings to LCC. Then the  
 318 median of all LCC from single SPAD reading was computed as reference to validate  
 319 corresponding IoTA retrieval. The standard deviation of LCC from different equations was  
 320 used as the uncertainty of the reference dataset. Only equations built with only wheat dataset  
 321 or including wheat were selected. The total canopy chlorophyll content ( $\text{g}/\text{m}^2$ ) was then  
 322 obtained by multiplying the GAI and the LCC that were measured within three days.

### 323 2.3.2 Reference measurements of multispectral camera diffuse fraction

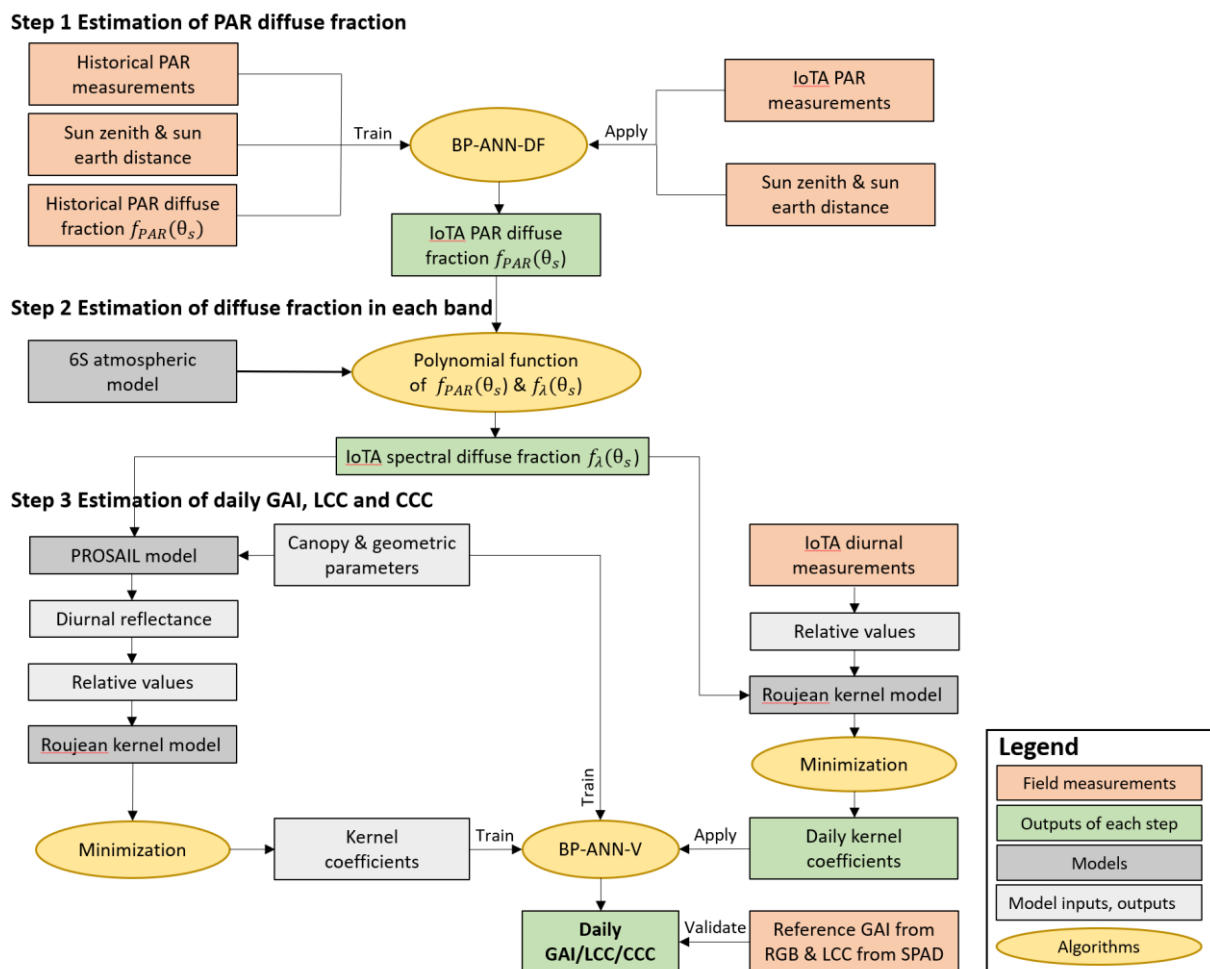
324 One important step of the algorithm is to estimate spectral diffuse fraction from IoTA  
 325 PAR measurements. We therefore used a multispectral sensor with band settings similar to  
 326 multi-band spectrometer to validate the accuracy of spectral diffuse fraction estimations. A  
 327 specific experiment was designed and conducted at the INRAE site of Toulouse ( $43.53^\circ\text{N}$ ,

328 1.50 °E) from the 31<sup>st</sup> July 2019 to 1<sup>st</sup> August 2019 (Lopez-Lozano et al., 2019). That period  
 329 corresponded to a changeable weather with various illumination conditions induced by  
 330 moving clouds during the whole morning on both dates. Measurements were acquired with  
 331 the AIRPHEN multispectral camera (<https://www.hiphen-plant.com/solutions/airphen/>) which  
 332 has six synchronized multispectral bands centered at 450 nm, 530 nm, 570 nm, 675 nm, 730  
 333 nm and 850 nm, with a full width at half maximum close to 10 nm (Li et al., 2021a), and thus  
 334 present some similarities with the IoTA systems (Fig. 2). More details about the experiment  
 335 are presented in Supplementary Materials Part B (Fig. S2, Table S3).

### 336 3 Methods

337 Our approach is split in three steps (Fig. 4): 1) estimation of the PAR diffuse fraction; 2)  
 338 the estimation of the spectral diffuse fraction in each IoTA band; and 3) the estimation of  
 339 daily GAI, LCC and CCC variables.

340  
 341



342  
 343 Fig. 4. Flowchart of retrieving daily GAI, LCC and CCC from IoTA measurements.

### 3.1 Step 1: Estimation of PAR diffuse fraction $f_{PAR}$

We first trained a neural network to directly estimate the PAR diffuse fraction using the ground total PAR ( $PAR_T$ ) measured by each IoTA without considering ancillary inputs. Similarly to [Jacovides et al. \(2010\)](#) who related global and diffuse PAR by fitting empirical functions, we used  $PAR_T$  as input and we complemented by the cosine of the sun zenith angle and the sun-Earth distance correction coefficient  $d(t)$  at each acquisition date ([Spitters et al., 1986](#)).  $d(t)$  is derived as

$$d(t) = \frac{1}{(1-0.01673 \times \cos(0.0172 \times (t-2)))^2} \quad (4)$$

where  $t$  is the Julian day corresponding to the acquisition date with reference of 01/01/1950. Indeed, adding  $d(t)$  as input improves the accuracy of estimation.

We used ground measurements of the instantaneous total and diffuse PAR acquired over multiple years described in Section 2.2.2 to generate the training database. The inputs included instantaneous total PAR,  $d(t)$  and optical path defined as the cosine of sun zenith angle, and the output was the instantaneous diffuse PAR. The database has in total 84587 cases, and it was divided into two parts: 69659 samples were randomly selected to train the neural network, and the remaining 14928 samples were used for overfitting control and evaluation of the theoretical performances.

We found that a Back Propagation Artificial Neural Network (BP-ANN) made of one hidden layer of four neurons characterized by a tangent-sigmoid transfer function followed by a single linear transfer function output neuron provided the best results, e.g., no overfitting and best accuracy. Ten BP-ANN-DF were trained and the performance using the training dataset was shown in [Fig. S3](#). The best one was selected based on the smallest root mean square error (RMSE) computed on the validation dataset. It was then applied to instantaneous PAR measured by each IoTA to estimate corresponding PAR diffuse fraction.

### 3.2 Step 2: Estimation of the diffuse fraction in each band $f_\lambda$

Step 2 consists in retrieving the diffuse fraction in each band  $f_\lambda$  from the PAR diffuse fraction estimated in step 1 (section 3.1). Based on the study by [Spitters et al. \(1986\)](#), we first isolated fully cloudy conditions and the other conditions. When  $f_{PAR}$  is greater than 0.9 (e.g. cloudy conditions),  $f_\lambda$  is assumed to be equal to  $f_{PAR}$ ; otherwise, the diffuse fraction in each band was estimated by using a polynomial function calibrated using simulations of 6S atmospheric correction model ([Vermote et al., 1997](#)).

375 Using 6S (version v2.1), we simulated the variation of the diffuse fraction by considering  
376 a range of aerosol optical thicknesses (e.g., visibility ranging from 1 km to 40 km by steps of  
377 2 km). We assumed a continental aerosol model that fits with the atmospheric characteristics  
378 of our areas of interest. For each sun zenith angle ranging from  $20^\circ$  to  $65^\circ$  with a step of  $5^\circ$ ,  
379 we simulated the direct and diffuse absolute irradiance over 400 – 900 nm and accounted for  
380 the spectral response function of each spectral band (e.g., of the IoTA or the AIRPHEN  
381 camera) to simulate the corresponding  $f_\lambda$ . Similarly, direct and diffuse PAR and  
382 corresponding  $f_{PAR}$  were computed by integration over the 400 - 700 nm range. We then  
383 fitted a five-degree polynomial between  $f_{PAR}$  and  $f_\lambda$  that we applied when  $f_{PAR}$  is lower than  
384 0.9 (Table S3).

### 385 3.3 Step 3: Estimation of daily GAI, LCC and CCC

#### 386 3.3.1 Generation of PROSAIL training database

387 Similarly to Li et al., (2015) and Weiss et al., (2020), a training database was simulated  
388 thanks to the PROSAIL radiative transfer model that couples PROSPECT (Jacquemoud and  
389 Baret, 1990) to simulate the leaf optical properties and SAIL (Verhoef, 1985, 1984) to  
390 generate top of canopy reflectance. Table 1 lists the range and distribution law for all  
391 variables of PROSAIL model. The soil reflectance data was simulated using five typical soil  
392 reflectance spectra multiplied by a brightness coefficient allowing to increase the diversity in  
393 actual soil properties (Weiss et al., 2020). This resulted in a total of 41472 combinations of  
394 canopy structures, leaf biophysical properties and backgrounds. For every combination, the  
395 hemispherical-directional reflectance  $\rho_{HDR,\lambda}(\theta_s, \theta_v, \phi)$  and bi-directional reflectance  
396  $\rho_{BRDF,\lambda}(\theta_s, \theta_v, \phi)$  at waveband  $\lambda$  (Schaepman-Strub et al., 2006) were computed for any sun-  
397 sensor geometry, defined by the sun zenith angle  $\theta_s$ , the view zenith angle  $\theta_v$  and the relative  
398 sun-sensor azimuth angle  $\phi$ . To consider the multiplicative or additive uncertainties of  
399 measured reflectance and get a more realistic canopy reflectance simulated value, an  
400 uncertainty model was used to describe the additive and multiplicative uncertainties based on  
401 a white Gaussian noise as previous studies (Li et al., 2015; Weiss et al., 2020).

402 To increase the realism of the distribution of  $f_\lambda$ , we relied on the IoTA measurements of  
403 the PAR diffuse fraction and sun positions to well sample the actual conditions of  
404 illuminations. From all available instantaneous real measurements, we totally extracted 2080  
405 daily combinations and each combination includes several instantaneous  $f_\lambda$ , corresponding  
406 sun zenith angle and relative azimuth angles during one day. Since the sampling interval of

407 acquisition is 15 minutes, each daily combination has at least 20 sets of instantaneous  $f_\lambda$ ,  
 408 corresponding sun zenith angle and relative azimuth angles, after removing outliers (e.g.,  
 409 negative  $f_\lambda$ , or  $f_\lambda > 1$ , or sun zenith angles larger than  $60^\circ$ ). The 2080 combinations were  
 410 repeated to a total size of 41472, randomly sorted. To note, the data in each combination don't  
 411 change. Then, they were combined with each of 41472 cases generated with the other  
 412 PROSAIL inputs. Finally, each simulation case is composed of variables for canopy  
 413 structures, leaf biophysical properties, backgrounds and a set of instantaneous  $f_\lambda$ ,  
 414 corresponding sun zenith angle and relative azimuth angles.

415

416 Table 1. List of variables and corresponding distribution laws to run the PROSAIL  
 417 simulations. Distribution laws are described by their mean and standard deviation (Std). ALA  
 418 = Average Leaf Angle inclination; HOT = Hot-spot parameter; N = leaf structure parameter;  
 419 Cdm = dry matter content; Cw\_Rel = relative leaf water content; Cbp = brown pigment  
 420 concentration; Bs = soil brightness.

421

	Variable	Minimum	Maximum	Law	Mean	Std
	GAI	0.0	7.0	Gauss	2.0	2.0
Canopy	ALA ( $^\circ$ )	60	80	Gauss	70	20
	HOT	0.1	0.5	Gauss	0.2	0.5
	N	1.20	1.80	Gauss	1.50	0.30
Leaf	Cab ( $\mu\text{g}\cdot\text{m}^{-2}$ )	20	80	Gauss	40	10
	Cdm ( $\text{g}\cdot\text{m}^{-2}$ )	0.003	0.011	Gauss	0.005	0.005
	Cw_Rel	0.60	0.85	Uniform	0.75	0.08
	Cbp	0.00	2.00	Gauss	0.00	0.30
Soil	Bs	0.50	3.50	Gauss	1.20	2.00

422

### 423 3.3.2 Setting up the neural network (BP-ANN-V) for GAI, CCC and LCC estimation

424 Because practical considerations to make the use of reference panels are not available  
 425 and the incoming irradiance is unknown, we cannot perform absolute calibration of the IoTA  
 426 spectrometer to derive reflectance values as simulated by PROSAIL. Therefore, we used the  
 427 ratio between the signal in a given band to the mean value over all bands according to [Verger](#)  
 428 [et al. \(2014\)](#):



$$\overline{X_\lambda(\theta_s, \theta_v, \phi)} = \frac{X_\lambda(\theta_s, \theta_v, \phi)}{\sum_{\lambda=1}^6 X_\lambda(\theta_s, \theta_v, \phi)/6} \quad (5)$$

where  $X_\lambda(\theta_s, \theta_v, \phi)$  is either the irradiance  $R_\lambda(\theta_s, \theta_v, \phi)$  measured by the IoTA spectrometer at waveband  $\lambda$ , at sun zenith angle  $\theta_s$ , view zenith angle  $\theta_v$  and relative sun-sensor azimuth angle  $\phi$ , or the reflectance  $\rho_\lambda(\theta_s, \theta_v, \phi)$  simulated by PROSAIL.  $\overline{X_\lambda(\theta_s, \theta_v, \phi)}$  represents the relative correspondence.

Due to operational constraints and computational costs, the inversion of the PROSAIL model is performed by training a machine learning algorithm as it is currently done in the remote sensing community (Verrelst et al., 2012). The machine learning algorithm must make use of the IoTA signal and sun geometry as inputs and the variable of interest (GAI, LCC and CCC) as output. Assuming that these variables are constant during a whole day, the whole set of 15 min acquisitions composed of six spectral bands and three angles varying from day to day, can be exploited for a single retrieval. This makes a huge set of inputs with strong correlations, suggesting to apply dimensionality reduction (May et al., 2011). Therefore, similarly to Weiss and Baret (1999), we used kernel driven BRDF models (Roujean et al., 1992) to reduce the dimensionality of the directional information. However, conversely to Weiss and Baret (1999) that was performed on satellite data, we needed to account for the contribution of the direct and diffuse components and used a modified version of kernel BRDF models (Dong et al., 2018).

The modeled  $X_\lambda(\theta_s, \theta_v, \phi)$ , denoted  $X_{mod,\lambda}(\theta_s, \theta_v, \phi)$ , is expressed as the sum of the diffuse and the direct contributions:

$$X_{mod,\lambda}(\theta_s, \theta_v, \phi) = f_\lambda(\theta_s) \cdot X_{HDR,\lambda}(\theta_v) + [1 - f_\lambda(\theta_s)] \cdot X_{BRDF,\lambda}(\theta_s, \theta_v, \phi) \quad (6)$$

where  $X_{HDR,\lambda}(\theta_v)$  and  $X_{BRDF,\lambda}(\theta_s, \theta_v, \phi)$  are, respectively, the canopy hemispherical-directional component and canopy bi-directional component (Schaeppman-Strub et al., 2006), and  $f_\lambda(\theta_s)$  is the diffuse fraction at wavelength  $\lambda$  and sun zenith angle  $\theta_s$ . According to Dong et al. (2018),  $X_{mod,\lambda}(\theta_s, \theta_v, \phi)$  in Eq. (6) can be simulated from a revised kernel-driven model :

$$X_{mod,\lambda}(\theta_s, \theta_v, \phi) = f_{iso,\lambda} + f_{vol,\lambda} K_{volDLC,\lambda}(\theta_s, \theta_v, \phi) + f_{geo,\lambda} K_{geoDLC,\lambda}(\theta_s, \theta_v, \phi) \quad (7)$$

where  $K_{volDLC,\lambda}$  and  $K_{geoDLC,\lambda}$  are diffuse-light correction (DLC) versions of original kernels of  $K_{vol,\lambda}$  and  $K_{geo,\lambda}$  present in Roujean et al. (1992). The DLC kernels are the sum of original kernels and their integrals over the illumination hemisphere weighted by  $f_\lambda(\theta_s)$  (Dong et al., 2018).  $f_{vol,\lambda}$  and  $f_{geo,\lambda}$  are, respectively, the coefficients of the  $K_{volDLC,\lambda}$  and  $K_{geoDLC,\lambda}$  (Roujean et al., 1992).

461 For either PROSAIL reflectance simulations or IoTA measurements, 18 kernel  
 462 coefficients (three kernels times six bands) were estimated from a series of acquisitions or  
 463 simulations by minimizing the following cost function:

$$464 J \left[ (f_{iso,\lambda}, f_{geo,\lambda}, f_{vol,\lambda})_{\lambda=1\dots6} \right] = \sum_{\theta_s, \theta_v, \phi} \sum_{\lambda=1}^6 \left[ \overline{X_{\lambda}(\theta_s, \theta_v, \phi)} - \overline{X_{mod,\lambda}(\theta_s, \theta_v, \phi)} \right]^2 \quad (8)$$

465 where  $\overline{X_{mod,\lambda}(\theta_s, \theta_v, \phi)}$  is the relative values obtained by combining Eq. 5 and Eq. 7. The  
 466 cost function  $J$  was minimized using Sequential Least Squares Programming algorithm  
 467 (Kraft, 1988).

468 In the case of PROSAIL reflectance simulations, kernel coefficients were estimated for  
 469 each case of the 41472 simulations that corresponds to a given set of acquisitions. In the case  
 470 of IoTA, only instantaneous measurements with sun zenith angle less than  $60^\circ$ ,  $f_{PAR}$  is  
 471 positive and lower than 1 and measurements are positive were treated as valid and used in the  
 472 estimation of kernel coefficients. Since the optimization algorithm requires at least 18  
 473 measurements for the estimation of 18 coefficients (3 kernel coefficients  $\times$  6 wavelengths) at  
 474 the same time, IoTA daily continuous observations acquired during a moving window of 1, 3,  
 475 5 or 7 days were used, assuming that the crop variables remain stable during this short period.  
 476 The sensitivity of kernel parameter estimation to the size of moving window was evaluated by  
 477 computing the RMSE between simulations from kernel parameters and real IoTA  
 478 measurements.

### 479 3.3.3 Training and applying the BP-ANN-V

480 Following Weiss and Baret (1999) and Li et al. (2015), we trained one BP-ANN-V per  
 481 each variable. The training database was divided into two parts: two thirds of the simulations  
 482 were randomly selected to train the neural network and the remaining one third was used for  
 483 validation. The inputs were the 18 kernel parameters, and the output was either GAI, LCC or  
 484 CCC. Each neural network was made of one input layer, one hidden layer composed of 5  
 485 neurons with tangent sigmoid transfer functions and one output layer with a linear transfer  
 486 function. For each output variable, ten networks were trained with different initial guess of the  
 487 weight. They were applied to kernel parameters derived from diurnal IoTA measurements  
 488 and the median of inversions from ten networks was computed as the final result, which  
 489 allows better generalization capacities.

490 We kept only field measurements for which the BP-ANN-V estimates are within a given  
 491 range described in (Table 2) and that the kernel parameters obtained from the IoTA systems  
 492 fall within the range of those obtained from the PROSAIL simulations.

493 Table 2. The minimum, maximum values and tolerance for each output product.

	Unit	Minimum	Maximum
GAI	m <sup>2</sup> /m <sup>2</sup>	0	7
LCC	μg/cm <sup>2</sup>	0	80
CCC	g/m <sup>2</sup>	0	5.6

494 **3.4 Evaluation procedures**

495 Model accuracy was assessed thanks to different statistics: coefficient of determination  
 496 ( $R^2$ ), bias and root mean squared error (RMSE), Relative bias which is the ratio between bias  
 497 and average of reference, and relative RMSE which is the ratio of RMSE to average of  
 498 references are also computed to provide further evaluation information.

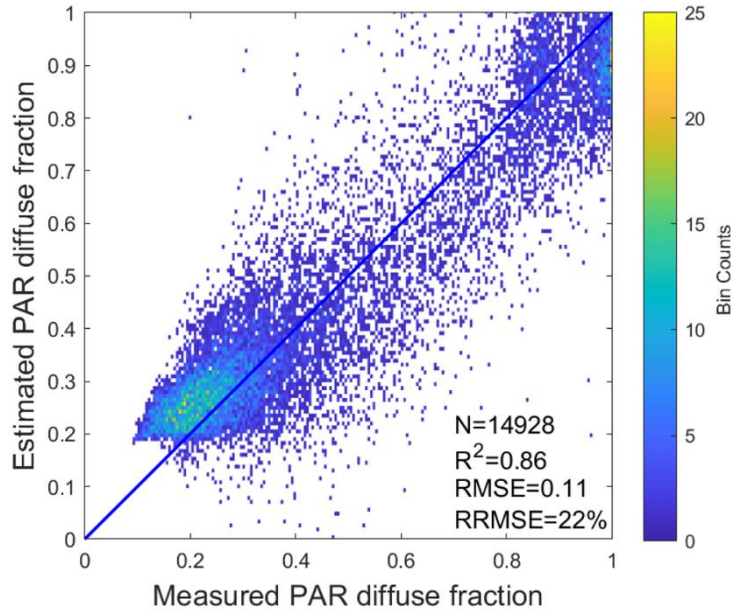
499

500 **4 Results**

501 **4.1 Diffuse fraction from incoming PAR measurements**

502 4.1.1 PAR diffuse fraction

503 The results presented in Fig. 5 show that, over our experimental sites, the PAR diffuse  
 504 fraction can be accurately estimated from the total PAR, sun zenith angle and a correction  
 505 coefficient accounting for variations in sun-Earth distance, using the BP-ANN-DF neural  
 506 network ( $R^2 = 0.86$ ,  $RMSE = 0.11$ ). Our dataset mainly includes low diffuse fraction values  
 507 (lower than 0.5), mostly corresponding to the Avignon site in Southern France characterized  
 508 by frequent sunny illumination conditions and small aerosol concentration values, and very  
 509 high diffuse fraction values (greater than 0.9), mostly corresponding to the Ouzouer site in  
 510 Northern France which presents frequent overcast illumination conditions. Additional  
 511 medium PAR diffuse fraction measurements might thus be required to ensure a similar  
 512 accuracy over the intermediate range of values.



513

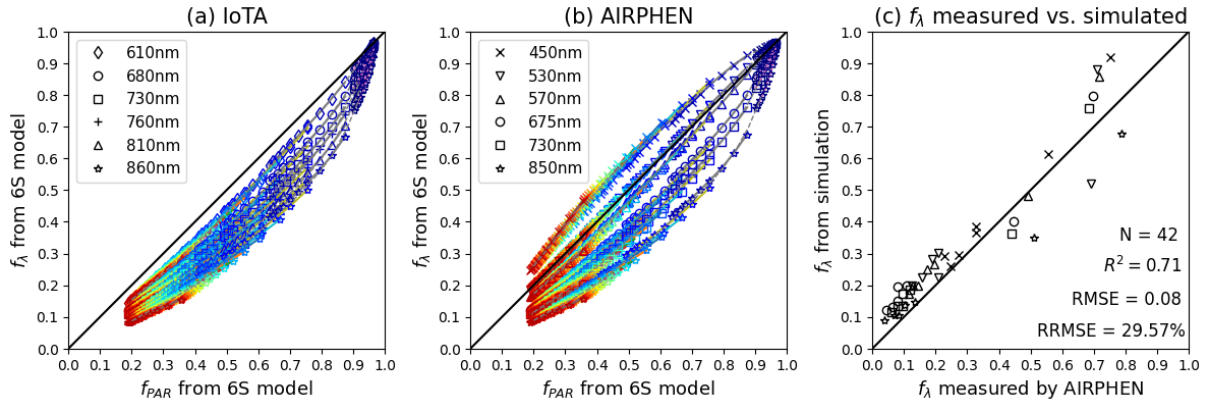
514 Fig. 5. Performances of PAR diffuse fraction estimation from neural networks (BP-ANN-DF)  
 515 over the validation dataset (Avignon-Ouzouer measurements). Colors correspond to the  
 516 number of data available for a given  $f_{PAR}$  value.

517

#### 518 4.1.2 Spectral diffuse fraction

519 The relationship between  $f_{PAR}$  and  $f_{\lambda}$  was evaluated both using 6S model simulations in  
 520 IoTA and AIRPHEN spectral bands, and using AIRPHEN camera ground measurements.  
 521 Results from the 6S model simulations show that the  $f_{\lambda}$  is related to  $f_{PAR}$  through a  
 522 polynomial relationship for IoTA (Fig. 6a) and the AIRPHEN camera (Fig. 6b). Under high to  
 523 medium visibility conditions (e.g.,  $f_{PAR} < 0.9$ ), the PAR diffuse fraction is systematically  
 524 higher than  $f_{\lambda}$  for the red to NIR domain and the difference increases with the wavelength due  
 525 to the decreasing influence of aerosol effects. Accordingly, the PAR diffuse fraction is lower  
 526 than  $f_{\lambda 450nm}$  and is close to that at in the green wavelengths (530 nm and 570 nm). Under  
 527 very low visibility sky conditions (e.g.,  $f_{PAR} \geq 0.9$ ),  $f_{\lambda}$  is almost equal to the PAR diffuse  
 528 fraction for all the bands. We evaluated the fitted polynomial functions derived from 6S  
 529 simulations using ground measurements acquired with the AIRPHEN camera (Fig. 6c). The  
 530 spectral diffuse fractions were estimated with  $R^2 = 0.71$ ,  $RMSE = 0.08$  and relative  $RMSE =$   
 531  $29.57\%$  (Fig. 6c) for all the six bands together, using the polynomial relationships presented  
 532 in Table S3. The validation performance in each band was shown in Table 3. In general, all  
 533 bands have good correlations with references ( $R^2 \geq 0.83$  and  $RMSE \leq 0.11$ ).

534



535

536 Fig. 6. Comparison between PAR diffuse fraction ( $f_{PAR}$ ) and spectral diffuse fraction ( $f_{\lambda}$ )  
 537 obtained from 6S model simulations for (a) the IoTA spectral bands and (b) the AIRPHEN  
 538 camera bands. Different colors represent the visibility input to 6S model, while gray lines  
 539 show the fitted polynomial relationships. (c) Spectral diffuse fractions estimated from  
 540 polynomial relationships versus the ones measured by the AIRPHEN camera using PAR  
 541 diffuse fraction of 0.9 as the threshold value to discriminate the cloudy conditions.  $R^2$ , RMSE  
 542 and RRMSE were computed over all bands. RRMSE is relative RMSE calculated as the ratio  
 543 between RMSE and average value.

544

545 Table 3. Statistics of comparison between simulated  $f_{\lambda}$  and measured  $f_{\lambda}$  of each wavelength  
 546 of AIRPHEN camera. RRMSE is relative RMSE calculated as the ratio between RMSE and  
 547 average of references.

	450 nm	530 nm	570 nm	675 nm	730 nm	850 nm
$R^2$	0.99	0.83	0.97	0.96	0.95	0.97
RMSE	0.08	0.11	0.08	0.08	0.06	0.08
RRMSE (%)	19.63	33.73	27.87	38.52	28.64	31.70

548

549

## 550 4.2 Suitability of kernel BRDF model parameters to be used as inputs to BP-ANN-V

551 We first retrieved the kernel BRDF model parameters in each spectral band and then  
 552 reconstructed the corresponding relative reflectances that were compared to the initial relative  
 553 reflectances simulated with PROSAIL. Results were very consistent with  $R^2 = 0.99$  and an  
 554 overall relative  $RMSE = 0.32\%$  over all the wavelengths (Fig. S6). For each individual  
 555 wavelength, a very good correspondence was also observed (Table 4). The performance was  
 556 better on red-edge and NIR bands (relative  $RMSE < 1\%$ ), compared to the red bands (relative

557 RMSE > 1%). This indicates the kernel parameters can reconstructed the reflectance from  
 558 PROSAIL model, thus can replace the reflectance from PROSAIL model in the inversion of  
 559 biophysical variables. It also implies the good performance of the optimization methods  
 560 applied on kernel-driven models.

561

562 Table 4. Statistics between relative reflectances ( $\bar{\rho}$ ) obtained from PROSAIL simulations and  
 563 reconstructed after BRDF kernel model inversion for each IoTA spectral band.

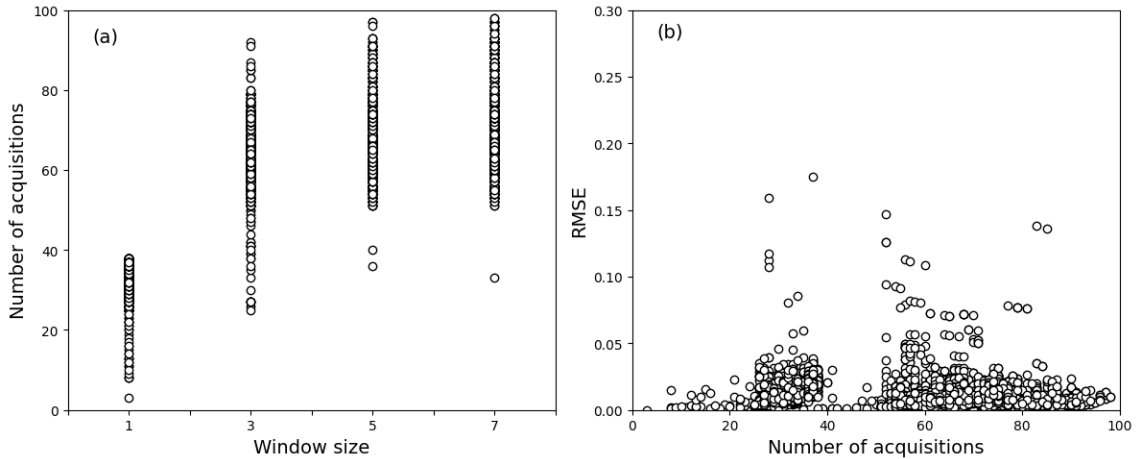
	610 nm	680 nm	730 nm	760 nm	810 nm	860 nm
$R^2$	0.999	0.999	0.999	0.999	0.999	0.999
RMSE	0.004	0.005	0.003	0.003	0.004	0.005
RRMSE (%)	1.87	1.11	0.35	0.21	0.23	0.32

564

565 The same exercise was applied to the IoTA measurements: we estimated the kernel  
 566 BRDF model parameters using each set of measurements determined by the size of the  
 567 moving window used (1, 3, 5, or 7 days). Like the regression in Fig. S6, the kernel model  
 568 simulations also correspond very well with the measurements from IoTA relative  
 569 measurements ( $R^2 > 0.98$ ). The regression figure was therefore not shown for the sake of  
 570 brevity. In order to further evaluate the performance of the optimization algorithm, we  
 571 calculated the RMSE and used it to set a strict criterion to remove some outliers and select the  
 572 best moving window size. The RMSE between kernel model simulated relative values and  
 573 IoTA relative measurements over all bands ranges from 0 to 0.17 depending on the window  
 574 size (Fig. 7). The median RMSE (0.009 – 0.014 in Fig. S7) was obviously larger than the  
 575 0.005 RMSE from PROSAIL model simulations because of the noise associated to the ground  
 576 measurements. Although one white noise was added in the PROSAIL absolute reflectance,  
 577 there are no quantitative results demonstrating the propagated uncertainties that includes all  
 578 potential noises in the field, e.g., the diffuse fraction estimation, spectrometer intra-calibration  
 579 among bands and noise co-distributions between bands.

580 The choice of the size of the moving windows is a compromise between the number of  
 581 acquisitions used to retrieve the BRDF kernel parameters and the length of the window during  
 582 which the canopy biophysical variable is assumed constant. When the window size increases  
 583 from 1-day to 7-day, the number of acquisitions that could be used in the estimations almost  
 584 doubles (Fig. 7a). The performance of kernel BRDF model inversion also varies with the  
 585 number of acquisitions (Fig. 7b). When using a single day of acquisition, the RMSE  
 586 fluctuates with a median RMSE of 0.014 (Fig. S7). Adding more measurements as inputs to

587 the optimization algorithm is helpful to find the local minimum. These results are improved  
 588 when increasing the length of the moving window with very similar RMSE of 0.009 between  
 589 3-, 5- or 7-day window size. We therefore selected the 3-day window as the best compromise  
 590 between accuracy and the assumption that GAI, CCC and LCC remain constant during that  
 591 period.



592  
 593 Fig. 7. (a) Number of IoTA acquisitions for each moving window size of 1, 3, 5, and 7 days;  
 594 (b) Relationship between number of acquisitions with the RMSE calculated between the  
 595 measured relative signal and kernel model reconstructed relative signal using moving window  
 596 size of 1, 3, 5, and 7 days for the IoTA systems during the experiment campaign.

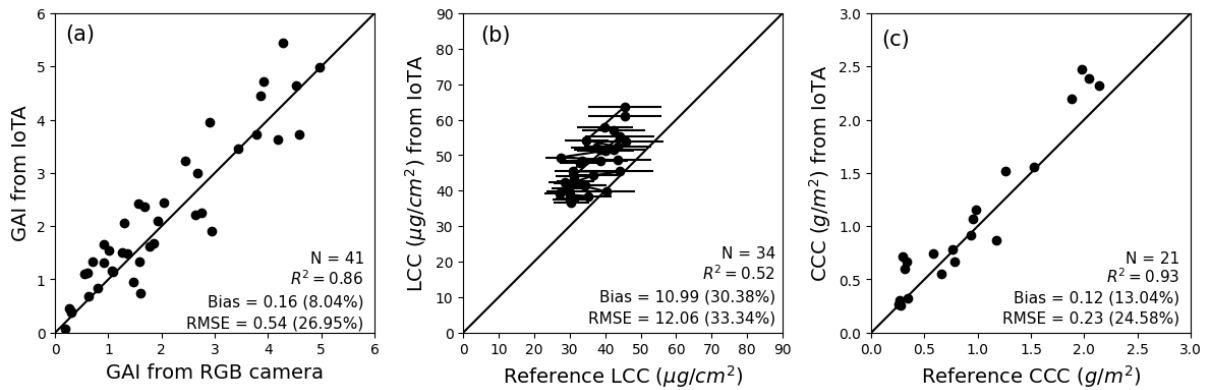
### 597 4.3 Validation against ground measurements

598 The retrieved biophysical variables were compared with the corresponding ground  
 599 measurements at the same dates. The GAI estimated from IoTA systems has a very good  
 600 consistency with the field data taken by RGB cameras ( $R^2 = 0.86$ ,  $RMSE = 0.54$ , relative  
 601  $RMSE = 26.95\%$ , Fig. 8a).

602 The LCC retrieval from IoTA has very similar correspondences with reference LCC  
 603 converted using various equations ( $R^2 = 0.51 - 0.53$ ) but quite different scattering and biases  
 604 ( $RMSE = 5.59 \mu\text{g}/\text{cm}^2 - 18.94 \mu\text{g}/\text{cm}^2$ , relative  $RMSE = 12.08\% - 65.51\%$ ) (Fig. S8). The  
 605 best correlation and minimum RMSE was obtained using calibration equation No. 4 and 12,  
 606 while the largest RMSE was found using equation No. 6. Using proposed ensemble method  
 607 which took the median of all equations as the reference, IoTA LCC exhibits a good  
 608 correlation but a systematic overestimation ( $R^2 = 0.52$ ,  $RMSE = 12.06 \mu\text{g}/\text{cm}^2$ , relative  $RMSE$   
 609  $= 33.34\%$ ) (Fig. 8b). The uncertainty of reference LCC ranges from  $4.21 \mu\text{g}/\text{cm}^2$  to  $11.78$   
 610  $\mu\text{g}/\text{cm}^2$ , and the overall uncertainty is  $7.44 \mu\text{g}/\text{cm}^2$ .

611 Conversely to LCC, the chlorophyll content at canopy level presents a good  
 612 correspondence between ground reference datasets and estimations from IoTA systems ( $R^2 =$   
 613  $0.93$ ,  $RMSE = 0.25 \text{ g/m}^2$ , relative  $RMSE = 26.12\%$ , Fig. 8c). Since the RGB images and  
 614 SPAD measurements were taken on different dates and sites, only few measurements can be  
 615 used to calculate the ground CCC values. In this study, we used the SPAD LCC and RGB  
 616 GAI values measured within 3 days to compute CCC, assuming wheat status was stable  
 617 during this period. This assumption is consistent with 3-day moving in the proposed algorithm  
 618 (section 3.3).

619



620

621 Fig. 8. Direct validation of (a) GAI, (b) leaf chlorophyll content and (c) canopy chlorophyll  
 622 content derived from IoTA with the ground validation dataset. The dark line is the 1:1 line. In  
 623 (b), error bars represent the standard deviation of LCC converted from all equations shown in  
 624 Table S2. In (c), ground CCC was calculated from chlorophyll meter derived LCC and RGB  
 625 camera derived GAI within 3 days assuming wheat status was stable during this short period.

626

627 When calculating relative values of IoTA measurements or PROSAIL simulations ( $\overline{X_\lambda(\theta_s, \theta_v, \phi)}$ ), we used the average of all bands as denominator (Eq. (4)), as Verger et al.  
 628 (2014) using multispectral camera onboard a drone. However, Jay et al. (2019) used 850 nm  
 629 band of AIRPHEN camera as the denominator to compute relative values. Regarding to IoTA  
 630 systems, we compared the inverted GAI, LCC and CCC from different relative values using  
 631 average or single band as reference with ground measurements (Table 5). Results show that  
 632 the performances are similar for GAI,  $R^2$  ranging from 0.83 to 0.86. The differences are  
 633 slightly larger for LCC, that using 810 nm and 860 nm as reference has the lowest  
 634 correspondence ( $R^2$  is around 0.4 to 0.42). For CCC, using average of all bands or 610 nm or  
 635 680 nm has similar better accuracy. Overall, using average of all bands as reference has best  
 636 performance for the three variables in this study.

637



638 Table 5. Comparison of direct validation accuracy of GAI, LCC and CCC, estimated from  
 639 relative measurements using reference of mean of all bands and each single band.

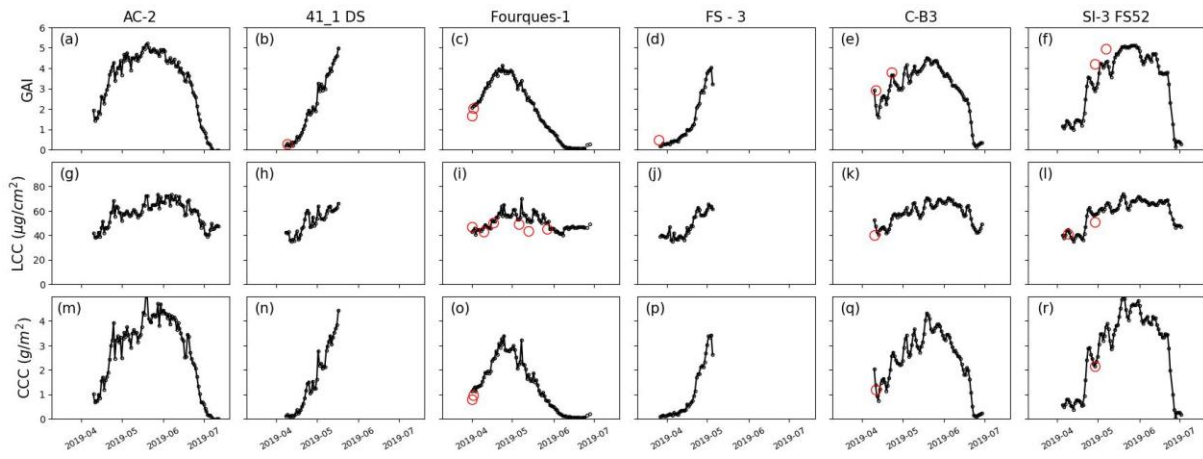
Reference to compute relative values (nm)	GAI		LCC		CCC	
	R <sup>2</sup>	RMSE	R <sup>2</sup>	RMSE	R <sup>2</sup>	RMSE
Average	0.86	0.51	0.52	8.44	0.93	0.25
610	0.85	0.56	0.47	9.52	0.91	0.26
680	0.83	0.58	0.47	8.74	0.91	0.26
730	0.83	0.56	0.48	9.02	0.79	0.32
760	0.85	0.55	0.52	9.72	0.8	0.31
810	0.83	0.55	0.4	9.73	0.8	0.33
860	0.83	0.59	0.42	10.53	0.78	0.34

640

#### 641 4.4 Continuous monitoring of GAI, LCC and CCC with IoTA systems

642 Temporal profiles of GAI, LCC and CCC over four sample sites are shown in Fig. 9.  
 643 Results show that the profiles capture well the expected seasonal variation of each variable.  
 644 Differences of GAI trends are observed among sites on the maximum values and the peak  
 645 growth period, for example, maximum GAI around 5 of AC-2 arrives on mid of May, while  
 646 the GAI of Fourques-1 and FS-3 sites increases from the beginning of April to a peak value of  
 647 4 in beginning of May. These differences among sites are mainly due to wheat variety,  
 648 climate, management practices and available measurement periods (Table S1). LCC also  
 649 presents seasonal variations although the data intervals are narrow, ranging from 40 to 80  
 650  $\mu\text{g}/\text{cm}^2$  over four sample sites. CCC which is the combination of GAI and LCC, presents  
 651 similar seasonal trends as GAI. Some fluctuations can be found over the three variables and  
 652 four sample sites, and the other sites which are not shown for brevity. They mainly result  
 653 from the availability of measurements during a day and inevitable error propagation of all  
 654 processing procedures. This is particularly obvious for CCC, because fluctuations of GAI and  
 655 LCC will be amplified in CCC after multiplication.

656



657  
 658 Fig. 9. Seasonal variations of GAI, LCC and CCC estimations on four selected IoTA systems,  
 659 including AC-2 from Muizon, 41\_1 DS from Boigneville, Fourques-1 from Nimes, FS-3 from  
 660 Gréoux, C-B3 from Chalons and SI-3 FS52 from St-Hilaire. Red circles represent ground  
 661 measurements. The measurements of IoTA didn't cover the whole growth cycle as shown in  
 662 Table S1.

## 663 5 Discussion

### 664 5.1 Estimation of diffuse fraction in each spectral band

665 Near-surface sensor measurements are affected by varying illumination conditions in  
 666 natural environments. Indeed, the targeted surface receives the combination of both the direct  
 667 and diffuse components of the solar irradiance, which impacts the signal measured by the  
 668 sensor (Schaeppman-Strub et al., 2006). Diffuse solar irradiance has important impacts on  
 669 canopy photosynthesis in the context of global change (Durand et al., 2021). Accurate  
 670 assessment of diffuse irradiance or diffuse fraction is essential for simulating its contribution  
 671 to canopy. Previous studies have demonstrated that diffuse irradiance in each spectral band is  
 672 different because the main contributors driving the proportion of diffuse radiation (e.g.,  
 673 clouds and aerosol) are wavelength-dependent (Kirchstetter et al., 2004). And the spectral  
 674 diffuse fraction is also required by canopy radiative transfer models, such as PROSAIL. It is  
 675 therefore mandatory to evaluate the diffuse fraction of irradiance during the acquisition.

676 The most accurate method to measure spectral diffuse irradiance is to measure normal  
 677 direct irradiance and global irradiance, and then calculate diffuse irradiance or diffuse fraction  
 678 from the measurements (López et al., 2004). The global irradiance is widely measured, yet the  
 679 pyrhelimeter instrument to measure direct normal irradiance is very expensive. Many  
 680 researchers thus used alternate methods, such as pyranometer with a shadowband, or a  
 681 rotating shadowband and a tracking solar disk, to measure spectral diffuse irradiance by

682 blocking direct irradiance from total irradiance (de Simón-Martín et al., 2015; Harrison et al.,  
683 1999; Michalsky and Kiedron, 2022). Although the feasibility of these instruments or models  
684 have been greatly improved, their cost and use do not correspond to the constraints of the  
685 IoT systems (affordable and installed without requiring RS expertise) and thus not  
686 applicable in this study.

687 Alternatively, Spitters et al. (1986) indicated that the diffuse fraction in each spectral  
688 band can be approximated from the PAR diffuse fraction. However, although the total PAR is  
689 widely monitored in meteorological ground stations, diffuse PAR is not routinely measured.  
690 Diffuse PAR is usually obtained through various semi-empirical relationships, either with the  
691 diffuse fraction of the global incoming radiation (Ezhova et al., 2018; Gu et al., 2002; Spitters  
692 et al., 1986), or with the ratio of total PAR to extraterrestrial PAR (Hassika and Berbigier,  
693 1998; Jacovides et al., 2010, 2007). Nevertheless, the calibration of these semi-empirical  
694 functions are site dependent and show poor extrapolation capacities (Gueymard and Ruiz-  
695 Arias, 2016; Jacovides et al., 2007; Spitters et al., 1986; Yang and Gueymard, 2020). In this  
696 study, we propose to use a fully empirical, data driven approach that does not require a priori  
697 knowledge of the relationship as it consists in training some machine learning algorithm (e.g.,  
698 neural networks). We trained it over a limited number of sites in this study, but its  
699 applicability could be extended by adding ancillary data as inputs (meteorology, site location),  
700 and collecting and gathering data under different illumination conditions and locations to  
701 improve the representativeness and robustness of this method.

702 Thanks to atmospheric radiative transfer model, e.g., 6S simulations, we showed that the  
703 spectral diffuse fraction present polynomial relationships with PAR diffuse fraction through  
704 6S model simulations for a variety of low to high visibility conditions (Fig. 6). They are in  
705 line with those reported in Spitters et al. (1986), who showed that PAR diffuse fraction can be  
706 almost twice as great as that in the red part since the degree of aerosol scattering decreases as  
707 the wavelength increases. This method was evaluated by setting up a simple experiment using  
708 a multispectral camera. The spectral diffuse fraction in the validation experiments was  
709 approximated by the ratio of the total radiance over small shaded and illuminated areas of the  
710 grey carpet. Results might be affected by the distance between two measurements (around  
711 500 m), a small dyssynchronization between the acquisition systems, or differences in  
712 integration time, since the illumination conditions were highly variable. Note also, that  
713 although the two areas were close and the radiance was extracted from the same image, the  
714 grey carpet is not perfectly homogeneous and flat as compared to a spectralon, which also  
715 might impact the results (Eq. S1). Promising results were obtained (Fig. 6c, Table 3) even if

716 some scattering occurs especially in the blue and green bands that are the most affected by  
717 aerosols. Nevertheless, these two bands do not correspond to IoTA specifications. Further  
718 experiments specifically designed for such objective should be conducted, similarly to the one  
719 developed by [Michalsky and Kiedron \(2022\)](#) for example. Another uncertainty might result  
720 from the 6S atmospheric correction model which does not incorporate the cloud component.  
721 To solve this, we isolated fully cloudy conditions and other conditions by setting a threshold  
722 on PAR diffuse fraction, i.e.,  $> 0.9$  represents cloudy conditions. Spectral diffuse fraction  
723 equals to PAR diffuse fraction under cloudy conditions, otherwise, they were simulated by  
724 setting large range of visibility in 6S model. More evaluations are necessary to study this  
725 isolation in multiple locations and illumination conditions.

## 726 **5.2 Relative values of spectrometer measurements as inputs to inversion**

727 This study takes advantage of previous approaches applied to satellite observation to  
728 develop an original close-range sensing method by exploiting the angular and spectral  
729 variations of the signal for GAI, LCC and CCC retrieval through kernel-driven model and  
730 PROSAIL radiative transfer model ([Weiss and Baret, 1999](#)). Due to the difficulties of  
731 absolute radiometric calibration of continuous multi-band spectrometer measurements from  
732 near-surface systems under varying illumination conditions, we used an algorithm that relies  
733 on relative values. Raw measurements from multi-band spectrometers were converted into  
734 irradiance and used to calculate the relative values. The relative values present seasonal  
735 variation of wheat during the whole growth stage and diurnal variations under different  
736 illumination conditions ([Fig. S4](#) and [Fig. S5](#) in Supplementary Materials Part D). Accordingly,  
737 the kernel-driven and PROSAIL model simulations were also converted into relative values to  
738 keep the consistency between simulations and measurements. Relative values were already  
739 applied to images acquired by multispectral cameras on board UAV ([Jay et al., 2019](#); [Verger  
740 et al., 2014](#)). However, in those studies, it was designed to remove possible effects of the  
741 spatial variability of the incoming light (especially in case of clouds passing during the flight)  
742 between the reference panel used for the calibration and the image acquired by the UAV. We  
743 applied here the same principle and extended it successfully for the first time to continuous  
744 spectrometer measurements without any calibration reference measurements. The relative  
745 values can be calculated in different ways, using average of all bands as denominator ([Verger  
746 et al., 2014](#)) or using one single band as denominator ([Jay et al., 2019](#)). Our results showed  
747 that the former present overall better performance when comparing with ground  
748 measurements for GAI, LCC and CCC. This might be because the average values neutralize

749 the uncertainties among bands and thus improve the inversion accuracy. This could be further  
750 checked by setting up experiments based on calibrated reflectance measurements under  
751 different illumination conditions.

752 Conversely to traditional ground measurements methods based on the gap fraction theory,  
753 we were able to exploit both the spectral and the angular variations of the signal with the sun  
754 positions thanks to continuous acquisitions during the day. These multi-spectral and multi-  
755 angle measurements are an efficient way to constrain the ill-posed inversion problem (Baret  
756 and Buis, 2008) and improve the retrieval accuracy of GAI, LCC and CCC as already  
757 demonstrated in UAV or satellite experiment contexts (Deng et al., 2006; Dorigo, 2012; Duan  
758 et al., 2014; Roosjen et al., 2018; Roujean and Lacaze, 2002). Dorigo (2012), Duan et al.  
759 (2014) and Roosjen et al. (2018) applied Look-up tables in the inversion, while Deng et al.  
760 (2006) and Roujean and Lacaze (2002) normalized multi-angle reflectance into specific view  
761 angles using kernel-driven models and estimated biophysical variable using normalized  
762 values. However, simple application of above methods is not feasible in the continuous  
763 spectrometer measurements. In this study, some invalid measurements (e.g., sun zenith angle  
764 larger than  $60^\circ$  or negative measurements) were removed before the inversion and the sun  
765 position vary every day, resulting in different number of valid measurements and  
766 corresponding geometry per day. This will increase the dimension of training database for  
767 look-up table and impact the efficiency in the inversion. Alternatively, we combined the  
768 kernel-driven model and PROSAIL model and estimated biophysical variables from an BP-  
769 ANN algorithm. BP-ANN inversion technique has proven to be successful on an operational  
770 basis thanks to its accuracy and efficiency (Verrelst et al., 2015). A fixed number of inputs is  
771 required to use BP-ANN. Nevertheless, the number of valid measurements from multi-band  
772 spectrometer during a day varies, putting obstacles on the use of BP-ANN. A kernel-driven  
773 model (Roujean et al., 1992) was thus introduced to reduce the dimension in training and  
774 inversion. Kernel parameters of each band were calculated from diurnal measurements,  
775 leading to 18 kernel parameters for six bands (three per band) in total. These kernel  
776 parameters were used as inputs of BP-ANN to invert daily GAI, LCC and CCC. The quite  
777 good estimation accuracy of canopy biophysical variables reveals the feasibility of this  
778 method.

779 At least 18 measurements are required to compute daily BRDF kernel parameters (6  
780 bands  $\times$  3 kernels) using optimization algorithms. In fact, more than 90% of days satisfy this  
781 requirement because the IoTA measurements were taken every 15 minutes. However, the GAI  
782 estimation using data from one day measurement may present some shaky profiles as shown

783 in Fig. 10. A moving-window strategy was therefore applied, thus filling gaps and minimizing  
784 the impact of outliers on the inversion process. After investigating the optimal window size,  
785 we decided to use 3 days moving window to capture the rapid changes of crops while keeping  
786 good accuracy of kernel parameter estimation. This is in agreement with Hufkens et al. (2019)  
787 who kept the sites that have up to 2.9 images per week during the peak of growing seasonal.  
788 As a matter for fact, in the fast growing stages (e.g., tillering and stem extension) and ripening  
789 stages (Magney et al., 2016), the assumption that wheat status is stable in 3 days remains  
790 reasonable but not acceptable for 5 or 7 days. Even during the heading period when the wheat  
791 NDVI changes slowly, Velumani et al. (2020) found that there are around 3 days from the  
792 emergence of the spikes from the stem to the end of heading.

### 793 5.3 Accuracy of daily GAI, LCC and CCC estimations

794 The good accuracy of GAI, LCC and CCC demonstrated the feasibility of this method  
795 despite the absence of absolute radiometric calibration of the multi-band spectrometer. GAI  
796 was well estimated with acceptable RMSE and relative RMSE, consistent with previous  
797 studies using close-range monitoring systems (Chen et al., 2022; Kim et al., 2019; Rogers et  
798 al., 2021). For leaf chlorophyll content of wheat, similar results by PROSAIL inversion based  
799 on close-range measurements were also reported in other studies. The RMSE obtained in this  
800 study ( $15.49 \mu\text{g}/\text{cm}^2$ ) is lower than that reported by Botha et al. (2010) ( $15.61 - 23.31$   
801  $\mu\text{g}/\text{cm}^2$ ) that was estimated by hyperspectral reflectance over wheat canopy in different  
802 stages. Using a field goniometer multi-angle hyperspectral reflectance, Lunagaria and Patel  
803 (2019) obtained a RMSE of  $15.62 \mu\text{g}/\text{cm}^2$  over wheat based on all angles and reached a lower  
804 RMSE of  $10.5 \mu\text{g}/\text{cm}^2$  when reducing the angular sampling around the hotspot direction.  
805 Other studies have shown better performances on LCC estimation by calibrating relationships  
806 with vegetation indices, like for example Li et al., (2022) (RMSE of  $6.22 - 6.87 \mu\text{g}/\text{cm}^2$ )  
807 using soil-removed semi-empirical model or Jay et al. (2019) (RMSE less than  $5 \mu\text{g}/\text{cm}^2$ )  
808 who computed vegetation indices only on pixels corresponding to vegetation elements from  
809 hyperspectral images acquired by a drone. However, these empirical relationships may not be  
810 transferable to other contexts (wheat cultivars, soil background, acquisition conditions). The  
811 systematic bias of IoTA LCC is mainly resulted from the reference LCC which is discussed  
812 below. Note that CCC is less affected by calibration as it is an integrated value at the canopy  
813 level. Our results are similar to Jay et al. (2017b) who also obtained better results of CCC  
814 estimation ( $R^2 = 0.76$ ) than LCC ( $R^2 = 0.26$ ) over sugarbeet from both radiative transfer  
815 models inversion and empirical relationships with vegetation indices. Conversely to

816 vegetation indices, our method does not require absolute calibration of the signal or ground  
817 measurements to fit an empirical relationship.

818 Although the overall accuracy of GAI, LCC and CCC is acceptable and comparable with  
819 previous studies, uncertainties still exist and influence the validation results. GAI was  
820 retrieved from the inversion of the PROSAIL 1-D radiative transfer model (Jacquemoud et  
821 al., 2009; Verrelst et al., 2019; Weiss et al., 2002), which does not consider either the  
822 vegetation clumping or row effect at early wheat stages. Therefore, the proposed approach  
823 allows to assess the effective value GAI (Yan et al., 2019), which is consistent with our  
824 reference effective GAI calculated from RGB gap fraction. Indeed, Jiang et al., (2022)  
825 showed that for wheat and maize, effective GAI is better estimated from reflectance  
826 measurements as compared to the true GAI even when considering the clumping effect  
827 through the use of a 3D radiative transfer model. They also showed that, even with a 1D-RTM  
828 model inversion, effective GAI is better estimated than effective LAI for non-reproductive  
829 stages, which was the case of this study. Note also that effective GAI is better suited than true  
830 LAI to describe the light interception within the canopy, which is a key component of crop  
831 growth models. Considering LCC, calibration issues may impact the actual location of the  
832 inflection point in the red-edge domain which is very sensitive to LCC content (Gitelson et  
833 al., 1996). More efforts are required in the future to deeply study the influences of radiometric  
834 calibration on LCC estimations using data at canopy level. The early version PROSPECT  
835 model (Jacquemoud and Baret, 1990) was used in this study, while several improved  
836 PROSPECT models were proposed, such as PROSPECT-D (Féret et al., 2017) and FASPECT  
837 (Jiang et al., 2021) which have been proved to have better LCC retrieval accuracy (Berger et  
838 al., 2018; Jiang et al., 2021; Li et al., 2020). Further, the range of input parameters for  
839 generating the training database also has direct impacts on the retrieval accuracy. For  
840 example, chlorophyll a+b content for wheat varies within 0 - 90 ug/cm<sup>2</sup>, e.g., 10 - 80 ug/cm<sup>2</sup>  
841 in Li et al., (2022), 0 - 80 ug/cm<sup>2</sup> in Berger et al., (2018) and 20 - 90 ug/cm<sup>2</sup> in Delloye et al.,  
842 (2018). We finally set the range to 20-80 ug/cm<sup>2</sup> based on prior knowledge of the wheat in  
843 our study area. The ALA of wheat was demonstrated to be erectophile (from 70° to 80°),  
844 therefore, the ALA for PROSAIL model was set to 60° – 80° with mean of 70°. This is  
845 consistent with Dong et al., (2019) which characterized wheat by erectophile leaf angle  
846 distribution with mean ALA of 62.49° and standard deviation of 11.08°.

847 The accuracy of estimated GAI, LCC and CCC relies on the ground reference dataset. In  
848 this study, reference GAI was estimated from gap fraction based on segmentation of green  
849 pixels on RGB images. We used a robust deep learning method trained on a comprehensive

850 dataset composed of a variety of species, instruments, and environmental conditions (Madec  
851 et al., 2023; Serouart et al., 2022) to guarantee the accuracy of segmentation. It is worth  
852 noting the segmentation might be difficult when GAI is larger than 4 or 5. The derivation of  
853 the GAI reference dataset assumes a constant G-function for a 45° viewing direction. This is  
854 actually very similar to the approach validated by Campos-Taberner et al., (2016) and  
855 Francone et al., (2014), who used the 57.5° angle for which the G-function is constant  
856 regardless of the leaf inclination angle value. We preferred using a 45° which show less  
857 saturation for dense canopies and eases the RGB image segmentation. At 45°, G can still be  
858 assumed constant for wheat canopies that were shown erectophile (mean inclination angle  
859 between 70° and 74° as estimated by Barillot et al., (2019) for different wheat types).  
860 Additionally, this allows to be consistent with the inclination angle of the multi-band  
861 spectrometer. When using a single camera, the choice of the viewing angle to get a constant  
862 G-function over other crop types need further investigations. This can be overcome by using  
863 at least two cameras looking in different view angles to concurrently assess GAI and  
864 inclination angle (Weiss et al., 2004).

865 SPAD meters are routinely used to measure chlorophyll content in the field. Calibration  
866 of raw SPAD readings to LCC is a critical step before using them in validation. The strictest  
867 calibration procedure is composed of three steps: cutting several leaves samples in regular  
868 shapes and recording multiple SPAD readings per sample, measuring absolute LCC of these  
869 samples in laboratory through standard wet chemistry procedures (Lichtenthaler and  
870 Wellburn, 1983), and establishing empirical relationships between the absolute LCC and  
871 SPAD values for each variety of wheat. However, this procedure is time-consuming and  
872 impractical for large number of samples. One alternative solution is to apply existing  
873 equations from literatures to our SPAD readings to obtain the LCC values. Previous studies  
874 showed that the calibration equations are various in the format (linear, polynomial,  
875 exponential or homographic)(Cerovic et al., 2012; Zhang et al., 2022). For a single format, the  
876 coefficients are also different depending on the species and measurement periods, although  
877 the differences of might be very small as reported by Uddling et al., (2007) and Zhang et al.,  
878 (2022). Since there was no absolute reference LCC in this study, choosing which calibration  
879 equation has direct impacts on the validation results. Applying available twelve equations  
880 built for wheat or with wheat, we found a very similar correlation between IoTA LCC and  
881 reference LCC ( $R^2$  between 0.51 and 0.53, Fig. S8) with some bias depending on relationship  
882 (RMSE between 5.59  $\mu\text{g}/\text{cm}^2$  – 18.94  $\mu\text{g}/\text{cm}^2$ , Fig. S8), which actually questions the  
883 reliability of the SPAD to actually assess the LCC without any specific calibration. A generic



884 approach for this calibration remains lack. To solve this, we proposed an ensemble method to  
885 compute the median of LCC converted from all available equations as the reference, which  
886 could evaluate IoTA LCC to some extent. Nevertheless, the reference itself has an overall  
887 uncertainty of  $7.44 \mu\text{g}/\text{cm}^2$ , and it greatly relies on selected calibration equations. Further  
888 studies are urgently required to investigate a reliable and generic calibration method to  
889 convert SPAD readings into absolute LCC. Furthermore, this uncertainty may be also related  
890 to the SPAD sampling protocol. We measured only the top leaves as suggested by many other  
891 research teams (De Grave et al., 2021; Zhou et al., 2020) while the vertical chlorophyll  
892 distribution within the wheat canopy may have some influence, also depending on the  
893 phenological stage. Indeed, few studies investigated this aspect and we found contradictory  
894 results about this distribution with higher chlorophyll content measured at the upper layer (T.  
895 Wang et al., 2022; Wu et al., 2021) using destructive measurements, while Li et al., (2019)  
896 found that the highest chlorophyll content in the middle of the canopy (SPAD). Besides the  
897 measurement method, more investigations are needed regarding the sampling protocol.

898       Regarding the canopy chlorophyll content, we assumed it constant during a three-day  
899 period which corresponds to the size of the moving window selected for our algorithm.  
900 Additionally, the PROSAIL model assumes a turbid medium only composed of leaves,  
901 therefore CCC was computed as the product of the leaf chlorophyll content by effective LAI.  
902 This is consistent with the SPAD reference measurements acquired over top leaves during our  
903 measurement period that does not include reproductive stage (e.g., presence of ears). Indeed,  
904 from the top of canopy, the signal captured from the multi-band spectrometers comes mainly  
905 from the leaves, reducing the possible impact of differences in chlorophyll content between  
906 stems and leaves. However, the chlorophyll content and its contribution to CCC and canopy  
907 reflectance of other elements than green leaves (e.g., stems, ears, mix of green and yellow  
908 leaves between the senescent phase) should be better investigated following the studies of Li  
909 et al., (2021) who showed experimentally a significant impact of ears on the measured NDVI  
910 (around 9%), and Jiang et al., (2022) who used a 3D radiative transfer model to evaluate the  
911 impact of yellow stems and leaves on the reflectance signal or Amin et al., (2021) who trained  
912 a machine learning algorithm to estimate Green and Brown GAI from Sentinel-2 using  
913 experimental data.

#### 914 **5.4 Limitations and implications**

915 Constrained by the low-cost instrument design, this algorithm uses several  
916 approximations that may impact the retrieval accuracy. Although we made some attempts to  
917 evaluate each step, further investigations are needed to strengthen these results: (i) additional  
918 measurements should be used to allow good generalization capacities of PAR diffuse fraction  
919 estimation. This could be achieved by making use of site networks such as FLUXNET (ii) the  
920 relationships between the diffuse fraction in the PAR and in other wavebands derived from  
921 the 6S model should be better investigated by setting up a proper experiment (iii) the  
922 uncertainties associated to the use of relative reflectance should be better investigated by  
923 comparing with an approach based on absolute and calibrated reflectance using experimental  
924 setups like the one developed by [Michalsky and Kiedron \(2022\)](#) (iv) completing the  
925 validation campaign with more reference points and simultaneous LCC laboratory and SPAD  
926 measurements to strengthen the SPAD/LCC relationships.

927 Based on this common feature, we developed a practical and computationally efficient  
928 approach that allows inverting a radiative transfer model in situations where measuring  
929 incoming radiance is not feasible, and/or acquisitions are acquired with a variable geometry  
930 by normalizing the data (e.g., relative radiance value, use of kernel BRDF models). This  
931 could be particularly useful when using UAV data during unstable cloud conditions or  
932 monitoring closed canopies where installing sensors to measure incoming might not be  
933 feasible. We also proposed a simple mean to characterize the incoming diffuse fraction from  
934 incident PAR measurements, although the relationship to estimate diffuse PAR from  
935 incoming radiation should be strengthened by using additional meteorological measurements.  
936 Deploying networks of IoT systems would allow to better assess the within and between  
937 fields heterogeneity and provide valuable information to decision support systems and  
938 farmers.

#### 939 **6 Conclusions**

940 Non-destructive measurements of daily GAI, LCC and CCC offer insightful information  
941 to monitor crop status. Whilst substantial efforts have been devoted to monitor continuous  
942 GAI through near-surface platforms, concurrent and autonomous monitoring GAI, LCC and  
943 CCC is scarce. In this study, we developed a comprehensive approach to estimate canopy  
944 GAI, LCC and CCC from a near-surface monitoring system with a low-cost multi-band  
945 spectrometer multispectral spectrometers and a PAR. This approach overcomes several

946 challenges related to the use of multi-band spectrometer from near-surface system in natural  
947 environment, through estimation of various diffuse fraction in each spectral band and  
948 consideration of multi-angle observations. We validated the accuracy of this approach using  
949 43 IoT systems in wheat fields. Our results indicate that this algorithm works well for the  
950 multi-band spectrometer installed on the near-surface platforms, to track wheat GAI, CCC,  
951 and in a lesser extent LCC simultaneously at a daily temporal resolution. We demonstrated  
952 that multi-angle information can be properly used to retrieve variables using ANN inversion  
953 strategy, based on the combined use of kernel-driven BRDF and PROSAIL models. In  
954 addition, we provide a practical method to derive the spectral diffuse fraction from PAR  
955 sensor measurements, based on empirical relationships for PAR diffuse/direct partitioning and  
956 model simulations to relate spectral to PAR diffuse fractions. Compared with reference data,  
957 our method achieved satisfactory performances with GAI (RMSE = 0.51), LCC (RMSE =  
958  $8.44 \mu\text{g}/\text{cm}^2$ ), CCC (RMSE =  $0.25 \text{ g}/\text{m}^2$ ) and. Given the advantages of this algorithm and  
959 comparable low cost of multi-band spectrometers and PAR sensors, we recommend it to be  
960 applied over other crops or other near-surface platforms for simultaneous estimations of GAI,  
961 LCC and CCC. More measurements on multiple crops and under different climate conditions  
962 are needed to further investigate the robustness of the algorithm. For next generations of such  
963 IoT observation system, sensors able to measure spectral and diffuse irradiance directly such  
964 as those developed for the purpose of observing solar-induced fluorescence should be  
965 evaluated (e.g., the accuracy, price and possibility for large deployment in a field).  
966 Furthermore, as demonstrated by numerous previous studies, adding sensors with a band  
967 located in the green domain could be added to improve GAI, LCC and CCC inversion  
968 (Daughtry, 2000; Gitelson et al., 2003; Weiss et al., 2000). More efforts will also be put to  
969 explore the combination of RGB camera and the multi-band spectrometer to retrieve GAI,  
970 LCC and CCC.

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